

Example  $\int_1^2 \ln x \, dx \stackrel{x=e^u}{=} \int_0^{\ln 2} u e^u \, du =$

$$dx = e^u du$$

$$1 = e^0$$

$$2 = e^{\ln 2}$$

by parts  $(u-1)e^u \Big|_0^{\ln 2} = 2\ln 2 - 1$

Double integral: polar coordinates

$$x = r \cos \theta \quad y = r \sin \theta$$

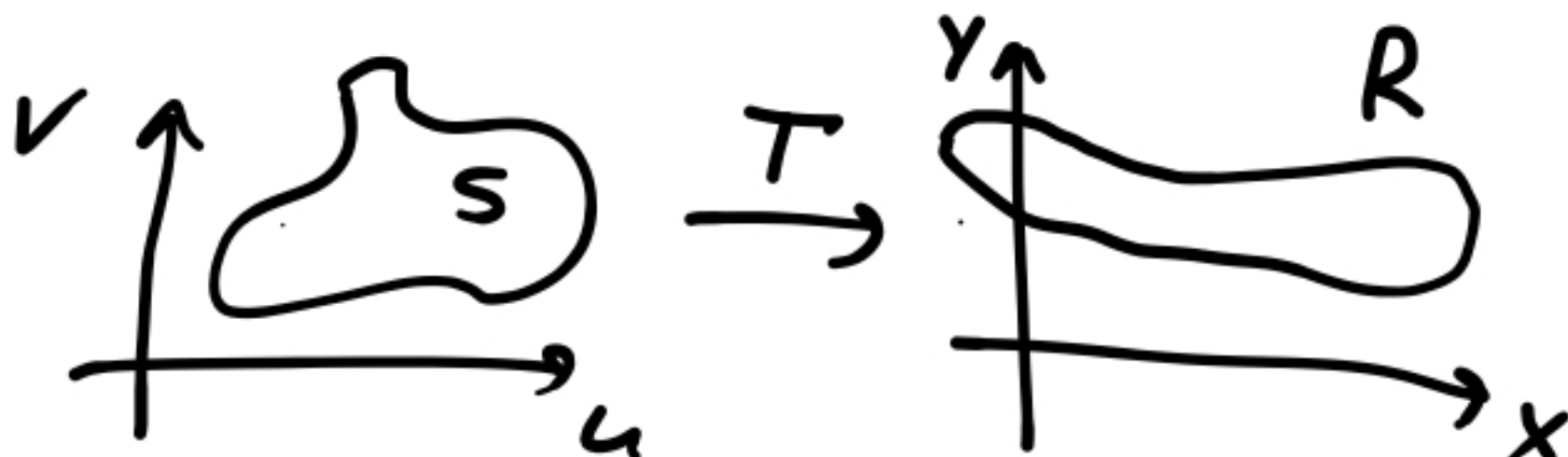
$$\iint_R f(x, y) \, dA = \iint_S f(r \cos \theta, r \sin \theta) r \, dr \, d\theta$$

$S$ -region in  $r\theta$ -plane  
that corresponds to  $R$  in  $xy$ -plane

e.g. if  $R = \{(x, y) \mid x^2 + y^2 \leq 1\}$   $S = \{(r, \theta) \mid 0 \leq r \leq 1, 0 \leq \theta \leq 2\pi\}$

## General setting

Transformation  $T$   $\begin{cases} x = g(u, v) \\ y = h(u, v) \end{cases}$   
from  $uv$ -plane to  $xy$ -plane



$T$  transforms  $S$  into  $R$

## Example

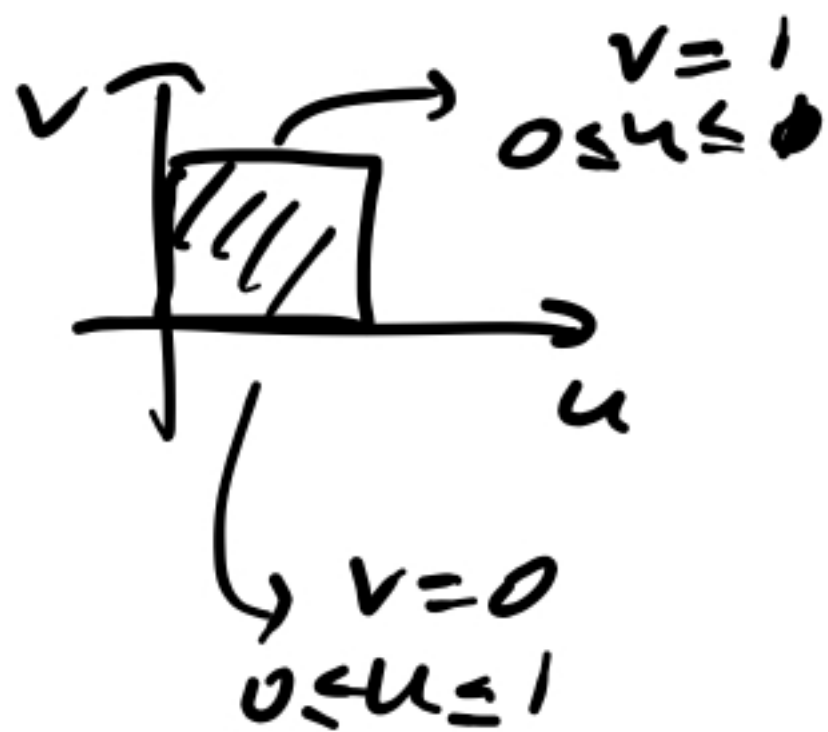
$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$T$  transforms  $S = [0, 1] \times [0, 2\pi]$   
into  $R = \left\{ \begin{array}{l} x^2 + y^2 \leq 1 \\ (x, y) \end{array} \right\}$

