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MIXED VOLUME AND AN EXTENSION OF INTERSECTION THEORY OF DIVISORS

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ABSTRACT. Let $K_{rat}(X)$ be the collection of all non-zero finite dimensional subspaces of rational functions on an n-dimensional irreducible variety X. For any *n*-tuple $L_1, \ldots, L_n \in \mathbf{K}_{rat}(X)$, we define an intersection index $[L_1, \ldots, L_n]$ as the number of solutions in X of a system of equations $f_1 = \cdots = f_n = 0$ where each f_i is a generic function from the space L_i . In counting the solutions, we neglect the solutions x at which all the functions in some space L_i vanish as well as the solutions at which at least one function from some subspace L_i has a pole. The collection $\mathbf{K}_{rat}(X)$ is a commutative semigroup with respect to a natural multiplication. The intersection index $[L_1, \ldots, L_n]$ can be extended to the Grothendieck group of $K_{rat}(X)$. This gives an extension of the intersection theory of divisors. The extended theory is applicable even to non-complete varieties. We show that this intersection index enjoys all the main properties of the mixed volume of convex bodies. Our paper is inspired by the Bernstein-Kushnirenko theorem from the Newton polytope theory.

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1. INTRODUCTION

The present paper is the first in a series of three papers in which we extend the well-known Bernstein–Kushnirenko theorem to a far more general setting. It is a revised and expanded version of the first half of the preprint [KKh1]. In this introduction we discuss the content of the paper as well as a brief discussion of the two coming papers.

The Bernstein–Kushnirenko theorem computes the number of solutions in $(\mathbb{C}^*)^n$ of a system of equations $P_1 = \cdots = P_n = 0$ where each P_i is a generic function from a fixed finite dimensional vector space of functions spanned by monomials.

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The answer is given in terms of the mixed volume of the Newton polytopes of the equations in the system (Section 2.2).

In this paper, instead of $(\mathbb{C}^*)^n$ we take any irreducible *n*-dimensional complex algebraic variety X,¹ and instead of a space of functions spanned by monomials, we consider any non-zero finite dimensional vector space of rational functions on X. For any *n*-tuple of such finite dimensional spaces L_1, \ldots, L_n of rational functions on X we define an *intersection index* $[L_1, \ldots, L_n]$ as the number of solutions in Xof a system of equations $f_1 = \cdots = f_n = 0$ where each f_i is a generic function from the space L_i . In counting the solutions, we neglect the solutions x at which all the functions in some space L_i vanish, as well as the solutions at which at least one function from some space L_i has a pole. As this intersection index only depends on the birational type of X, we will also refer to it as the *birationally invariant intersection index*.

Let $\mathbf{K}_{rat}(X)$ denote the collection of all the non-zero finite dimensional subspaces of rational functions on X. The set $\mathbf{K}_{rat}(X)$ has a natural multiplication: product L_1L_2 of two subspaces $L_1, L_2 \in \mathbf{K}_{rat}(X)$ is the subspace spanned by all the products fg, where $f \in L_1, g \in L_2$. With this multiplication, $\mathbf{K}_{rat}(X)$ is a commutative semigroup. As with any other commutative semigroup, there corresponds a Grothendieck group to the semigroup $\mathbf{K}_{rat}(X)$.² We prove that the intersection index $[L_1, \ldots, L_n]$ is linear in each argument with respect to the multiplication in $\mathbf{K}_{rat}(X)$, and hence can be extended to the Grothendieck group of $\mathbf{K}_{rat}(X)$.

With each space $L \in \mathbf{K}_{rat}(X)$, one associates a rational Kodaira map $\Phi_L: X \to \mathbb{P}(L^*)$, the projectivization of the dual space L^* . Let $x \in X$ be such that all the $f \in L$ are defined at x and not all of them vanish at x. To such x there corresponds a non-zero functional in L^* which evaluates $f \in L$ at x. The Kodaira map sends x to the image of this functional in $\mathbb{P}(L^*)$. It is a rational map, i.e., defined on a Zariski open subset in X. The collection of subspaces in $\mathbf{K}_{rat}(X)$ for which the Kodaira map extends to a regular map everywhere on X, is a subsemigroup of $\mathbf{K}_{rat}(X)$ which we denote by $\mathbf{K}_{Cart}(X)$.

We show that if X is an irreducible normal projective variety then the Grothendieck group of $\mathbf{K}_{Cart}(X)$ is naturally isomorphic to the group of Cartier divisors on X (Section 6). Under this isomorphism the intersection index of subspaces corresponds to the intersection index of Cartier divisors. Hence the intersection index of subspaces introduced in the present paper can be considered as an extension of the intersection theory of Cartier divisors to general varieties. For a (not necessarily complete) variety X, the Grothendieck group of the semigroup $\mathbf{K}_{rat}(X)$, equipped with the intersection index, can be identified with the direct limit of groups of

¹Throughout the paper, all the varieties are assumed to be over complex numbers, and a variety is not automatically assumed to be irreducible.

