

Long-time Asymptotics for the Cubic Nonlinear Schrödinger Equation

Approach via the Method of Space-Time Resonances

Adam Morgan

June 25, 2021

- 1 Intro to the PDE, loose statement of main result
- 2 Facts about linear Schrödinger eqn
- 3 Heuristic computation underlying asymptotic analysis
- 4 Highlights of rigorous proof of main result

- Today, we study the Cauchy (initial value) problem for the **cubic nonlinear Schrödinger equation (NLS)**:

$$\begin{cases} iu_t + \frac{1}{2}\Delta u + \lambda|u|^2u = 0 & \forall (t, x) \in \mathbb{R} \times \mathbb{R}^d \\ u|_{t=0}(x) = u_0(x) & \forall x \in \mathbb{R}^d \end{cases}$$

$u(t, x): \mathbb{R} \times \mathbb{R}^d \rightarrow \mathbb{C}$, $u_0: \mathbb{R}^d \rightarrow \mathbb{C}$, and $\lambda = \pm 1$

- Today, we study the Cauchy (initial value) problem for the **cubic nonlinear Schrödinger equation (NLS)**:

$$\begin{cases} iu_t + \frac{1}{2}\Delta u + \lambda|u|^2u = 0 & \forall (t, x) \in \mathbb{R} \times \mathbb{R}^d \\ u|_{t=0}(x) = u_0(x) & \forall x \in \mathbb{R}^d \end{cases}$$

$u(t, x): \mathbb{R} \times \mathbb{R}^d \rightarrow \mathbb{C}$, $u_0: \mathbb{R}^d \rightarrow \mathbb{C}$, and $\lambda = \pm 1$

- NLS is a universal model for the evolution of wavepackets of the form

$$U(t, x) = u(t, x)e^{i(\xi_0 x - \omega_0 t)}$$

in nonlinear dispersive systems (w/ $\xi_0, \omega_0 \in \mathbb{R}$ s.t. $u(x, t)$ changes “slowly” compared to the sinusoidal term)

Main Questions

- Global-in-time well-posedness of NLS in L_x^2 with $d = 1$ is well-understood (Y. Tsutsumi, 1987)

Main Questions

- Global-in-time well-posedness of NLS in L_x^2 with $d = 1$ is well-understood (Y. Tsutsumi, 1987)

Main Question

Suppose $d = 1$. How do solns of NLS behave as $t \rightarrow \infty$? If u_0 is sufficiently small, does the nonlinearity eventually become negligible?

Main Questions

- Global-in-time well-posedness of NLS in L_x^2 with $d = 1$ is well-understood (Y. Tsutsumi, 1987)

Main Question

Suppose $d = 1$. How do solns of NLS behave as $t \rightarrow \infty$? If u_0 is sufficiently small, does the nonlinearity eventually become negligible?

- Main question is a baby step towards understanding stability of special solutions (solitons)
- Technically, we need to have a soln that's a bit better than L_x^2 to say something about the main question

The Best Answer to the Main Question

Theorem (Main Theorem, Loose Version)

Suppose

$$\|u_0(x)\|_{H_x^1} + \|xu_0(x)\|_{L_x^2} \leq \epsilon \ll 1.$$

Then, the unique global-in-time solution to NLS satisfies the following asymptotics: there exists some small $\beta > 0$ and two (unique) bounded, real-valued functions $F(\xi), \phi(\xi)$ such that

$$u(t, x) = (it)^{-1/2} F(x/t) \exp\left(\frac{i|x|^2}{2t} + i|F(x/t)|^2 \log t + i\phi(x/t)\right) + \mathcal{O}\left(t^{-1/2-\beta}\right).$$

Interpreting the Main Theorem

- Note the weighted norm $\|xu_0(x)\|_{L_x^2}$ appearing in the hypothesis! We shall see why this is pretty much *unavoidable*

Interpreting the Main Theorem

- Note the weighted norm $\|xu_0(x)\|_{L_x^2}$ appearing in the hypothesis! We shall see why this is pretty much *unavoidable*
- The weighted norm does not scale nicely wrt NLS scaling symmetry, so *cannot remove smallness hypothesis*

Interpreting the Main Theorem

- Note the weighted norm $\|xu_0(x)\|_{L_x^2}$ appearing in the hypothesis! We shall see why this is pretty much *unavoidable*
- The weighted norm does not scale nicely wrt NLS scaling symmetry, so *cannot remove smallness hypothesis*
- We shall also see that the $\log t$ frequency correction represents *deviation from linear behaviour*

