

3 - Topology of \mathbb{C}

It is going to be the exact same thing as in the multivariable calculus class.

Definition: The open disk of \mathbb{C} centered at $z_0 \in \mathbb{C}$ and of radius $\varepsilon > 0$ is

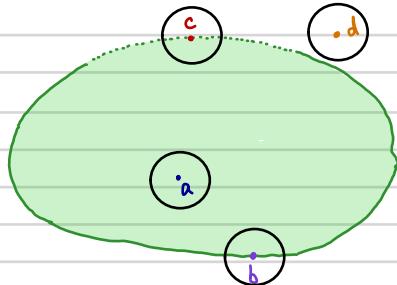
$$D_\varepsilon(z_0) := \{z \in \mathbb{C} : |z - z_0| < \varepsilon\}$$

(You can also see the name ε -vicinity of z_0)

Definition: $V \subset \mathbb{C}$ is a neighborhood of z_0 if $\exists \varepsilon > 0$, $D_\varepsilon(z_0) \subset V$.

Definition: A subset $S \subset \mathbb{C}$ is bounded if there exists $r > 0$ s.t. $S \subset D_r(0)$

Let's fix a subset $S \subset \mathbb{C}$.



$a \in S$	$b \in S$	$c \notin S$	$d \notin S$
$a \in S$	$b \notin S$	$c \notin S$	$d \notin S$
$a \notin S$	$b \in S$	$c \in S$	$d \notin S$
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Definition: the interior of S is $\overset{\circ}{S} := \{z \in \mathbb{C} : \exists \varepsilon > 0, D_\varepsilon(z) \subset S\}$
(or S^{int})

Definition: the closure of S is $\bar{S} := \{z \in \mathbb{C} : \forall \varepsilon > 0, D_\varepsilon(z) \cap S \neq \emptyset\}$

Theorem: $\overset{\circ}{S} \subset S \subset \bar{S}$

$\Delta \overset{\circ}{S} \subset S$: Let $z \in \overset{\circ}{S}$ then $\exists \varepsilon > 0$ s.t. $D_\varepsilon(z) \subset S$, hence $z \in D_\varepsilon(z) \subset S$, $\Rightarrow z \in S$

$S \subset \bar{S}$: Let $z \in S$. Pick $\varepsilon > 0$, then $z \in S \cap D_\varepsilon(z)$

hence $\forall \varepsilon > 0$, $S \cap D_\varepsilon(z) \neq \emptyset$, and $z \in \bar{S}$

□

Definition: the boundary of S is $\partial S := \bar{S} \setminus \overset{\circ}{S}$

Proposition: $\bar{S} = S \cup \partial S$ and $\overset{\circ}{S} \cap \partial S = \emptyset$

Δ Trivial □

Theorem: $\partial S = \{z \in \mathbb{C} : \forall \varepsilon > 0, D_\varepsilon(z) \cap S \neq \emptyset \text{ and } D_\varepsilon(z) \cap S^c \neq \emptyset\}$

$\Delta z \in \bar{S} \Leftrightarrow \forall \varepsilon > 0, D_\varepsilon(z) \cap S \neq \emptyset$

$z \notin \overset{\circ}{S} \Leftrightarrow \exists \varepsilon > 0, D_\varepsilon(z) \subset S^c \Leftrightarrow \forall \varepsilon > 0, D_\varepsilon(z) \cap S^c \neq \emptyset$

□

Corollary: $\partial S = \partial(S^c)$

Δ Note that $(S^c)^c = S$ □

Definition: $S \subset \mathbb{C}$ is open if $\overset{\circ}{S} = S$

Theorem: S open $\Leftrightarrow S \cap \partial S = \emptyset$

$\Delta \Rightarrow$: Assume that S is open, then $S \cap \partial S = \overset{\circ}{S} \cap \partial S = \emptyset$

\Leftarrow : We prove the contrapositive: S not open $\Rightarrow S \cap \partial S \neq \emptyset$

