

# MAT244, 2014F, Solutions to Final Exam

**Problem 1.** Solve the initial value problem

$$(3x + 2y) dx + \left(x + \frac{6y^2}{x}\right) dy = 0 \quad y(0) = 3.$$

*Solution.* As  $M = 3x + 2y$ ,  $N = x + \frac{6y^2}{x}$ ,  $M_y - N_x = 2 - \left(1 - \frac{6y^2}{x^2}\right)$  and  $(M_y - N_x)/N = 1/x$  is a function of  $x$  only. So we can find integrating factor  $\mu = \mu(x)$  from  $\mu'/\mu = 1/x \implies \ln \mu = \ln x$  (modulo constant factor) and  $\mu = x$ . Therefore

$$(3x^2 + 2xy)dx + (x^2 + 6y^2)dy = 0.$$

then

$$U_x = 3x^2 + 2xy, \quad U_y = x^2 + 6y^2$$

where the first equation implies that

$$U = x^3 + x^2y + \phi(y)$$

and plugging to the second equation we see that

$$\phi' = 6y^2 \implies \phi = 2y^3.$$

Then

$$U := x^3 + x^2y + 2y^3 = C$$

is a general solution and finding  $C = 54$  from initial condition we arrive to

$$U := x^3 + x^2y + 2y^3 = 54.$$

□

**Problem 2.** Find the general solution of

$$x^4 y^{(4)} + 6x^3 y^{(3)} + 7x^2 y^{(2)} + xy' - y = 3 \ln x + \cos(\ln x).$$

*Solution.* It is Euler's equation. Its characteristic polynomial is

$$\begin{aligned} r(r-1)(r-2)(r-3) + 6r(r-1)(r-2) + 7r(r-1) + r - 1 = \\ r^4 - 6r^3 + 11r^2 - 6r + 6r^3 - 18r^2 + 12r + 7r^2 - 7r + r - 1 = r^4 - 1 \end{aligned}$$

with characteristic roots  $r_{1,2} = \pm 1$ ,  $r_{3,4} = \pm i$  and plugging  $t = \ln x$  we arrive to

$$y_t^{(4)} - y = 3t + \cos(t). \quad (2.1)$$

Solution to homogeneous equation is

$$\begin{aligned} z = C_1 e^t + C_2 e^{-t} + C_3 \cos(t) + C_4 \sin(t) = \\ C_1 x + C_2 x^{-1} + C_3 \cos(\ln x) + C_4 \sin(\ln x) \end{aligned} \quad (2.2)$$

and the particular solution to inhomogeneous equation is  $y_p = y_{p1} + y_{p2}$  with  $y_{p1} = at + b$  and  $y_{p2} = (c \cos(t) + d \sin(t))t$  solving equation with right hand expressions  $f_1 = 3 \ln x$  and  $f_2 = \cos(\ln x)$  respectively.

Plugging  $y_{p1}$  we get

$$-at - b = 3t \implies a = -3, b = 0 \implies y_{p1} = -3t = -3 \ln x \quad (2.3)$$

and plugging  $y_{p2}$  we get

$$\begin{aligned} 3(c \sin(t) - d \cos(t)) = \cos(t) \implies c = 0, d = -\frac{1}{3} \implies \\ y_{p2} = -\frac{1}{3} \sin(t)t = -\frac{1}{3} \sin(\ln x) \ln x. \end{aligned} \quad (2.4)$$

Adding (2.2)–(2.4) we get

$$y = C_1 x + C_2 x^{-1} + C_3 \cos(\ln x) + C_4 \sin(\ln x) - 3 \ln x - \frac{1}{3} \sin(\ln x) \ln x.$$

□

**Problem 3.** Find the general solution of the system of ODEs

$$\begin{cases} x'_t = -\frac{5}{4}x + \frac{3}{4}y + \frac{2}{1+e^t}, \\ y'_t = \frac{3}{4}x - \frac{5}{4}y. \end{cases}$$

*Solution.* Characteristic equation is

$$\begin{vmatrix} -\frac{5}{4} - r & \frac{3}{4} \\ \frac{3}{4} & \frac{5}{4} - r \end{vmatrix} = (r + \frac{5}{4})^2 - \frac{9}{16} = 0$$

with characteristic roots  $r_{1,2} = -\frac{5}{4} \pm \frac{3}{4}$ ,  $r_1 = -\frac{1}{2}$ ,  $r_2 = -2$ .

Finding corresponding eigenvectors: (a)  $r_1 = 1$ ,

$$\begin{pmatrix} -\frac{3}{4} & \frac{3}{4} \\ \frac{3}{4} & -\frac{3}{4} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = 0$$

and then  $\alpha = \beta = 1$  and eigenvector is  $\mathbf{e}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ .

(b)  $r_2 = 2$  and  $\mathbf{e}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  (since matrix is symmetric eigenvectors are orthogonal).