Interpreting the Main Theorem

- Note the weighted norm $\|xu_0(x)\|_{L_x^2}$ appearing in the hypothesis! We shall see why this is pretty much *unavoidable*
- The weighted norm does not scale nicely wrt NLS scaling symmetry, so *cannot remove smallness hypothesis*
- We shall also see that the $\log t$ frequency correction represents *deviation from linear behaviour*
- Small technical detail: we'll construct $F(\xi)$ as *a priori* complex-valued, but WLOG we can absorb its argument into $\phi(\xi)$

Today's Approach to the Main Theorem

- We follow J. Kato & Pusateri 2011: use **method of space-time resonances (STR)** to establish a framework for getting the right asymptotics
- STR starts from a formal computation based on the stationary phase lemma... proof then reduces to justifying the steps of the computation (usually by bootstrapping)

Today's Approach to the Main Theorem

- We follow J. Kato & Pusateri 2011: use **method of space-time resonances (STR)** to establish a framework for getting the right asymptotics
- STR starts from a formal computation based on the stationary phase lemma... proof then reduces to justifying the steps of the computation (usually by bootstrapping)
- STR introduced by Germain, Masmoudi, & Shatah in 2009, has been applied to other problems including the water waves equations

Today's Approach to the Main Theorem

- We follow J. Kato & Pusateri 2011: use **method of space-time resonances (STR)** to establish a framework for getting the right asymptotics
- STR starts from a formal computation based on the stationary phase lemma... proof then reduces to justifying the steps of the computation (usually by bootstrapping)
- STR introduced by Germain, Masmoudi, & Shatah in 2009, has been applied to other problems including the water waves equations
- Method does not require “structural assumptions” on PDE \Rightarrow hope for STR working with difficult PDEs like the Benjamin-Bona-Mahony eqn!

Other Points of View

- NOTE: the Strauss approach based on a naïve perturbative argument w/ Duhamel (cf. my last talk) will not work here!

Other Points of View

- NOTE: the Strauss approach based on a naïve perturbative argument w/ Duhamel (cf. my last talk) will not work here!
- To my knowledge, earliest rigorous version of main theorem is due to Hayashi & Naumkin 1998
- Today, we will use part of their approach, but we do not control weighted norms with **method of vector fields** as they do

Other Points of View

- NOTE: the Strauss approach based on a naïve perturbative argument w/ Duhamel (cf. my last talk) will not work here!
- To my knowledge, earliest rigorous version of main theorem is due to Hayashi & Naumkin 1998
- Today, we will use part of their approach, but we do not control weighted norms with **method of vector fields** as they do
- Deift & Zhou 2003: used **inverse scattering theory**
- Lindblad & Soffer 2006: used a clever ansatz based on soln of linear Schrödinger, then constructed an iterative procedure
- Ifrim & Tataru 2015: used the **method of testing by wave packets**

Linear Schrödinger Review 1

- The Cauchy problem for the linear Schrödinger equation reads

$$\begin{cases} iu_t + \frac{1}{2}\partial_x^2 u = 0 & \forall (t, x) \in \mathbb{R} \times \mathbb{R} \\ u|_{t=0}(x) = u_0(x) & \forall x \in \mathbb{R} \end{cases}$$

- Soln can be written in terms of the Fourier transform $u_0(x) \mapsto \widehat{u}_0(\xi)$:

$$u(t, x) = e^{\frac{it}{2}\partial_x^2} u_0 \doteq \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i(\xi x - \frac{t}{2}\xi^2)} \widehat{u}_0(\xi) d\xi.$$

Linear Schrödinger Review 1

- The Cauchy problem for the linear Schrödinger equation reads

$$\begin{cases} iu_t + \frac{1}{2}\partial_x^2 u = 0 & \forall (t, x) \in \mathbb{R} \times \mathbb{R} \\ u|_{t=0}(x) = u_0(x) & \forall x \in \mathbb{R} \end{cases}$$

- Soln can be written in terms of the Fourier transform $u_0(x) \mapsto \widehat{u}_0(\xi)$:

$$u(t, x) = e^{\frac{it}{2}\partial_x^2} u_0 \doteq \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i(\xi x - \frac{t}{2}\xi^2)} \widehat{u}_0(\xi) d\xi.$$