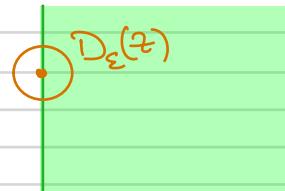
Assume that S is not open, then $\overset{\circ}{S} \subsetneq S$, i.e. $\exists z \in S \setminus \overset{\circ}{S}$
but $S \setminus \overset{\circ}{S} \subset \overline{S} \setminus \overset{\circ}{S} = \partial S$, so $z \in S \cap \partial S$ and $S \cap \partial S \neq \emptyset$ \square

Theorem: S open $\Leftrightarrow \forall z \in S, \exists \varepsilon > 0, D_\varepsilon(z) \subset S$

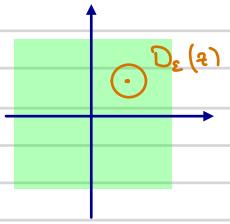
$\Delta \Rightarrow$: let $z \in S$ then $z \in \overset{\circ}{S}$ since $\overset{\circ}{S} = S$, so $\exists \varepsilon > 0, D_\varepsilon(z) \subset S$

\Leftarrow : We already know that $\overset{\circ}{S} \subset S$, let's prove that $S \subset \overset{\circ}{S}$.
Let $z \in S$ then $\exists \varepsilon > 0, D_\varepsilon(z) \subset S$ hence $z \in \overset{\circ}{S}$
Therefore $S \subset \overset{\circ}{S}$.

Eg: $\{z \in \mathbb{C} : \operatorname{Re}(z) \geq 0\}$ is not open



Eg: $\{z \in \mathbb{C} : \max(|\operatorname{Re}(z)|, |\operatorname{Im}(z)|) < 1\}$ is open



Definition: $S \subset \mathbb{C}$ is closed if $\overline{S} = S$

Theorem: S closed $\Leftrightarrow \partial S \subset S$

$\Delta \Rightarrow$: $\partial S = \overline{S} \setminus \overset{\circ}{S} \subset \overline{S} = S$

\Leftarrow : $\overline{S} = S \cup \partial S = S$ \square

Theorem: S closed $\Leftrightarrow S^c$ open

Δ S closed $\Leftrightarrow \partial S \subset S \Leftrightarrow \partial(S^c) \subset S^c \Leftrightarrow \partial(S^c) \cap S^c = \emptyset \Leftrightarrow S^c$ open \square

Eg: $\{z \in \mathbb{C} : \operatorname{Re}(z) > 0\}$ is closed

$\{z \in \mathbb{C} : |z| \leq 1\}$ is closed

$D_\varepsilon(z)$ is not closed

$\{z \in \mathbb{C} : |z| < 1\}$ is open not closed

$\{z \in \mathbb{C} : |z| \leq 1\}$ is closed not open

\mathbb{C} is open and closed

$\{z \in \mathbb{C} : \operatorname{Re}(z) = 0, \operatorname{Im}(z) > 0\}$ is not open not closed

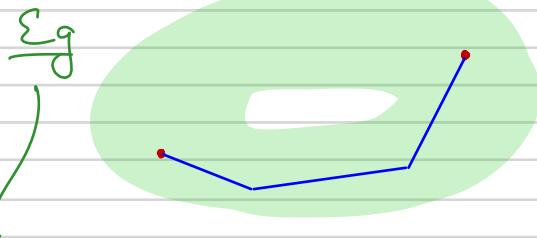
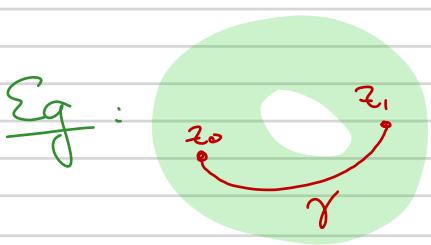


Definition: A subset $S \subset \mathbb{C}$ is path-connected if $\forall z_0, z_1 \in S$,

$\exists \gamma: [0,1] \rightarrow \mathbb{C}$ continuous such that $\gamma(t) \in S$ $\forall t \in [0,1]$

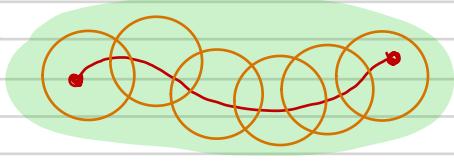
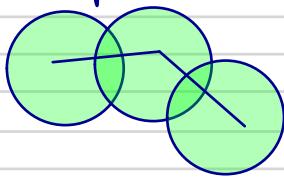
meaning that
both the real and imaginary
parts of γ are continuous