Example Find the image of

$S = \{ (u, v) \mid \begin{matrix} 0 \leq u \leq 1 \\ 0 \leq v \leq 1 \end{matrix} \}$  under transformation

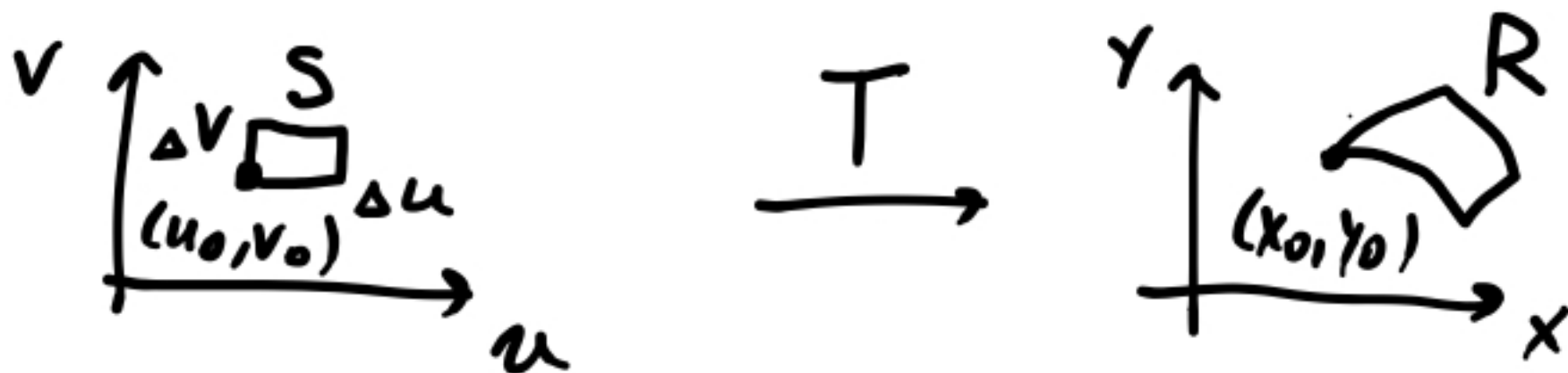
$$\begin{aligned} x &= u^2 - v^2 \\ y &= 2uv \end{aligned}$$



$$\begin{aligned} x &= u^2 - 1 \\ y &= 2u \\ x &= \frac{y^2}{4} - 1 \end{aligned}$$

$$\begin{aligned} x &= u^2 - 0 \\ y &= 0 \end{aligned}$$

What happens to the integral?



$$\mathbf{r}(u, v) = g(u, v)\hat{i} + h(u, v)\hat{j} + 0\hat{k}$$

position vector  
of the image of  
point  $(u, v)$

Idea:

Approximate  $R$  with a parallelogram



$$\vec{a} = \mathbf{r}(u_0, v_0 + \Delta v) - \mathbf{r}(u_0, v_0)$$

$$\vec{b} = \mathbf{r}(u_0 + \Delta u, v_0) - \mathbf{r}(u_0, v_0)$$

Recall,  $r_u = \lim_{\Delta u \rightarrow 0} \frac{r(u_0 + \Delta u, v_0) - r(u_0, v_0)}{\Delta u}$   
 (partial derivative)

So  $\vec{a} \approx r_v \cdot \Delta v$   
 $\vec{b} \approx r_u \cdot \Delta u$

Approximate area of  $R$ :

$$\begin{aligned} \|\vec{a} \wedge \vec{b}\| &= \|(r_u \cdot \Delta u) \times (r_v \cdot \Delta v)\| = \\ &= \|\underline{r_u} \times \underline{r_v}\| \cdot \underline{\Delta u} \cdot \underline{\Delta v} \end{aligned}$$

$$r_u \times r_v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & 0 \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & 0 \end{vmatrix} = \underbrace{\begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix}}_{\text{Jacobian of transformation T}} \hat{k}$$

Jacobian of  
 transformation T

# Result

$$\iint_R f(x,y) dA = \iint_S f(g(u,v), h(u,v)) \underbrace{|J|}_{\|g_u h_v - g_v h_u\|} du dv$$

$$g = r \cos \theta$$
$$h = r \sin \theta$$

Exercise: find the  
Jacobian