- Immediately, we find by Plancherel that

$$\left\| e^{\frac{it}{2}\partial_x^2} u_0 \right\|_{L_x^2} = \|u_0\|_{L_x^2}$$

Linear Schrödinger Review 2

- After some contour integration, can represent Schrödinger flow as a convolution in spatial variable:

$$e^{\frac{it}{2}\partial_x^2} u_0 = (2\pi it)^{-1/2} \int_{-\infty}^{+\infty} dy \exp\left(\frac{i|x-y|^2}{2t}\right) u_0(y).$$

- Can simplify if taking $t \gg 1$:

Lemma (Linear Schrödinger Asymptotics)

We can write

$$e^{\frac{it}{2}\partial_x^2} u_0 = (it)^{-1/2} e^{\frac{ix^2}{2t}} \widehat{u}_0\left(\frac{x}{t}\right) + r(t, x)$$

and there exists $\kappa > 0$ so that

$$\|r(t, x)\|_{L_x^\infty} \lesssim t^{-1/2-\kappa} \|xu_0(x)\|_{L_x^2}$$

Proof of the Lemma 1

From spatial convolution representation of soln,

$$\begin{aligned} e^{\frac{it}{2}\partial_x^2} u_0 &= (2\pi it)^{-1/2} \int_{-\infty}^{+\infty} dy \exp\left(\frac{ix^2}{2t} - \frac{ixy}{t} + \frac{iy^2}{2t}\right) u_0(y) \\ &= (it)^{-1/2} \exp\left(\frac{ix^2}{2t}\right) \widehat{u}_0\left(\frac{x}{t}\right) \\ &\quad + \left[(2\pi it)^{-1/2} \exp\left(\frac{ix^2}{2t}\right) \int_{-\infty}^{+\infty} dy u_0(y) e^{-ixy/t} \left(e^{iy^2/2t} - 1\right) \right] \end{aligned}$$

where we added and subtracted $e^{-ixy/t}$ to the integrand. Define $r(t, x)$ to be stuff in square brackets above.

Proof of the Lemma 2

It's an easy exercise to show, for any $\kappa < \frac{1}{2}$, have

$$\left| e^{iy^2/2t} - 1 \right| \lesssim_{\kappa} t^{-\kappa} \langle y \rangle^{2\kappa}$$

where $\langle y \rangle^2 = 1 + y^2$.

Proof of the Lemma 2

It's an easy exercise to show, for any $\kappa < \frac{1}{2}$, have

$$\left| e^{iy^2/2t} - 1 \right| \lesssim_{\kappa} t^{-\kappa} \langle y \rangle^{2\kappa}$$

where $\langle y \rangle^2 = 1 + y^2$.

Thus since $\langle y \rangle^{-\zeta} \in L_x^1$ for $\zeta > 1/2$, Cauchy-Schwarz gives

$$\begin{aligned} \|r(t, x)\|_{L_x^\infty} &\lesssim t^{-\frac{1}{2}-\kappa} \int_{-\infty}^{+\infty} dy \langle y \rangle^{2\kappa} |u_0(y)| \\ &\lesssim t^{-\frac{1}{2}-\kappa} \left\| \langle x \rangle^{2\kappa+\zeta} u_0(x) \right\|_{L_x^2}. \end{aligned}$$

To finish the proof, shrink κ until $2\kappa + \zeta \leq 1$.

Proof of the Lemma 2

It's an easy exercise to show, for any $\kappa < \frac{1}{2}$, have

$$\left| e^{iy^2/2t} - 1 \right| \lesssim_{\kappa} t^{-\kappa} \langle y \rangle^{2\kappa}$$

where $\langle y \rangle^2 = 1 + y^2$.

Thus since $\langle y \rangle^{-\zeta} \in L_x^1$ for $\zeta > 1/2$, Cauchy-Schwarz gives

$$\begin{aligned} \|r(t, x)\|_{L_x^\infty} &\lesssim t^{-\frac{1}{2}-\kappa} \int_{-\infty}^{+\infty} dy \langle y \rangle^{2\kappa} |u_0(y)| \\ &\lesssim t^{-\frac{1}{2}-\kappa} \left\| \langle x \rangle^{2\kappa+\zeta} u_0(x) \right\|_{L_x^2}. \end{aligned}$$

To finish the proof, shrink κ until $2\kappa + \zeta \leq 1$.

NOTE: This proof is where we find weighted norm is unavoidable!