²For a commutative semigroup K, the Grothendieck group G(K) is defined as follows: for $x, y \in K$ let us say $x \sim y$ if there is $z \in K$ with xz = yz. Then G(K) consists of all the formal quotients $x/y, x, y \in K$, where we identify x/y and z/w if xw = zy. One has a natural homomorphism $\phi: K \to G(K)$ with the following universal property: for any abelian group G' and a homomorphism $\phi: K \to G'$, there exists a unique homomorphism $\psi: G(K) \to G'$ such that $\phi' = \psi \circ \phi$ (Section 6).

Cartier divisors on all the complete birational models of X. (Such limit is studied from an algebraic point of view in [BFJ].)

The semigroup $\mathbf{K}_{rat}(X)$, equipped with the intersection index, has an analogue in convex geometry. This analogy is more evident in the toric case considered by Bernstein and Kushnirenko. They deal with $X = (\mathbb{C}^*)^n$ and the subsemigroup $\mathbf{K}_{mon} \subset \mathbf{K}_{rat}(X)$ consisting of the finite dimensional subspaces spanned by monomials. Each monomial $z^k = z_1^{k_1} \dots z_n^{k_n}$ on $(\mathbb{C}^*)^n$ corresponds to a point $k = (k_1, \dots, k_n)$ in the lattice \mathbb{Z}^n (where z_1, \dots, z_n are the coordinates on $(\mathbb{C}^*)^n$). A finite subset $A \subset \mathbb{Z}^n$ gives a subspace L_A in \mathbf{K}_{mon} , namely, L_A is the subspace spanned by the monomials corresponding to the points in A. It is easy to see that $L_{A+B} = L_A L_B$ and thus the semigroup \mathbf{K}_{mon} is isomorphic to the semigroup of finite subsets of \mathbb{Z}^n with respect to the addition of subsets.

Let $\Delta_1, \ldots, \Delta_n$ be the convex hulls of finite subsets $A_1, \ldots, A_n \subset \mathbb{Z}^n$ respectively. According to the Bernstein–Kushnirenko theorem, the intersection index $[L_{A_1}, \ldots, L_{A_n}]$ is equal to n! times the mixed volume of the convex polytopes $\Delta_1, \ldots, \Delta_n$ (when all the polytopes are the same this was proved by Kushnirenko [Kush], and the general case is due to Bernstein [Ber]). Thus the intersection index in the semigroup \mathbf{K}_{mon} has all the properties of the mixed volume of convex bodies. In the present paper, we prove that in general for any irreducible variety X, the intersection index in the semigroup $\mathbf{K}_{\text{rat}}(X)$ also enjoys all the main properties of the mixed volume. These are listed in Section 2.1.

The semigroup of finite subsets in \mathbb{Z}^n does not have the cancellation property: the equality A + C = B + C does not imply A = B. But the semigroup of convex bodies in \mathbb{R}^n does have the cancellation property. In fact, the Grothendieck group of the semigroup of finite subsets in \mathbb{Z}^n is isomorphic to the group of *virtual* integral polytopes in \mathbb{R}^n , i.e., the formal differences of integral convex polytopes (see [Kh2]). The isomorphism is induced by the map which sends a finite subset $A \subset \mathbb{Z}^n$ to its convex hull $\Delta(A)$. For a given subset $A \subset \mathbb{Z}^n$, among the sets $B \subset \mathbb{Z}^n$ with $\Delta(A) =$ $\Delta(B)$, there is a biggest set $\overline{A} = \Delta(A) \cap \mathbb{Z}^n$. The Bernstein–Kushnirenko theorem implies that the space $L_{\overline{A}}$ has the same intersection indices as the subspace L_A .

In the semigroup $\mathbf{K}_{rat}(X)$ of an irreducible variety X, there is a similar operation to taking convex hull. Let us say that spaces $L_1, L_2 \in \mathbf{K}_{rat}(X)$ are equivalent if there is $M \in \mathbf{K}_{rat}(X)$ with $L_1M = L_2M$. One can show that among all the subspaces equivalent to a given subspace L, there is a biggest subspace $\overline{L} \in \mathbf{K}_{rat}(X)$. This subspace \overline{L} is the *integral closure* or *completion* of L: it consists of all the rational functions which are integral over L (Section 6.1). The subspace \overline{L} in $\mathbf{K}_{rat}(X)$ has the same intersection indices as L (Section 5).