Therefore the general solution of the homogeneous system is

$$\begin{pmatrix} x^* \\ y^* \end{pmatrix} = C_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-\frac{1}{2}t} + C_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-2t}. \quad (3.1)$$

To solve inhomogeneous system we use method of variation of parameters leading to

$$\begin{pmatrix} e^{-\frac{t}{2}} & e^{-2t} \\ e^{-\frac{t}{2}} & -e^{-2t} \end{pmatrix} \begin{pmatrix} C_1' \\ C_2' \end{pmatrix} = \begin{pmatrix} \frac{2}{1+e^t} \\ 0 \end{pmatrix} \implies$$

$$C_1' = \frac{e^{\frac{t}{2}}}{1+e^t} \implies C_1 = \int \frac{e^{\frac{t}{2}}}{1+e^t} dt = 2 \arctan(e^{\frac{t}{2}}) + c_1,$$

$$C_2' = \frac{e^{2t}}{1+e^{2t}} \implies C_2 = \int \frac{e^{2t}}{1+e^t} dt = \int \left( e^t - \frac{e^t}{1+e^t} \right) dt = e^t - \ln(1+e^t) + c_2$$

where the first integral is taken by substitution  $u = e^{\frac{t}{2}}$  and the second by substitution  $u = 1 + e^t$ .

Thus

$$\begin{pmatrix} x \\ y \end{pmatrix} = (2 \arctan(e^{\frac{t}{2}}) + c_1) \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-\frac{1}{2}t} + (e^t - \ln(1+e^t) + c_2) \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-2t}.$$

□

**Problem 4.** Find the general solution of the ODE

$$xy' = y - xe^{y/x}$$

and solve the initial value problem  $y(1) = -2$ .

*Solution.* Since it is homogeneous equation we plug  $y = ux$  and then

$$\begin{aligned} u'x^2 + ux &= ux - xe^u \implies u' = -e^u \implies x^{-1}dx = -e^{-u}du \implies \\ \ln x &= e^{-u} + \ln C \implies u = -\ln \ln(Cx) \implies y = -x \ln \ln(Cx). \end{aligned}$$

As  $x = 1$ ,  $y = -2$ ,  $u = -2$  we get  $\ln \ln C = 2$ , and  $y = -x \ln(e^2 + \ln x)$ .  $\square$

**Problem 5.** For the system of ODEs

$$\begin{cases} x'_t = x(5 - 2x - 3y), \\ y'_t = y(5 - 3x - 2y) \end{cases}$$

- (a) describe the locations of all critical points,
- (b) classify their types (including whatever relevant: stability, orientation, etc.),
- (c) sketch the phase portraits near the critical points,
- (d) sketch the phase portrait of this system of ODEs.

*Solution.* (a) Solving  $x(5 - 2x - 3y) = 0$ ,  $y(5 - 3x - 2y) = 0$  we have 4 cases  $x = y = 0$ ,  $x = 5 - 3x - 2y = 0$ ,  $y = 5 - 2x - 3y = 0$  and  $5 - 3x - 2y = 5 - 2x - 3 = 0$  giving us 4 points  $(0, 0)$ ,  $(0, \frac{5}{2})$ ,  $(\frac{5}{2}, 0)$  and  $(1, 1)$ .

(b) Let  $f = x(5 - 2x - 3y) = 5x - 2x^2 - 3xy$ ,  $g = y(5 - 3x - 2y) = 5y - 2y^2 - 3xy$ . Then  $f_x = 5 - 4x - 3y$ ,  $f_y = -3x$ ,  $g_x = -3y$ ,  $g_y = 5 - 4y - 3x$ .