An Instructive Heuristic 1

- If $u(t, x)$ satisfies NLS, define its **profile** by

$$f(t, x) = e^{-\frac{it}{2}\partial_x^2} u(t, x)$$

- Notice: if $u(t, x)$ was a linear wave, then $f = f(x)$ hence $\partial_t f \neq 0$ implies genuinely nonlinear behaviour

An Instructive Heuristic 1

- If $u(t, x)$ satisfies NLS, define its **profile** by

$$f(t, x) = e^{-\frac{it}{2}\partial_x^2} u(t, x)$$

- Notice: if $u(t, x)$ was a linear wave, then $f = f(x)$ hence $\partial_t f \neq 0$ implies genuinely nonlinear behaviour
- We'll write out NLS in terms of the profile *in Fourier space*:

$$\partial_t \hat{f} = i\lambda e^{\frac{it}{2}\xi^2} (|u|^2 u)^\wedge.$$

Need to write RHS all in terms of \hat{f} ... use convolution theorem

An Instructive Heuristic 2

- After some calculation (see notes), get the following: define a phase function by

$$\Phi(\eta, \sigma; \xi) \doteq \eta(\xi - \sigma),$$

then the transformed profile $\hat{f}(t, \xi)$ obeys the ODE

$$\partial_t \hat{f} = \frac{i\lambda}{2\pi} \int d\eta \int d\sigma e^{it\Phi(\eta, \sigma; \xi)} \hat{f}(t, \xi - \eta) \hat{f}(t, \sigma) \overline{\hat{f}(t, \sigma - \eta)}.$$

- RHS is like an oscillatory integral (pretend \hat{f} varies slowly in time compared to exponential term), so can use classical tools to estimate for $t \gg 1$

What are Resonances?

Definition

We call a pair (η_0, σ_0) a space resonance if

$$\nabla_{\eta, \sigma} \Phi(\eta_0, \sigma_0) = 0$$

or a time resonance if

$$\Phi(\eta_0, \sigma_0) = 0.$$

If (η_0, σ_0) is both a space resonance and a time resonance, we call it a space-time resonance.

What are Resonances?

Definition

We call a pair (η_0, σ_0) a space resonance if

$$\nabla_{\eta, \sigma} \Phi(\eta_0, \sigma_0) = 0$$

or a time resonance if

$$\Phi(\eta_0, \sigma_0) = 0.$$

If (η_0, σ_0) is both a space resonance and a time resonance, we call it a space-time resonance.

- **Method of stationary phase** \Rightarrow dominant contributions to RHS of profile ODE for $t \gg 1$ come from space-time resonances

Asymptotic Approx. of Profile ODE

- After computing space-time resonances and plugging into the stationary phase lemma, find for $t \gg 1$ that

$$\partial_t \hat{f}(t, \xi) \approx i\lambda t^{-1} \left| \hat{f}(t, \xi) \right|^2 \hat{f}(t, \xi)$$

- Above implies that $\partial_t \left| \hat{f}(t, \xi) \right|^2 \approx 0$ for $t \gg 1$ so $\exists F(\xi)$ s.t.

$$\left| \hat{f}(t, \xi) \right|^2 \approx |F(\xi)|^2$$

- Thus we can integrate the approximate ODE to get (up to a ξ -dependent phase correction)

$$\hat{f}(t, \xi) \approx F(\xi) e^{i\lambda |F(\xi)|^2 \log t}$$

No Convergence to Linear Dynamics!

- Thus we find that for $t \gg 1$

$$\hat{u}(t, \xi) \approx F(\xi) \exp \left[-\frac{it}{2} \xi^2 + i\lambda |F(\xi)|^2 \log t \right]$$

- By rough analogy with linear Schrödinger asymptotics we then expect

$$u(t, x) \approx (it)^{-1/2} F(x/t) \exp \left(\frac{i|x|^2}{2t} + i |F(x/t)|^2 \log t \right)$$

again up to phase.

No Convergence to Linear Dynamics!

- Thus we find that for $t \gg 1$

$$\hat{u}(t, \xi) \approx F(\xi) \exp \left[-\frac{it}{2} \xi^2 + i\lambda |F(\xi)|^2 \log t \right]$$

- By rough analogy with linear Schrödinger asymptotics we then expect

$$u(t, x) \approx (it)^{-1/2} F(x/t) \exp \left(\frac{i|x|^2}{2t} + i |F(x/t)|^2 \log t \right)$$

again up to phase.