- $\gamma(0) = z_0$
- $\gamma(1) = z_1$



Theorem: An open subset $S \subset \mathbb{C}$ is path-connected if and only if for for $z, w \in S$, there exists a polygonal curve from z to w lying in S
ie: $\exists P_0, \dots, P_m$ s.t. the segment line $[P_i, P_{i+1}] \subset S$ and $P_0 = z, P_m = w$

Idea of proof: in this case, we may cover a path γ from z to w with finitely many open disks lying in S and we use the fact that the disks are convex:



□

Remark: the "open" assumption is very important here, for instance:

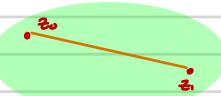
the curve $z \cdot \text{---} \cdot w$ is path-connected, but there is no polygonal curve from z to w lying in it.

Definition: we say that an open set is connected if it is path-connected.

⚠ we only defined connectedness for open sets, there is a more general notion but connectedness and path-connectedness coincide for open sets

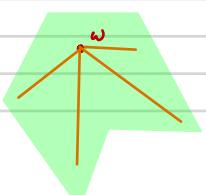
Definition: Domain := open and connected

Definition: $S \subset \mathbb{C}$ is convex if $\forall z_0, z_1 \in S, \forall t \in [0,1], (1-t)z_0 + tz_1 \in S$



Definition: $S \subset \mathbb{C}$ is star-shaped if $\exists w \in S, \forall z \in S, \forall t \in [0,1], (1-t)w + tz \in S$

ϕ is convex but not star-shaped



Remark

$\xrightarrow{\quad}$ convex + non-empty \Rightarrow star-shaped \Rightarrow path-connected

✗

✗

The point at ∞

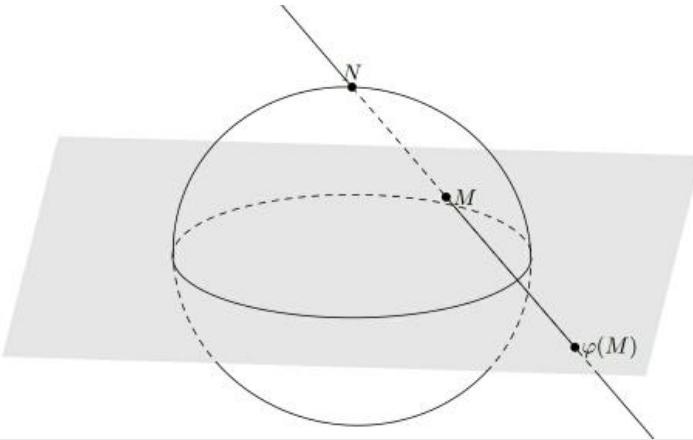
We are going to extend \mathbb{C} by adding one point at ∞ . There are different ways to do that, the model we are going to use is the Riemann Sphere.

$$\mathbb{S}^2 := \{(r, s, t) \in \mathbb{R}^3 : r^2 + s^2 + t^2 = 1\}, N = (0, 0, 1) \text{ "the North Pole"}$$

We identify \mathbb{C} with the plane $P = \{t=0\} \subset \mathbb{R}^3$

We consider the stereographic projection with respect to N :

$$\varphi: \mathbb{S}^2 \setminus \{N\} \xrightarrow{\quad P \quad} M \mapsto (N \bar{M}) \cap P \quad (\text{mapping } M \text{ to the intersection of the line } (MN) \text{ with the plane } P)$$



We may check that φ is a bijection (see next page), then we may identify \mathbb{C} with $\mathbb{S}^2 \setminus \{N\}$ and see N as the point at ∞ .

