

Why can't we go further to the sedenions?
 linear independence fails in S^{15} .

By the way: S^7 is not a Lie group because $(e_1 e_2) e_4 \neq e_1 (e_2 e_4)$. The octonions are not associative!

Change e_i to x_i to get T_x vector fields on S^7 !

e_7	e_7	$-e_6$	$-e_5$	e_4	e_3	e_2	e_1	$-e_0$
e_6	e_6	e_7	$-e_4$	$-e_5$	e_2	$-e_3$	$-e_0$	$-e_1$
e_5	e_5	e_4	e_7	$-e_6$	$-e_1$	e_0	e_3	$-e_2$
e_4	e_4	$-e_5$	e_6	e_7	$-e_0$	$-e_2$	$-e_3$	e_1
e_3	e_3	e_2	$-e_1$	$-e_0$	$-e_7$	e_6	e_5	$-e_4$
e_2	e_2	$-e_3$	$-e_0$	e_1	$-e_6$	$-e_7$	e_4	e_5
e_1	e_1	$-e_0$	e_3	$-e_2$	e_5	$-e_4$	$-e_7$	e_6
e_0	e_0	e_1	e_2	e_3	e_4	e_5	e_6	e_7
e_7	e_7	e_6	e_5	e_4	e_3	e_2	e_1	e_0

III

Then use the product to compute the table:

$$e_0 = (1, 0) \quad e_1 = (i, 0) \quad e_2 = (0, 1) \quad e_3 = (0, i) \\ e_4 = (j, 0) \quad e_5 = (k, 0) \quad e_6 = (0, j) \quad e_7 = (0, k)$$

Let's decompose \mathbb{R}^8 :

THE OCTONIONS

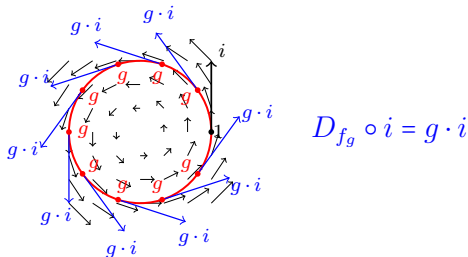
LIE GROUPS

Definition. A Lie group is a group that is also a manifold, for which inversion and group multiplication are smooth.

Example 3. The unit circle $S^1 \subset \mathbb{C}$ is a Lie group with complex multiplication (the linear rotation map). More generally, if $\mathbb{K} = \mathbb{R}, \mathbb{C}$, then any matrix group over \mathbb{K} is a Lie group.

Theorem 4. If G is a Lie group, then G is parallelizable.

Proof. Let $\sigma_1, \dots, \sigma_n$ be a basis of $T_{id}G$. Then define $\sigma_i(g) = Df_g(\sigma_i)$, where $f_g(x) = gx$ is a diffeomorphism, and hence $\text{Rk}(Df_g) = \dim(G)$. \square



S^1 and S^3 are Lie groups, but what about S^7 ?

COMPLEXIFICATION

“Complexification is the art of turning something real, tangible, and in proper order into something complex, hard to grasp, or even imaginary”

Definition. A complex number is a pair of real numbers (x, y) , with multiplication¹:

$$(x_1, y_1) \cdot (x_2, y_2) = (x_1 x_2 - \bar{y}_2 y_1, y_2 x_1 + y_1 \bar{x}_2)$$

$$\text{We set } \overline{(x_1, x_2)} = (x_1, -x_2).$$

Definition. A quaternion is a pair of complex numbers (x, y) , with multiplication:

$$(x_1, y_1) \cdot (x_2, y_2) = (x_1 x_2 - \bar{y}_2 y_1, y_2 x_1 + y_1 \bar{x}_2)$$

$$\text{We set } \overline{((x_1, x_2), (x_3, x_4))} = ((x_1, -x_2), (-x_3, -x_4)).$$

Definition. An octonion is a pair of quaternions (x, y) , with multiplication:

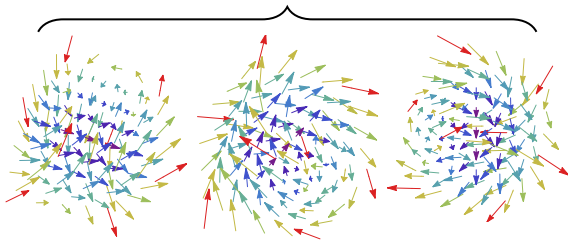
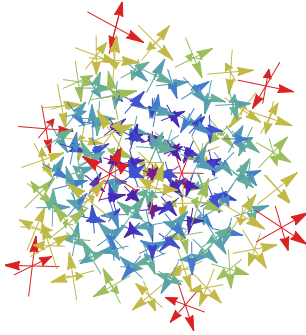
$$(x_1, y_1) \cdot (x_2, y_2) = (x_1 x_2 - \bar{y}_2 y_1, y_2 x_1 + y_1 \bar{x}_2)$$

$$\text{We set } \overline{(((x_1, x_2), (x_3, x_4)), ((x_5, x_6), (x_7, x_8)))} = (((x_1, -x_2), (-x_3, -x_4)), ((-x_5, -x_6), (-x_7, -x_8)))$$

Nice

¹If a is real, $\bar{a} = a$.

