

UNIVERSITY OF TORONTO
 FACULTY OF APPLIED SCIENCE AND ENGINEERING
 FINAL EXAMINATION, APRIL 2018
 DURATION: 2 AND 1/2 HRS
 FIRST YEAR - CHE, CIV, CPE, ELE, ENG, IND, LME, MEC, MMS
MAT188H1S - Linear Algebra
 EXAMINER: D. BURBULLA

Exam Type: A.

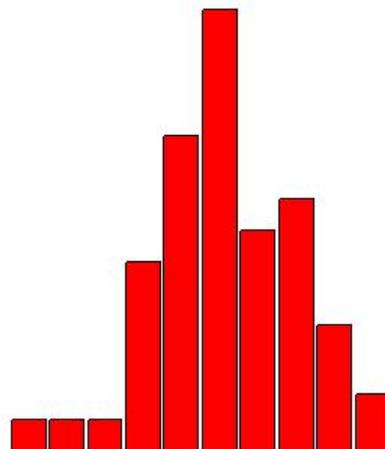
Aids permitted: Casio FX-991 or Sharp EL-520 calculator.

General Comments:

- Six questions had passing averages; four had failing averages. On the whole, Questions 4, 8 and 10 were very poorly done, yet they were not complicated questions. Indeed, many students made questions 1(d), 4, 8 and 10 much more complicated and messy than necessary.
- Many students did not answer the question in Question 9; they attempted to find a linear or other least squares approximation instead. You must answer the question asked!

Breakdown of Results: 54 registered students wrote this test. The marks ranged from 4% to 97%, and the average was only 55.8%. Some statistics on grade distribution are in the table on the left, and a histogram of the marks (by decade) is on the right.

Grade	%	Decade	%
A	11.1%	90-100%	3.7%
		80-89%	7.4%
B	14.8%	70-79%	14.8%
C	13.0%	60-69%	13.0%
D	25.9%	50-59%	25.9%
F	35.2%	40-49%	18.4%
		30-39%	11.1%
		20-29%	1.9%
		10-19%	1.9%
		0-9%	1.9%



1. [avg: 6.8/10] Find the following:

(a) [2 marks] $\dim(S^\perp)$, if S is a subspace of \mathbb{R}^7 and $\dim(S) = 4$.

Solution: $\dim(S^\perp) = 7 - \dim(S) = 7 - 4 = 3$.

(b) [4 marks] $\det(-2AB^{-1}A^T)$, if A and B are 3×3 matrices, with $\det(A) = 3$ and $\det(B) = 5$.

Solution: $\det(-2AB^{-1}A^T) = (-2)^3 \det(A) \det(B^{-1}) \det(A^T) = (-8)(3)(5^{-1})(3) = -\frac{72}{5}$

(c) [2 marks] the characteristic polynomial of $\begin{bmatrix} 4 & 3 \\ 6 & 5 \end{bmatrix}$.

Solution: $\det \begin{bmatrix} x-4 & -3 \\ -6 & x-5 \end{bmatrix} = (x-4)(x-5) - 18 = x^2 - 9x + 2$.

(d) [2 marks] $\det \begin{bmatrix} 4 & 3 & 10 & -3 \\ 13 & 5 & e & -5 \\ -9 & 4 & \pi & -4 \\ 14 & -1 & \sqrt{2} & 1 \end{bmatrix}$

Solution: add the second column to the fourth column:

$$\det \begin{bmatrix} 4 & 3 & 10 & -3 \\ 13 & 5 & e & -5 \\ -9 & 4 & \pi & -4 \\ 14 & -1 & \sqrt{2} & 1 \end{bmatrix} = \det \begin{bmatrix} 4 & 3 & 10 & 0 \\ 13 & 5 & e & 0 \\ -9 & 4 & \pi & 0 \\ 14 & -1 & \sqrt{2} & 0 \end{bmatrix} = 0.$$

2. Let $\vec{x} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}$, $\vec{u}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}$, $\vec{u}_2 = \begin{bmatrix} 2 \\ 1 \\ 2 \\ 0 \end{bmatrix}$, $\vec{u}_3 = \begin{bmatrix} 0 \\ -2 \\ 1 \\ 1 \end{bmatrix}$, $\vec{u}_4 = \begin{bmatrix} -2 \\ 2 \\ 1 \\ 3 \end{bmatrix}$. Show $\{\vec{u}_1, \vec{u}_2, \vec{u}_3, \vec{u}_4\}$ is an orthogonal set, and write \vec{x} as a linear combination of $\vec{u}_1, \vec{u}_2, \vec{u}_3, \vec{u}_4$.