- This differs from linear behaviour by logarithmic frequency correction!

Roadmap to the Main Theorem

- 1 Get local existence in the right norm, trivial
- 2 Need to show small solns to NLS at least decay in time like linear solns:

$$\|u(t, x)\|_{L_x^\infty} \lesssim \langle t \rangle^{-1/2}$$

plus some other weighted norm bounds. Requires a long bootstrap argument! Main contribution of Kato & Pusateri 2011.

- 3 From here, follow Hayashi & Naumkin 1998: rewrite the ODE for the profile using an “integrating factor”, get a sequence converging to asymptotic profile amplitude $F(\xi)$.
- 4 Concluding the main asymptotic expansion is very easy from here!

Some Norms

$\mathcal{S}'(\mathbb{R})$ = tempered distributions on \mathbb{R}

Definition (Weighted Sobolev Spaces)

$$H_x^{s,\ell} = \left\{ u \in \mathcal{S}'(\mathbb{R}) \mid \|u\|_{H_x^{s,\ell}} \doteq \left\| \langle x \rangle^\ell \langle \partial_x \rangle^s u \right\|_{L_x^2} < \infty \right\}$$

Similarly, we have

$$\dot{H}_x^{s,\ell} = \left\{ u \in \mathcal{S}'(\mathbb{R}) \mid \|u\|_{\dot{H}_x^{s,\ell}} \doteq \left\| \langle x \rangle^\ell |\partial_x|^s u \right\|_{L_x^2} < \infty \right\}$$

Some Norms

$\mathcal{S}'(\mathbb{R})$ = tempered distributions on \mathbb{R}

Definition (Weighted Sobolev Spaces)

$$H_x^{s,\ell} = \left\{ u \in \mathcal{S}'(\mathbb{R}) \mid \|u\|_{H_x^{s,\ell}} \doteq \left\| \langle x \rangle^\ell \langle \partial_x \rangle^s u \right\|_{L_x^2} < \infty \right\}$$

Similarly, we have

$$\dot{H}_x^{s,\ell} = \left\{ u \in \mathcal{S}'(\mathbb{R}) \mid \|u\|_{\dot{H}_x^{s,\ell}} \doteq \left\| \langle x \rangle^\ell |\partial_x|^s u \right\|_{L_x^2} < \infty \right\}$$

Definition (Bootstrap Norm)

In terms of a given $T > 0$ and some small $\alpha \ll 1$ to be determined later,

$$\|u\|_{X_T} = \left\| t^{1/2} u \right\|_{L_t^\infty L_x^\infty} + \left\| t^{-\alpha} u \right\|_{L_t^\infty \dot{H}_x^{1,0}} + \left\| t^{-\alpha} f \right\|_{L_t^\infty H_x^{0,1}} + \|u\|_{L_t^\infty L_x^2}$$

Proposition (Local Well-Posedness)

Given $\epsilon > 0$ sufficiently small and a function $u_1(x)$ satisfying

$$\|u_1\|_{H_x^{1,0} \cap H_x^{0,1}} \leq \epsilon,$$

there exists $T > 1$ and a unique solution

$$u \in C([0, T]; H_x^{1,0}(\mathbb{R}) \cap H_x^{0,1}(\mathbb{R}))$$

to NLS satisfying

$$\|u\|_{X_T} \lesssim \epsilon.$$

- We have switched to prescribing Cauchy data at $t = 1$ (always OK w/ “real” Cauchy problem by shrinking ϵ more if necessary)

Sketch of the Bootstrap Argument 1

Definition (Bootstrap Norm)

In terms of a given $T > 0$ and some small $\alpha \ll 1$ to be determined later,

$$\|u\|_{X_T} = \left\| t^{1/2} u \right\|_{L_t^\infty L_x^\infty} + \left\| t^{-\alpha} u \right\|_{L_t^\infty \dot{H}_x^{1,0}} + \left\| t^{-\alpha} f \right\|_{L_t^\infty H_x^{0,1}} + \|u\|_{L_t^\infty L_x^2}$$

Sketch of the Bootstrap Argument 1

Definition (Bootstrap Norm)