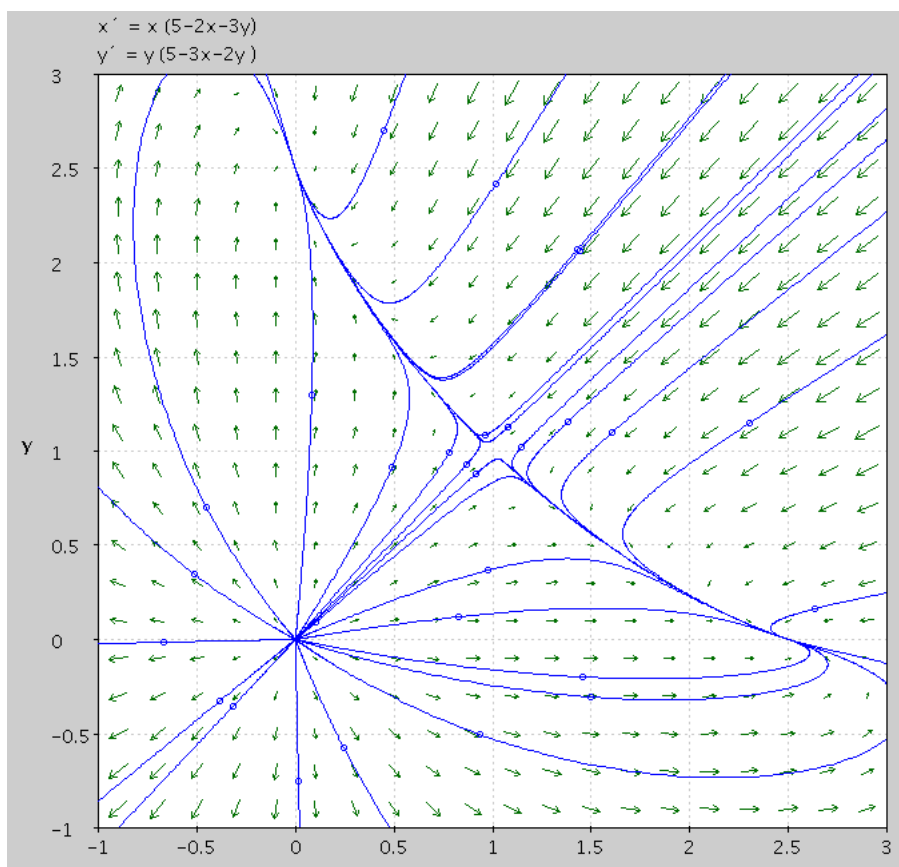
(i)  $(0, 0)$ ; matrix  $\begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix}$  at this point equals  $\begin{pmatrix} 5 & 0 \\ 0 & 5 \end{pmatrix}$  with eigenvalues  $r_1 = r_2 = 5$ ; and eigenvectors  $(1, 0)^T$  and  $(0, 1)^T$ ; unstable node;

(ii)  $(0, \frac{5}{2})$ ; matrix  $\begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix}$  at this point equals  $\begin{pmatrix} -\frac{5}{2} & 0 \\ -\frac{15}{2} & -5 \end{pmatrix}$  with eigenvalues  $r_1 = -\frac{5}{2}$ ,  $r_2 = -5$  and eigenvectors  $(1, -3)^T$  and  $(1, 0)^T$  respectively; stable node;

(iii)  $(\frac{5}{2}, 0)$ ; the same as in (ii);

(iv)  $(1, 1)$ ; matrix  $\begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix}$  at this point equals  $\begin{pmatrix} -2 & -3 \\ -3 & -2 \end{pmatrix}$  with eigenvalues  $r_1 = -5$  and  $r_2 = 1$  and eigenvectors  $(1, 1)^T$  and  $(1, -1)^T$  respectively; saddle.

(c-d) Plotting



*Remark.* This is “two competing species” system.

□

**Problem 6.** For the system of ODEs

$$\begin{cases} x'_t = 4x^2y - 2x^2 - 4xy + 2y, \\ y'_t = -4xy^2 + 2y^2 + 4xy - 2x \end{cases}$$

(a) linearize the system at  $x_0 = 1, y_0 = 1$  and sketch the phase portrait of this linear system,

(b) find the equation of the form  $H(x, y) = C$  satisfied by the trajectories of the nonlinear system,

(c) describe the type of the critical point  $x_0 = 1, y_0 = 1$  of the nonlinear system.

*Solution.* (a) Let  $f = 4x^2y - 2x^2 - 4xy + 2y$ ,  $g = -4xy^2 + 2y^2 + 4xy - 2x$ ; then  $f_x(1, 1) = 0$ ,  $f_y(1, 1) = 2$ ,  $g_x(1, 1) = -2$ ,  $g_y(1, 1) = 0$  and the linearized system is

$$\begin{cases} X'_t = 2Y, \\ Y'_t = -2X \end{cases}$$

with phase portrait consisting of clock-wise circles.

(b) Rewriting system as  $f dx - g dy = 0$  we get

$$(4xy^2 - 2y^2 - 4xy + 2x) dx + (4x^2y - 2x^2 - 4xy + 2y) dy = 0$$

which is exact; then

$$H_x = 4xy^2 - 2y^2 - 4xy + 2x, \quad H_y = 4x^2y - 2x^2 - 4xy + 2y$$

and the first equation implies that

$$H = 2x^2y^2 - 2xy^2 - 2x^2y + x^2 + \phi(y)$$

and the second equation implies that  $\phi' = 2y$  and  $y = y^2$  and then

$$H = 2x^2y^2 - 2xy^2 - 2x^2y + x^2 + y^2 = x^2(y - 1)^2 + y^2(x - 1)^2.$$

(c) Since linearized system has a center and original system has a solution  $H(x, y) = C$  the type of the stationary point is a center.

*Remark.* In fact the system has also critical point  $(0, 0)$  of the type center, and critical point  $(\frac{1}{2}, \frac{1}{2})$  of the type saddle (see next page)

□