Solution: [avg: 9.1/10] show that each pair of vectors $\vec{u}_i, \vec{u}_j, i \neq j$ is orthogonal. There are six dot products you must calculate:

1. $\vec{u}_1 \cdot \vec{u}_2 = 2 + 0 - 2 + 0 = 0$
2. $\vec{u}_1 \cdot \vec{u}_3 = 0 - 0 - 1 + 1 = 0$
3. $\vec{u}_1 \cdot \vec{u}_4 = -2 + 0 - 1 + 3 = 0$
4. $\vec{u}_2 \cdot \vec{u}_3 = 0 - 2 + 2 + 0 = 0$
5. $\vec{u}_2 \cdot \vec{u}_4 = -4 + 2 + 2 + 0 = 0$
6. $\vec{u}_3 \cdot \vec{u}_4 = 0 - 4 + 1 + 3 = 0$

Now let $\vec{x} = c_1\vec{u}_1 + c_2\vec{u}_2 + c_3\vec{u}_3 + c_4\vec{u}_4$. Using the results from Chapter 7 we can solve for c_i directly:

$$c_i = \frac{\vec{x} \cdot \vec{u}_i}{\|\vec{u}_i\|^2}.$$

Thus

$$c_1 = \frac{1 - 0 - 1 - 1}{3} = -\frac{1}{3}; c_2 = \frac{2 - 1 + 2 - 0}{9} = \frac{1}{3}; c_3 = \frac{0 + 2 + 1 - 1}{6} = \frac{1}{3}; c_4 = \frac{-2 - 2 + 1 - 3}{18} = -\frac{1}{3}.$$

OR you can solve a system of linear equations for c_i by reducing an augmented matrix:

$$\left[\begin{array}{cccc|c} 1 & 2 & 0 & -2 & 1 \\ 0 & 1 & -2 & 2 & -1 \\ -1 & 2 & 1 & 1 & 1 \\ 1 & 0 & 1 & 3 & -1 \end{array} \right] \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & -2 & 1 \\ 0 & 1 & -2 & 2 & -1 \\ 0 & 4 & 1 & -1 & 2 \\ 0 & -2 & 1 & 5 & -2 \end{array} \right] \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & -2 & 1 \\ 0 & 1 & -2 & 2 & -1 \\ 0 & 0 & 9 & -9 & 6 \\ 0 & 0 & -3 & 9 & -4 \end{array} \right] \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & -2 & 1 \\ 0 & 1 & -2 & 2 & -1 \\ 0 & 0 & 9 & -9 & 6 \\ 0 & 0 & 0 & 18 & -6 \end{array} \right];$$

and as before, $c_4 = -\frac{1}{3}$, $c_3 = \frac{1}{3}$, $c_2 = \frac{1}{3}$, $c_1 = -\frac{1}{3}$. Either way

$$\vec{x} = -\frac{1}{3}\vec{u}_1 + \frac{1}{3}\vec{u}_2 + \frac{1}{3}\vec{u}_3 - \frac{1}{3}\vec{u}_4.$$

3. [avg: 6.9/10]

Let $A = \frac{1}{17} \begin{bmatrix} 8 & 15 \\ 15 & -8 \end{bmatrix}$. Find the eigenvalues of A and a basis for each eigenspace of A . Plot the eigenspaces of A in \mathbb{R}^2 , and clearly indicate which eigenspace corresponds to which eigenvalue. Interpret your result geometrically.