In terms of a given $T > 0$ and some small $\alpha \ll 1$ to be determined later,

$$\|u\|_{X_T} = \left\| t^{1/2} u \right\|_{L_t^\infty L_x^\infty} + \left\| t^{-\alpha} u \right\|_{L_t^\infty \dot{H}_x^{1,0}} + \left\| t^{-\alpha} f \right\|_{L_t^\infty H_x^{0,1}} + \|u\|_{L_t^\infty L_x^2}$$

- To prove linear decay of $u(t, x)$ enough to control $\|u\|_{X_T}$
- To do this, we use the bootstrap principle and first prove that

$$\|u\|_{X_T} \leq \epsilon + C \|u\|_{X_T}^3 \quad (\star)$$

where ϵ controls size of Cauchy data

Sketch of the Bootstrap Argument 2

- Idea: if \star is true and we assume $\|u\|_{X_T}$ is “small”, then it is actually “really small”

Sketch of the Bootstrap Argument 2

- Idea: if \star is true and we assume $\|u\|_{X_T}$ is “small”, then it is actually “really small”
- Rigorously: start with an X_T -small local solution constructed earlier, flow out again for a short time, then use \star to show we always stay X_T -small

Sketch of the Bootstrap Argument 2

- Idea: if \star is true and we assume $\|u\|_{X_T}$ is “small”, then it is actually “really small”
- Rigorously: start with an X_T -small local solution constructed earlier, flow out again for a short time, then use \star to show we always stay X_T -small
- Iterate to prove global existence with linear decay

Sketch of the Bootstrap Argument 2

- Idea: if \star is true and we assume $\|u\|_{X_T}$ is “small”, then it is actually “really small”
- Rigorously: start with an X_T -small local solution constructed earlier, flow out again for a short time, then use \star to show we always stay X_T -small
- Iterate to prove global existence with linear decay
- So: it remains to prove \star ...

Proof of \star : L_x^2 -type bounds, part 1

Lemma

Let $u(t, x)$ be the local solution constructed to NLS constructed earlier. There exists some constant $C > 0$ such that

$$\sup_{t \in [1, T]} t^{-\alpha} \left[\|u(t, x)\|_{\dot{H}_x^{1,0}} + \|f(t, x)\|_{H_x^{0,1}} \right] \leq \epsilon + C \|u\|_{X_T}^3.$$

- The only hard part involves the bound on $\|f(t, x)\|_{H_x^{0,1}}$, we sketch the proof on next slide

Proof of \star : L_x^2 -type bounds, part 2

- Recall that the profile ODE is

$$\partial_t \hat{f} = \frac{i\lambda}{2\pi} \int d\eta \int d\sigma e^{it\eta(\xi-\sigma)} \hat{f}(t, \xi - \eta) \hat{f}(t, \sigma) \overline{\hat{f}}(t, \sigma - \eta)$$

Use this to get all our bounds

Proof of \star : L_x^2 -type bounds, part 2

- Recall that the profile ODE is

$$\partial_t \hat{f} = \frac{i\lambda}{2\pi} \int d\eta \int d\sigma e^{it\eta(\xi-\sigma)} \hat{f}(t, \xi - \eta) \hat{f}(t, \sigma) \overline{\hat{f}}(t, \sigma - \eta)$$

Use this to get all our bounds

- To estimate $\|xf(t, x)\|_{L_x^2}$, obsv. enough to estimate $\|\partial_\xi \hat{f}(t, x)\|_{L_\xi^2}$ using ODE above (integrate wrt time)
- When ∂_ξ hits the exponential term $e^{it\eta(\xi-\sigma)}$, gain an extra factor of $t!$ Bad news

Proof of \star : L_x^2 -type bounds, part 2

- Recall that the profile ODE is

$$\partial_t \hat{f} = \frac{i\lambda}{2\pi} \int d\eta \int d\sigma e^{it\eta(\xi-\sigma)} \hat{f}(t, \xi - \eta) \hat{f}(t, \sigma) \overline{\hat{f}(t, \sigma - \eta)}$$

Use this to get all our bounds

- To estimate $\|xf(t, x)\|_{L_x^2}$, obsv. enough to estimate $\left\| \partial_\xi \hat{f}(t, x) \right\|_{L_\xi^2}$ using ODE above (integrate wrt time)
- When ∂_ξ hits the exponential term $e^{it\eta(\xi-\sigma)}$, gain an extra factor of $t!$ Bad news
- Avoid this issue by changing variables $\sigma \mapsto \xi - \sigma$ so phase turns into $\eta\sigma$. Only doable bcz of special structure of nonlinearity

