# MAT 367: Differential Geometry Assignment #1 Due on Friday May 14, 2021 by 11:59 pm

Note: This assignment covers material from Week #1 (lectures, mandatory readings, and corresponding sections from the book).

## Problem 1

Recall the definition of a k-dim manifold in  $\mathbb{R}^n$ .  $M \subset \mathbb{R}^n$  is a k-dim manifold if  $\forall p \in M$ , there exists a neighbourhood U of p in M and an open set  $V \subset \mathbb{R}^k$ , and a map  $f: V \to U$ satisfying:

- f is  $C^{\infty}$ .
- f is bijective and continuous, and  $f^{-1}: U \to V$  is continuous. (f is a homeomorphism).
- The derivative  $Df|_q$  is injective  $\forall q \in V$ .
- (a) What is meant by "a neighbourhood of p in M"?
- (b) Informally explain why the above definition will be too general if the last condition is not included.

*Remark:* You can answer by giving an example of a set satisfying the above conditions except for the third, and justifying informally why we don't want to consider it as k-dim manifolds in  $\mathbb{R}^n$ .

We can extend the definition of smooth in the following way. A map  $g: A \to \mathbb{R}^k$  is "smooth" on an arbitrary set  $A \subset \mathbb{R}^n$  if it can locally be extended to a smooth function; more precisely, g is "smooth" if  $\forall p \in A$ , there exists a neighbourhood W of p in  $\mathbb{R}^n$  and a smooth map  $\tilde{g}: W \to \mathbb{R}^k$  such that  $\tilde{g}|_{W \cap A} = g$ . Given arbitrary sets  $A \subset \mathbb{R}^n$  and  $B \subset \mathbb{R}^k$ , we say  $g: A \to B$  is a "diffeomorphism" if it's a "smooth" homeomorphism with a "smooth" inverse.

(c) Let M be a k-dim manifold in  $\mathbb{R}^n$  and let  $f: V \to U$  be a map where  $V \subset \mathbb{R}^k$  is open and  $U \subset M$  is open in M. Show that if f is a "diffeomorphism", then f satisfies the three conditions listed in the definition of a manifold above.

*Remark:* The other direction requires more advanced tools since you need to prove the existence of a smooth extension. (requires bump functions). Consider the following new attempt of defining a surface in  $\mathbb{R}^3$ :  $S \subset \mathbb{R}^3$  is a surface if it's the graph of a smooth function. More precisely, this means that there exists a smooth function  $f: U \to \mathbb{R}$  on an open set  $U \subset \mathbb{R}^2$  such that  $S = \Gamma_f := \{(x, y, f(x, y)) : (x, y) \in U\}$  up to reordering of the coordinates.

(d) What is wrong with that definition? Is it too general or too specific?

*Hint:* Can you find a surface that doesn't satisfy the definition above, or a set that satisfies the definition above but is not a surface?

(e) Correct the above attempt by slightly modifying it, and then show it's equivalent to the definition described in the beginning of Problem 1.

*Hint:* Consider a set  $S \subset \mathbb{R}^3$  that is *locally* the graph of a smooth function.

(f) \*(bonus)\* Let S be a surface in  $\mathbb{R}^3$ , and let  $f: U \to S$  be an injective map defined on an open set  $U \subset \mathbb{R}^2$  satisfying the first and third condition of the definition of a surface. Show that f is a homeomorphism onto its image.

*Remark.* This shows that if we a priori know that S is a surface, we don't need to check that  $f^{-1}$  is continuous, provided that the other conditions hold.

### Problem 2

- (a) Prove proposition A.42 in Appendix A.10.
- (b) Let M be a topological space. Prove that M has k connected components if and only if there exists a continuous surjective function f : M → {1,2,...,k} such that for i = 1, 2, ..., k, f<sup>-1</sup>(i) are connected and pairwise disjoint. (The set {1, 2, ..., k} is equipped with the discrete topology).
- (c) Show that the number of connected parts is a topological invariant. More precisely, if M and N are topological spaces that are homeomorphic, then M has k connected components if and only if N also does.
- (d) Use this to show that  $\{(x, y) \in \mathbb{R}^2 : xy = 0\}$  equipped with the subspace topology that it inherits from  $\mathbb{R}^2$  is *not* a topological manifold.
- (e) (\*bonus\*) Show that a topological manifold has at most countably many connected components.

*Hint:* M is second countable.

#### Problem 3

Let  $M \subset \mathbb{R}^2$  be the boundary of a square with vertices  $(\pm 1, \pm 1)$ .

 $M = \left\{ (x, y) \in \mathbb{R}^2 : |x| \le 1 \text{ and } |y| \le 1, \text{ with } |x| = 1 \text{ or } |y| = 1 \right\}$ 

Decide whether or not the charts  $(U, \phi)$  and  $(V, \psi)$  given as

$$U = \{(x, y) \in M : y > -1\}, \quad \phi : U \to \mathbb{R}, \quad (x, y) \mapsto \frac{x}{1+y}$$
$$V = \{(x, y) \in M : y < 1\}, \quad \psi : V \to \mathbb{R}, \quad (x, y) \mapsto \frac{x}{1-y}$$

define a  $C^{\infty}$  atlas on M. Justify your answer.

(Hint: Compute  $\phi \circ \psi^{-1}$  and  $\psi \circ \phi^{-1}$  on their domain.)

## Problem 4

In this problem, we will look at an example of a non-Hausdorff "topological manifold" called "the real line with 2 origins".

- (a) Problem 5.1 (a) in section 5.
- (b) Problem 5.1 (b) in section 5.
- (c) Find a sequence  $\{x_n\}_{n=1}^{\infty}$  in the real line with 2 origins that converges to two different points.
- (d) Show that this doesn't happen in Hausdorff spaces. Namely, show that in a Hausdorff space, if a sequence  $\{x_n\}_{n=1}^{\infty}$  converges to p and q, then p = q.

#### Problem 5

Let  $f : \mathbb{R} \to \mathbb{R}$  be a continuous function.

(a) Show that the graph of f

$$\Gamma_f := \left\{ (x, f(x)) \in \mathbb{R}^2 : x \in \mathbb{R} \right\}$$

is a topological manifold of dimension 1.

- (b) Is it a smooth manifold? Justify your answer.
- (c) Is it a 1-dim manifold in  $\mathbb{R}^2$  as defined in problem 1? Justify your answer.