Solution: A is a reflection matrix, so the eigenvalues must be $\lambda = \pm 1$. OR: calculate them directly.

$$\det \begin{bmatrix} \lambda - 8/17 & -15/17 \\ -15/17 & \lambda + 8/17 \end{bmatrix} = \lambda^2 - \frac{64}{289} - \frac{225}{289} = \lambda^2 - 1 = (\lambda - 1)(\lambda + 1).$$

Eigenspaces: for $\lambda = 1$,

$$\text{null} \begin{bmatrix} 1 - 8/17 & -15/17 \\ -15/17 & 1 + 8/17 \end{bmatrix} = \text{null} \begin{bmatrix} 9 & -15 \\ -15 & 25 \end{bmatrix} = \text{null} \begin{bmatrix} 3 & -5 \\ 0 & 0 \end{bmatrix} = \text{span} \left\{ \begin{bmatrix} 5 \\ 3 \end{bmatrix} \right\}.$$

For $\lambda = -1$,

$$\text{null} \begin{bmatrix} -1 - 8/17 & -15/17 \\ -15/17 & -1 + 8/17 \end{bmatrix} = \text{null} \begin{bmatrix} -25 & -15 \\ -15 & -9 \end{bmatrix} = \text{null} \begin{bmatrix} 5 & 3 \\ 0 & 0 \end{bmatrix} = \text{span} \left\{ \begin{bmatrix} -3 \\ 5 \end{bmatrix} \right\}.$$

Thus

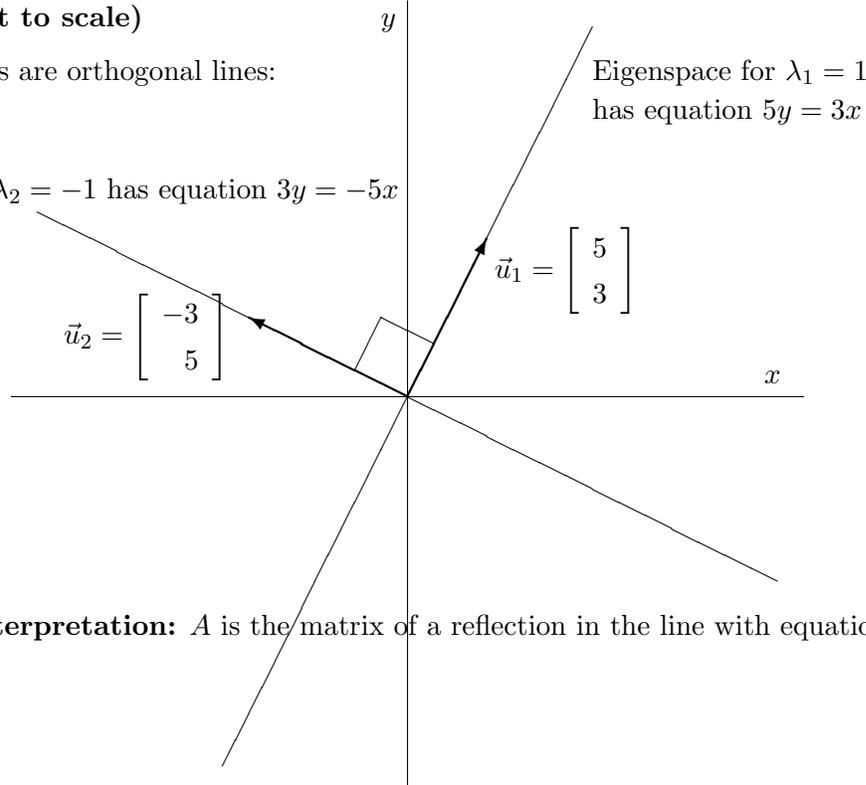
$$E_1(A) = \text{span} \left\{ \begin{bmatrix} 5 \\ 3 \end{bmatrix} \right\} \text{ and } E_{-1} = \text{span} \left\{ \begin{bmatrix} -3 \\ 5 \end{bmatrix} \right\},$$

which are lines with equations $y = \frac{3}{5}x$ and $y = -\frac{5}{3}x$, respectively.

Diagram: (not to scale)

The Eigenspaces are orthogonal lines:

Eigenspace for $\lambda_2 = -1$ has equation $3y = -5x$



Geometrical Interpretation: A is the matrix of a reflection in the line with equation $5y = 3x$.

4. [avg: 2.7/10] Let S be the set of vectors \vec{x} in \mathbb{R}^4 such that

$$\det \begin{bmatrix} 1 & 0 & 1 & x_1 \\ 2 & 1 & 0 & x_2 \\ 3 & 1 & 1 & x_3 \\ 5 & 2 & -1 & x_4 \end{bmatrix} = 0.$$

(a) [5 marks] Explain why S is a subspace of \mathbb{R}^4 .