Proof of \star : L_x^∞ -type bounds, part 1

- We start by strategically isolating the leading-order behaviour in the profile ODE:

Lemma

We may decompose $\partial_t \hat{f}(t, \xi)$ into the following form:

$$\partial_t \hat{f}(t, \xi) = i\lambda t^{-1} |\hat{f}(t, \xi)|^2 \hat{f}(t, \xi) + R(t, \xi)$$

and there exists $\delta \in (3\alpha, \frac{1}{4})$ such that

$$|R(t, \xi)| \lesssim t^{-1-\delta+3\alpha} \|u\|_{X_T}^3.$$

- Skip the proof today, mostly computation and easy bounds

Proof of \star : L_x^∞ -type bounds, part 2

Lemma

$$\sup_{t \in [1, T]} t^{1/2} \|u\|_{L_x^\infty} \leq \epsilon + C \|u\|_{X_T}^3$$

Proof of \star : L_x^∞ -type bounds, part 2

Lemma

$$\sup_{t \in [1, T]} t^{1/2} \|u\|_{L_x^\infty} \leq \epsilon + C \|u\|_{X_T}^3$$

- To prove this, start with previous result:

$$\partial_t \hat{f}(t, \xi) = i\lambda t^{-1} |\hat{f}(t, \xi)|^2 \hat{f}(t, \xi) + R(t, \xi)$$

Lemma

$$\sup_{t \in [1, T]} t^{1/2} \|u\|_{L_x^\infty} \leq \epsilon + C \|u\|_{X_T}^3$$

- To prove this, start with previous result:

$$\partial_t \hat{f}(t, \xi) = i\lambda t^{-1} |\hat{f}(t, \xi)|^2 \hat{f}(t, \xi) + R(t, \xi)$$

- Pretend $|\hat{f}(t, \xi)|^2$ does not depend on \hat{f} , then we can simplify the profile ODE by introducing an *integrating factor*:

$$B(t, \xi) \doteq \lambda \int_1^t \frac{ds}{s} |\hat{f}(s, \xi)|^2$$
$$\Rightarrow \partial_t \left(\hat{f}(t, \xi) e^{-iB(t, \xi)} \right) = R(t, \xi) e^{-iB(t, \xi)}$$

Proof of \star : L_x^∞ -type bounds, part 3

- Integrating wrt time gives

$$\widehat{w}(t, \xi) \doteq \widehat{f} e^{-iB} = \widehat{f}(1, \xi) + \int_1^t ds R(s, \xi) e^{-iB(s, \xi)}$$

Proof of \star : L_x^∞ -type bounds, part 3

- Integrating wrt time gives

$$\widehat{w}(t, \xi) \doteq \widehat{f} e^{-iB} = \widehat{f}(1, \xi) + \int_1^t ds R(s, \xi) e^{-iB(s, \xi)}$$

- Can replace \widehat{f} with \widehat{w} any time we need a bound in terms of $|\widehat{f}|$: good since \widehat{w} is controlled easily in terms of ICs and remainder R !

Proof of \star : L_x^∞ -type bounds, part 3

- Integrating wrt time gives

$$\widehat{w}(t, \xi) \doteq \widehat{f} e^{-iB} = \widehat{f}(1, \xi) + \int_1^t ds R(s, \xi) e^{-iB(s, \xi)}$$

- Can replace \widehat{f} with \widehat{w} any time we need a bound in terms of $|\widehat{f}|$: good since \widehat{w} is controlled easily in terms of ICs and remainder R !
- By linear Schrödinger asymptotics lemma applied to $u = e^{\frac{it}{2}\partial_x^2} f$ there is some $\kappa \ll 1$ such that

$$\|u(t, x)\|_{L_x^\infty} \leq t^{-1/2} \left\| \widehat{f}(t, \xi) \right\|_{L_\xi^\infty} + t^{-1/2-\kappa} \|f(t, x)\|_{H_x^{0,1}}.$$

- First term dealt with by remainder estimate, second one by earlier L_x^2 -type estimates.