A politically neutral guide to things mathematicians wished were related to string theory



How to tell if your sphere is parallelizable

The other direction is left as an exercise. \square

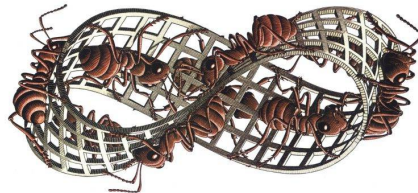
is a bundle isomorphism. is a linear isomorphism on the fibres, and hence is a well-defined smooth diffeomorphism, which

map $f : M \times \mathbb{R}^n \rightarrow E$ defined by $f(d, (x_1, \dots, x_n)) = (d, x_1 \sigma_1 + \dots + x_n \sigma_n)$

Proof. If $\sigma_1, \dots, \sigma_n$ are such sections, then the n linearly independent nonzero sections.

Theorem 1. An n -bundle E is trivial iff it admits n linearly independent nonzero sections.

The Möbius strip is a nontrivial line bundle over S^1 . It is nontrivial because there is no way to unwind the twist to make it a cylinder.



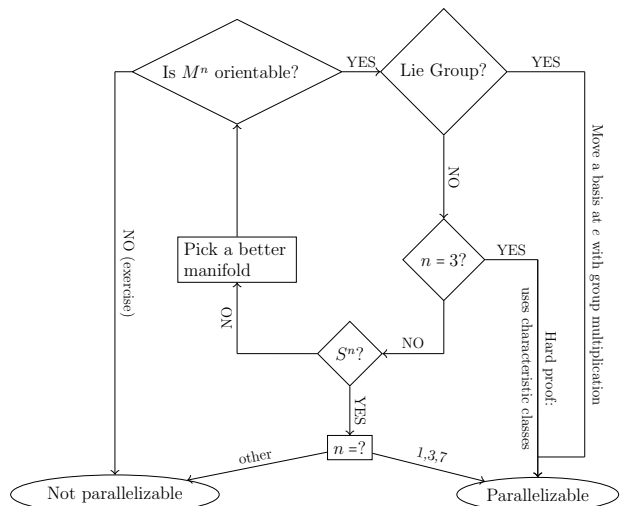
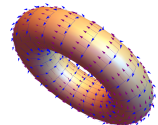
Definition. A manifold M^n is parallelizable if $TM \cong M \times \mathbb{R}^n$ (ie, TM is trivial).

SAY "PARALLELIZABLE" TEN TIMES FAST

UNWINDING THE TWISTY TO FLAT

For a manifold M^n to be parallelizable, we must find n independent nonvanishing vector fields. This is sometimes impossible, as shown by the Fundamental Theorem of S^2 .

Example 2. The torus is parallelizable (see picture).



This shows that S^3 is parallelizable. \square



The first column is the point on the sphere, and the other columns are orthogonal vectors tangent to the point!

x_1	x_2	x_3	x_4
x_2	$-x_1$	x_4	$-x_3$
x_3	$-x_4$	$-x_1$	x_2
x_4	x_3	x_2	$-x_1$

Do you care now? You should! Replace i, j, k with x_1, x_2, x_3, x_4 , and think of (x_1, x_2, x_3, x_4) as a vector on the unit sphere $S^3 \subset \mathbb{R}^4$.

k	j	i	-1
j	$-k$	-1	i
i	-1	k	$-j$
1	i	j	k

Who cares? Me. Have a multiplication table:

PARALLELIZATION

DECOMPLEXIFICATION

"Decomplexification is the art of turning something horrible into something reasonable. In other words, it's just choosing a basis"

The complex numbers (resp. quaternions), denoted \mathbb{C} (resp. \mathbb{H}) are 2 (resp. 4) dimensional real **algebras!** A basis makes understanding multiplication easier: If $z = (x, y) \in \mathbb{C}$ becomes $z = x + iy$, and $q = ((x_1, x_2), (x_3, x_4)) \in \mathbb{H}$ becomes $q = x_1 + ix_2 + jx_3 + kx_4$. Then:

$$ij = k, jk = i, ki = j$$

$$ji = -k, kj = -i, ik = -j$$

A mne-mon-ic: **Convoluted** 🤝👉👉

The rules:

1. Players (+) and (-) chant "i, j, k!" and then choose one of $\pm i, \pm j, \pm k$.
2. Multiply the choices.
3. If the result has a (-) sign in front of it, then player (-) wins.
4. Argue about the order of multiplication.