Solution 1: take the cofactor expansion along the 4th column of the matrix to get

$$x_1 C_{14} + x_2 C_{24} + x_3 C_{34} + x_4 C_{44} = 0 \Leftrightarrow x_1 + x_2 - x_3 = 0.$$

Thus S is the set of the solutions to a single homogeneous equation, so S is a subspace of \mathbb{R}^4 .

Equivalently, $S = \text{null} \begin{bmatrix} C_{14} & C_{24} & C_{34} & C_{44} \end{bmatrix} = \text{null} \begin{bmatrix} -2 & -2 & 2 & 0 \end{bmatrix}$.

Solution 2: since the first three columns, $\vec{c}_1, \vec{c}_2, \vec{c}_3$, of the matrix are linearly independent, $\vec{x} \in S$ if and only if the columns of the matrix are linearly dependent if and only if $\vec{x} \in \text{span}\{\vec{c}_1, \vec{c}_2, \vec{c}_3\}$. Thus $S = \text{span}\{\vec{c}_1, \vec{c}_2, \vec{c}_3\}$, so S is a subspace of \mathbb{R}^4 .

Solution 3: use the subspace test.

- $\vec{0} \in S$ since any matrix with an all-zero column has determinant equal to 0.
- if $\vec{x} \in S$ then $\det[\vec{c}_1 \ \vec{c}_2 \ \vec{c}_3 \ k\vec{x}] = k \det[\vec{c}_1 \ \vec{c}_2 \ \vec{c}_3 \ \vec{x}] = k \cdot 0 = 0$, so $k\vec{x} \in S$.
- suppose \vec{x} and \vec{y} are both in S , then as in Solution 1,

$$\begin{aligned} \det[\vec{c}_1 \ \vec{c}_2 \ \vec{c}_3 \ \vec{x} + \vec{y}] &= (x_1 + y_1)C_{14} + (x_2 + y_2)C_{24} + (x_3 + y_3)C_{34} + (x_4 + y_4)C_{44} \\ &= x_1 C_{14} + x_2 C_{24} + x_3 C_{34} + x_4 C_{44} + y_1 C_{14} + y_2 C_{24} + y_3 C_{34} + y_4 C_{44} \\ &= \det[\vec{c}_1 \ \vec{c}_2 \ \vec{c}_3 \ \vec{x}] + \det[\vec{c}_1 \ \vec{c}_2 \ \vec{c}_3 \ \vec{y}] \\ &= 0 + 0 = 0, \end{aligned}$$

so $\vec{x} + \vec{y} \in S$.

(b) [5 marks] Find a basis for S and its dimension.

Solution: from the second solution to part (a), a basis of S is

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 5 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix} \right\}$$

and $\dim(S) = 3$.

5. [avg: 7.6/10] Solve the system of differential equations

$$\begin{cases} \frac{dx}{dt} = -x + 4y \\ \frac{dy}{dt} = 8x - 5y \end{cases}$$

for x and y as functions of t , given that $(x, y) = (6, 12)$ when $t = 0$.

Solution: let $A = \begin{bmatrix} -1 & 4 \\ 8 & -5 \end{bmatrix}$; find the eigenvalues and eigenvectors of A .

Eigenvalues of A : $\det(\lambda I - A) = \det \begin{bmatrix} \lambda + 1 & -4 \\ -8 & \lambda + 5 \end{bmatrix} = \lambda^2 + 6\lambda - 27 = (\lambda + 9)(\lambda - 3)$. So the eigenvalues of A are $\lambda_1 = 3$ and $\lambda_2 = -9$.

Eigenvectors of A :

$$\text{null} \begin{bmatrix} 3 + 1 & -4 \\ -8 & 3 + 5 \end{bmatrix} = \text{null} \begin{bmatrix} 4 & -4 \\ -8 & 8 \end{bmatrix} = \text{null} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}; \text{ take } \vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{null} \begin{bmatrix} -9 + 1 & -4 \\ -8 & -9 + 5 \end{bmatrix} = \text{null} \begin{bmatrix} -8 & -4 \\ -8 & -4 \end{bmatrix} = \text{null} \begin{bmatrix} 2 & 1 \\ 0 & 0 \end{bmatrix} = \text{span} \left\{ \begin{bmatrix} -1 \\ 2 \end{bmatrix} \right\}; \text{ take } \vec{v}_2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