Proof of \star : L_x^∞ -type bounds, part 3

- Integrating wrt time gives

$$\widehat{w}(t, \xi) \doteq \widehat{f} e^{-iB} = \widehat{f}(1, \xi) + \int_1^t ds R(s, \xi) e^{-iB(s, \xi)}$$

- Can replace \widehat{f} with \widehat{w} any time we need a bound in terms of $|\widehat{f}|$: good since \widehat{w} is controlled easily in terms of ICs and remainder R !
- By linear Schrödinger asymptotics lemma applied to $u = e^{\frac{it}{2}\partial_x^2} f$ there is some $\kappa \ll 1$ such that

$$\|u(t, x)\|_{L_x^\infty} \leq t^{-1/2} \left\| \widehat{f}(t, \xi) \right\|_{L_\xi^\infty} + t^{-1/2-\kappa} \|f(t, x)\|_{H_x^{0,1}}.$$

- First term dealt with by remainder estimate, second one by earlier L_x^2 -type estimates. **BOOTSTRAP ARGUMENT DONE!**

Existence of Asymptotic Profile

- We know

$$\widehat{w}(t, \xi) = \widehat{f}(t, \xi) e^{-iB(t, \xi)} = \widehat{f}(1, \xi) + \int_1^t ds R(s, \xi) e^{-iB(s, \xi)}$$

and from earlier heuristics we expect

$$\widehat{f}(t, \xi) \approx e^{i\lambda|F(\xi)|^2 \log t} F(\xi), \quad t \gg 1$$

Existence of Asymptotic Profile

- We know

$$\widehat{w}(t, \xi) = \widehat{f}(t, \xi) e^{-iB(t, \xi)} = \widehat{f}(1, \xi) + \int_1^t ds R(s, \xi) e^{-iB(s, \xi)}$$

and from earlier heuristics we expect

$$\widehat{f}(t, \xi) \approx e^{i\lambda|F(\xi)|^2 \log t} F(\xi), \quad t \gg 1$$

- Since

$$B(t, \xi) = \lambda \int_1^t \frac{ds}{s} \left| \widehat{f}(s, \xi) \right|^2 \approx \lambda |F(\xi)|^2 \log t$$

we should therefore try to prove

$$\lim_{t \rightarrow \infty} \widehat{w}(t, \xi) = F(\xi).$$

ie. show $\widehat{w}(t, \xi)$ is Cauchy wrt t in L_ξ^∞ . *Easy using control of $R(t, \xi)$!*

- Now, we want to conclude

$$u(t, x) = (it)^{-1/2} F(x/t) \exp\left(\frac{i|x|^2}{2t} + i|F(x/t)|^2 \log t + i\phi(x/t)\right) + \mathcal{O}\left(t^{-1/2-\beta}\right)$$

- Existence of $\phi(\xi)$ follows from same tricks used to get $F(\xi)$, as well as

$$B(t, \xi) \rightarrow \lambda|F(\xi)|^2 \log t + \phi(\xi)$$

- Combine above with $\widehat{w}(t, \xi) \rightarrow F(\xi)$ and

$$\|u\|_{X_T} \lesssim \epsilon$$

to conclude (after doing some accounting in the error term)

Final Remarks

- Very similar arguments work to get asymptotics for Hartree equation (nonlinear term = $(|x|^{-1} * |u^2|) u$) or *systems* of NLS with nonlinear term = $|u_a|^2 u_b$

Final Remarks

- Very similar arguments work to get asymptotics for Hartree equation (nonlinear term = $(|x|^{-1} * |u^2|) u$) or *systems* of NLS with nonlinear term = $|u_a|^2 u_b$
- Life is usually not as easy as NLS though: generically we must at least understand oscillatory integral in profile ODE via Littlewood-Paley decomposition

Final Remarks

- Very similar arguments work to get asymptotics for Hartree equation (nonlinear term = $(|x|^{-1} * |u^2|) u$) or *systems* of NLS with nonlinear term = $|u_a|^2 u_b$
- Life is usually not as easy as NLS though: generically we must at least understand oscillatory integral in profile ODE via Littlewood-Paley decomposition
- Space-time resonance strategy may need to be massaged for some difficult systems like mKdV (combine with method of vector fields)

Final Remarks

- Very similar arguments work to get asymptotics for Hartree equation (nonlinear term = $(|x|^{-1} * |u^2|) u$) or *systems* of NLS with nonlinear term = $|u_a|^2 u_b$
- Life is usually not as easy as NLS though: generically we must at least understand oscillatory integral in profile ODE via Littlewood-Paley decomposition
- Space-time resonance strategy may need to be massaged for some difficult systems like mKdV (combine with method of vector fields)
- Optimistic about a space-time resonance approach to generalized Benjamin-Bona-Mahony (more on this in the future)!

Questions?