In practice we simply write $\hat{\mathbb{C}} = \mathbb{C} \sqcup \{\infty\}$.

$$\text{Eq: the inversion extends to } \hat{\mathbb{C}}: \begin{cases} \hat{\mathbb{C}} \xrightarrow{z \mapsto \frac{1}{z}} \hat{\mathbb{C}} \\ \infty \mapsto 0 \\ 0 \mapsto \infty \end{cases} \text{ if } z \neq 0, \infty$$

Definition: We say that $V \subset \mathbb{C}$ is a neighborhood of the ∞ if its complement $\mathbb{C} \setminus V$ is bounded

Theorem: $V \subset \mathbb{C}$ is a neighborhood of ∞ iff $\exists R > 0$ s.t. $\{z \in \mathbb{C} : |z| > R\} \subset V$

$$\begin{aligned} \Delta V \text{ is a neighborhood of } \infty &\Leftrightarrow \mathbb{C} \setminus V \text{ bounded} \\ &\Leftrightarrow \exists R > 0, \mathbb{C} \setminus V \subset \{z \in \mathbb{C} : |z| < R\} \\ &\Leftrightarrow \exists R > 0, \{z \in \mathbb{C} : |z| > R\} \subset V \end{aligned}$$

We obtain a topology on $\hat{\mathbb{C}}$: $S \subset \hat{\mathbb{C}}$ is open if it is a neighborhood of each of its points

$S \subset \hat{\mathbb{C}}$ is open if $\bullet S \cap \mathbb{C}$ is open

$\text{or } \bullet S = \{ \infty \} \cup K^c$ where $K \subset \mathbb{C}$ compact (closed and bounded)

This construction is a special case of a general topological construction called the "one point compactification" or "Alexandrov" compactification.

Proof that ϕ is a bijection:

Take $M = (r, s, t) \in \mathbb{S}^2 \setminus \{\mathbf{N}\}$ and set $M' = \phi(M)$

then $M' = (x, y, \lambda)$ and $\overrightarrow{NM} = \lambda \overrightarrow{NM}$

$$\text{i.e. } \begin{pmatrix} x \\ y \\ -1 \end{pmatrix} = \lambda \begin{pmatrix} r \\ s \\ t-1 \end{pmatrix}$$

$$\text{so } \lambda = \frac{1}{1-t}, x = \frac{r}{1-t}, y = \frac{s}{1-t}$$

$$\text{i.e. } \phi(r, s, t) = \frac{r}{1-t} + i \frac{s}{1-t}$$

We solve $\begin{cases} x = \frac{r}{1-t} \\ y = \frac{s}{1-t} \\ r^2 + s^2 + t^2 = 1 \end{cases}$ to find the inverse.

$$\text{we get } [x(t-1)]^2 + [y(t-1)]^2 + t^2 = 1 \Leftrightarrow (x^2 + y^2 + 1)t^2 - 2(x^2 + y^2)t + (x^2 + y^2 - 1) = 0$$

$$\text{so } t = \frac{x^2 + y^2 - 1}{x^2 + y^2 + 1} \text{ since } t \neq 1$$

$$\text{and } \phi^{-1}(x+iy) = \left(\frac{rx}{x^2+y^2+1}, \frac{sy}{x^2+y^2+1}, \frac{x^2+y^2-1}{x^2+y^2+1} \right)$$

]

A comment about the line-circle equation:

$$a\bar{z}z - \bar{z}z - \gamma\bar{z} + h = 0, a, h \in \mathbb{R}, \gamma \in \mathbb{C}, |\gamma|^2 - ah > 0$$

If we set $w = z^{-1}$ (i.e. we swap 0 and ∞ in $\hat{\mathbb{C}}$) then it becomes

$$a \frac{1}{w} \frac{1}{\bar{w}} - \bar{z} \frac{1}{w} - \gamma \frac{1}{\bar{w}} + h = 0 \Leftrightarrow h w \bar{w} - a \bar{w} - \bar{z} w + a = 0$$

where $a = \bar{\gamma}$

So the inversion maps "generalized line-circles" to "generalized line-circles"
and the equation makes sense in $\hat{\mathbb{C}}$.

⚠ Disclaimer: in $\hat{\mathbb{C}}$ we extended $i: z \mapsto z^{-1}$ so that $\frac{1}{0} = \infty$

But be careful, ∞ is NOT the multiplicative inverse of 0

$$0 \cdot \infty \neq 1$$

Actually we shouldn't say that "we can't divide by 0 " but rather that
we can't define a multiplicative inverse of 0 .