The general solution to the system of differential equations is

$$\begin{bmatrix} x \\ y \end{bmatrix} = c_1 \vec{v}_1 e^{4t} + c_2 \vec{v}_2 e^{5t} = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{3t} + c_2 \begin{bmatrix} -1 \\ 2 \end{bmatrix} e^{-9t}$$

To find c_1, c_2 , let $t = 0$ and solve the system of linear equations

$$\begin{aligned} \begin{bmatrix} 6 \\ 12 \end{bmatrix} &= c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} \Leftrightarrow \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 6 \\ 12 \end{bmatrix} \\ \Rightarrow \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} &= \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 6 \\ 12 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 6 \\ 12 \end{bmatrix} = \begin{bmatrix} 8 \\ 2 \end{bmatrix}. \end{aligned}$$

Thus the solutions to the system of differential equations is

$$x = 8e^{3t} - 2e^{-9t} \text{ and } y = 8e^{3t} + 4e^{-9t}.$$

6. [avg: 6.5/10]

Find an orthogonal matrix P and a diagonal matrix D such that $D = P^T A P$, if $A = \begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & -1 \\ -1 & -1 & 0 \end{bmatrix}$.

Step 1: find the eigenvalues of A .

$$\begin{aligned} \det(\lambda I - A) &= \det \begin{bmatrix} \lambda & -1 & 1 \\ -1 & \lambda & 1 \\ 1 & 1 & \lambda \end{bmatrix} = \det \begin{bmatrix} \lambda & -1 & 1 \\ -1 - \lambda & \lambda + 1 & 0 \\ 0 & \lambda + 1 & \lambda + 1 \end{bmatrix} \\ &= (\lambda + 1)^2 \det \begin{bmatrix} \lambda & -1 & 1 \\ -1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} = (\lambda + 1)^2 (\lambda - 2) \end{aligned}$$

Thus the eigenvalues of A are $\lambda_1 = -1$, repeated, and $\lambda_2 = 2$.

Step 2: find an *orthogonal* basis of eigenvectors for each eigenspace.

$$\begin{aligned} \text{For } \lambda_1 = -1 : \text{ null} \begin{bmatrix} -1 & -1 & 1 \\ -1 & -1 & 1 \\ 1 & 1 & -1 \end{bmatrix} &= \text{null} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} \right\}; \\ \text{for } \lambda_2 = 2 : \text{ null} \begin{bmatrix} 2 & -1 & 1 \\ -1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix} &= \text{null} \begin{bmatrix} 0 & 3 & 3 \\ -1 & 2 & 1 \\ 0 & 3 & 3 \end{bmatrix} = \text{null} \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \right\}. \end{aligned}$$

Step 3: for the columns of P , take the unit, orthogonal eigenvectors and for the diagonal entries of D take the corresponding eigenvalues:

$$P = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 0 & 2/\sqrt{6} & 1/\sqrt{3} \\ 1/\sqrt{2} & 1/\sqrt{6} & -1/\sqrt{3} \end{bmatrix} \text{ and } D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix},$$

7. [avg: 4.5/10] Let $S = \text{span} \left\{ [1 \ 0 \ 1 \ 0]^T, [0 \ 1 \ 2 \ 0]^T, [1 \ 1 \ 1 \ -2]^T \right\}$.

(a) [3 marks] Find a basis for S^\perp , the orthogonal complement of S .

Solution:

$$S^\perp = \text{null} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 \\ 1 & 1 & 1 & -2 \end{bmatrix} = \text{null} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & -2 & -2 \end{bmatrix} = \text{null} \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 1 \end{bmatrix} = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ -1 \\ 1 \end{bmatrix} \right\}.$$

Take $\vec{w} = [1 \ 2 \ -1 \ 1]^T$ as the basis for S^\perp .

(b) [4 marks] Find the standard matrix of the linear transformation $\text{perp}_S : \mathbb{R}^4 \rightarrow \mathbb{R}^4$.

Solution 1: $\text{perp}_S(\vec{x}) = \text{proj}_{S^\perp}(\vec{x}) = \frac{\vec{x} \cdot \vec{w}}{\|\vec{w}\|^2} \vec{w} =$

$$\frac{(x_1 + 2x_2 - x_3 + x_4)}{7} \begin{bmatrix} 1 \\ 2 \\ -1 \\ 1 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} x_1 + 2x_2 - x_3 + x_4 \\ 2x_1 + 4x_2 - 2x_3 + 2x_4 \\ -x_1 - 2x_2 + x_3 - x_4 \\ x_1 + 2x_2 - x_3 + x_4 \end{bmatrix},$$

from which you can read off the matrix: $[\text{perp}_S] = \frac{1}{7} \begin{bmatrix} 1 & 2 & -1 & 1 \\ 2 & 4 & -2 & 2 \\ -1 & -2 & 1 & -1 \\ 1 & 2 & -1 & 1 \end{bmatrix}$.

Solution 2: use definition of standard matrix.

$$[\text{perp}_S] = [\text{perp}_S(\vec{e}_1) \ \text{perp}_S(\vec{e}_2) \ \text{perp}_S(\vec{e}_3) \ \text{perp}_S(\vec{e}_4)] = [\text{proj}_{\vec{w}}(\vec{e}_1) \ \text{proj}_{\vec{w}}(\vec{e}_2) \ \text{proj}_{\vec{w}}(\vec{e}_3) \ \text{proj}_{\vec{w}}(\vec{e}_4)]$$

(c) [3 marks] What is the standard matrix of $\text{proj}_S : \mathbb{R}^4 \rightarrow \mathbb{R}^4$? (You can make use of part (b).)

Solution: use the fact that $[\text{proj}_S] = I - [\text{perp}_S]$. Thus

$$[\text{proj}_S] = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} - \frac{1}{7} \begin{bmatrix} 1 & 2 & -1 & 1 \\ 2 & 4 & -2 & 2 \\ -1 & -2 & 1 & -1 \\ 1 & 2 & -1 & 1 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 6 & -2 & 1 & -1 \\ -2 & 3 & 2 & -2 \\ 1 & 2 & 6 & 1 \\ -1 & -2 & -1 & 6 \end{bmatrix}.$$

8. [avg: 2.6/10] Prove the following:

(a) [5 marks] if A is an invertible $n \times n$ matrix with eigenvalue λ , then λ^{-1} is an eigenvalue of A^{-1} .

Proof: since λ is an eigenvalue of A there is a non-zero vector \vec{v} such that $A\vec{v} = \lambda\vec{v}$; and since the matrix A is invertible, $\lambda \neq 0$. Then

$$\begin{aligned} A\vec{v} = \lambda\vec{v} &\Rightarrow \vec{v} = A^{-1}(\lambda\vec{v}) = \lambda A^{-1}\vec{v} \\ &\Rightarrow \lambda^{-1}\vec{v} = A^{-1}\vec{v}. \end{aligned}$$

which means λ^{-1} is an eigenvalue of A^{-1} (with the same eigenvector \vec{v} ..)

(b) [5 marks] if A is a 7×5 matrix with rank 4, then the matrix $A^T A$ is not invertible.

Proof: by the Rank-Nullity Theorem, the nullity of A is $5 - 4 = 1$. Thus $\dim(\text{null}(A)) = 1$, and there is a non-zero vector \vec{x} such that $A\vec{x} = \vec{0}$. Then

$$\begin{aligned} A\vec{x} = \vec{0} &\Rightarrow A^T(A\vec{x}) = A^T\vec{0} \\ &\Rightarrow (A^T A)\vec{x} = \vec{0}, \end{aligned}$$

Therefore the null space of $A^T A$ is also non-trivial, and so the matrix $A^T A$ is not invertible.

9. [avg: 6.6/10] Use the method of least squares to find the best fitting quadratic function

$f(x) = a + bx + cx^2$ for the five data points $(x, y) = (-2, 3), (-1, 2), (0, 0), (1, 2)$ and $(2, 8)$.

Solution: let $M = \begin{bmatrix} 1 & -2 & 4 \\ 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix}$; $\vec{y} = \begin{bmatrix} 3 \\ 2 \\ 0 \\ 2 \\ 8 \end{bmatrix}$. The normal equations are $M^T M \begin{bmatrix} a \\ b \\ c \end{bmatrix} = M^T \vec{y}$.

Solve:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ -2 & -1 & 0 & 1 & 2 \\ 4 & 1 & 0 & 1 & 4 \end{bmatrix} \begin{bmatrix} 1 & -2 & 4 \\ 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ -2 & -1 & 0 & 1 & 2 \\ 4 & 1 & 0 & 1 & 4 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \\ 0 \\ 2 \\ 8 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 5 & 0 & 10 \\ 0 & 10 & 0 \\ 10 & 0 & 34 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 15 \\ 10 \\ 48 \end{bmatrix}$$

This system is easy to solve, since $b = 1$, by inspection. Then $5a + 10c = 15$ and $5a + 17c = 24$, from which you can deduce

$$7c = 9 \Leftrightarrow c = \frac{9}{7} \text{ and } a = 3 - 2c = 5 - \frac{18}{7} = \frac{3}{7}.$$

Thus the quadratic function that best fits the data has equation $y = \frac{3}{7} + x + \frac{9}{7}x^2$.

10. [avg: 2.5/10] Find all linear transformations $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ such that

the range of L is $\text{span} \left\{ \begin{bmatrix} -1 \\ 5 \\ 2 \end{bmatrix} \right\}$ and the null space (or kernel) of L is $\text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$.

Solution 1: let A be the standard matrix of L . Then in terms of A ,

$$(1), \text{col}(A) = \text{span} \left\{ \begin{bmatrix} -1 \\ 5 \\ 2 \end{bmatrix} \right\} \text{ and } (2), \text{null}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}.$$

By (1),

$$A = \begin{bmatrix} -a & -b & -c \\ 5a & 5b & 5c \\ 2a & 2b & 2c \end{bmatrix},$$

for some scalars a, b, c . By (2),

$$A \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \text{ and } A \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix},$$

which means

$$a + 2b + 3c = 0 \text{ and } a + b + c = 0.$$

Solving this system gives $a = c$ and $b = -2c$, for parameter c . Thus

$$A = \begin{bmatrix} -c & 2c & -c \\ 5c & -10c & 5c \\ 2c & -4c & 2c \end{bmatrix},$$

for $c \neq 0$. And

$$L(\vec{x}) = A\vec{x} = \begin{bmatrix} -c & 2c & -c \\ 5c & -10c & 5c \\ 2c & -4c & 2c \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = c \begin{bmatrix} -x_1 + 2x_2 - x_3 \\ 5x_1 - 10x_2 + 5x_3 \\ 2x_1 - 4x_2 + 2x_3 \end{bmatrix}$$

See the next page for an alternate solution.

This page is for rough work or for extra space to finish a previous problem. It will not be marked unless you have indicated in a previous question to look at this page.

Solution 2: extend the basis of the null space of L to a basis for \mathbb{R}^3 by including (say) the vector \vec{e}_3 . Let A be the standard matrix of L . Then, for some non-zero scalar a ,

$$A \begin{bmatrix} 1 & 1 & 0 \\ 2 & 1 & 0 \\ 3 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & -a \\ 0 & 0 & 5a \\ 0 & 0 & 2a \end{bmatrix} \Leftrightarrow A = \begin{bmatrix} 0 & 0 & -a \\ 0 & 0 & 5a \\ 0 & 0 & 2a \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 2 & 1 & 0 \\ 3 & 1 & 1 \end{bmatrix}^{-1}.$$

Use the Gaussian algorithm to find the inverse:

$$\left[\begin{array}{ccc|ccc} 1 & 1 & 0 & 1 & 0 & 0 \\ 2 & 1 & 0 & 0 & 1 & 0 \\ 3 & 1 & 1 & 0 & 0 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & -2 & 1 & 0 \\ 0 & -2 & 1 & -3 & 0 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -1 & 1 & 0 \\ 0 & 1 & 0 & 2 & -1 & 0 \\ 0 & 0 & 1 & 1 & -2 & 1 \end{array} \right];$$

thus

$$A = \begin{bmatrix} 0 & 0 & -a \\ 0 & 0 & 5a \\ 0 & 0 & 2a \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 \\ 2 & -1 & 0 \\ 1 & -2 & 1 \end{bmatrix} = \begin{bmatrix} -a & 2a & -a \\ 5a & -10a & 5a \\ 2a & -4a & 2a \end{bmatrix}.$$

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