To show the connection with the classical intersection index in topology and algebraic geometry, in Section 7 we give alternative proofs of the main properties of the intersection index (of subspaces of rational functions) using the usual topological and algebro-geometric techniques. In particular, we prove an algebraic analogue of the Alexandrov–Fenchel inequality from convex geometry using Hodge theory.

The algebraic analogue of Alexandrov–Fenchel inequality for the intersection index of Cartier divisors has been proved in [Kh1] and [Tei]. Our proof of the analogous inequality for the intersection index in $K_{rat}(X)$ is close to the proofs in the above papers.

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The authors have found surprisingly simple arguments which simultaneously prove the Alexandrov–Fenchel inequality in convex geometry as well as its algebraic analogue. These arguments are discussed in detail in a second paper [KKh2] (preliminary version appeared in [KKh1]). The main construction there, associates to any subspace $L \in \mathbf{K}_{rat}(X)$ a convex body $\Delta(L) \subset \mathbb{R}^n$. The body $\Delta(L)$ is a far-reaching generalization of the Newton polytope (of a Laurent polynomial). The construction of the body $\Delta(L)$ depends on a choice of a \mathbb{Z}^n -valued valuation on the field of rational functions on the variety X. We show that n! times the volume of $\Delta(L)$ is equal to the self-intersection index $[L, \ldots, L]$ (see [KKh2, Part IV]). The proof is based on the description of the asymptotic behavior of semigroups in \mathbb{Z}^{n+1} . This result is a direct generalization of the Kushnirenko theorem. Unfortunately, in general the identity $\Delta(L_1) + \Delta(L_2) = \Delta(L_1L_2)$ does not hold, and hence we do not get a generalization of the Bernstein theorem. Instead of equality, we have the inclusion $\Delta(L_1) + \Delta(L_2) \subset \Delta(L_1L_2)$. This inclusion enables us to give a simple proof of the Alexandrov–Fenchel inequality and its algebraic analogue.

In a third paper [KKh3] we address the case when the variety X is equipped with an action of a reductive algebraic group G. We generalize the Bernstein theorem to certain spherical G-varieties. The generalization of the Kushnirenko theorem to projective spherical varieties is due to M. Brion [Bri] (see also [Kaz] and [Kir]). But the Bernstein theorem can be extended only to certain classes of spherical varieties.

After the submission of [KKh1] to arXiv, we learned that we were not the only ones to have been working in this direction. Firstly, Okounkov was the first to define (in passing) a generalization of the notion of Newton polytope [Ok1], [Ok2]. Although his case of interest was when X has a reductive group action. Secondly, Lazarsfeld and Mustata, based on Okounkov's previous works, and independently of our preprint, came up with closely related constructions and results [LM]. Recently, following [LM], similar results/constructions have been obtained for line bundles on arithmetic surfaces [Yuan].

And a few words about location of the material: the main properties of mixed volume are recalled in Section 2.1. In Section 2.2 the Bernstein–Kushnirenko theorem is discussed and in Section 3 we give a straightforward generalization of this theorem to rational functions on $(\mathbb{C}^*)^n$. The intersection index for finite dimensional subspaces of regular functions without common zeros and on a smooth variety is defined in Section 4 and its main properties are established. Some of the properties, e.g., multi-linearity and invariance under the addition of integral elements, are deduced from the special case when X is a curve. The Alexandrov–Fenchel type inequality is deduced from the special case when X is a surface. In Section 5 we show that all the results in Section 4 for subspaces of regular functions easily generalize to the finite dimensional subspaces of rational functions (possibly with common zeros and poles) on a (possibly non-smooth) variety X. In Section 6.2 we show that for a projective variety X, the Grothendieck group of the subsemigroup $K_{Cart}(X)$ is isomorphic to the group of Cartier divisors on X preserving the intersection index. Finally in Section 7 we give proofs of the main properties of the intersection index using usual techniques from topology and algebraic geometry.

2. MOTIVATION AND PRELIMINARIES

2.1. Mixed volume of convex bodies and its properties. On the space of convex bodies³ in \mathbb{R}^n one has the following two operations:

1. (Minkowski sum of convex bodies): For any two subsets $A, B \subset \mathbb{R}^n$, let A+B denote the set consisting of all the points $a+b, a \in A, b \in B$. With this summation, the collection of subsets of \mathbb{R}^n becomes a commutative semigroup. In general, this semigroup does not have the cancellation property: if for subsets A, B, C we have A + C = B + C, it does not necessarily imply that A = B. The subset $\{0\}$, is the identity element for the summation of subsets, i.e., for any $A \subset \mathbb{R}^n$, we have $A+\{0\}=A$. For two convex bodies Δ_1, Δ_2 in \mathbb{R}^n , the set $\Delta_1+\Delta_2$ is a convex body, called the *Minkowski sum of* Δ_1 and Δ_2 . With this summation, the collection of convex bodies becomes a commutative semigroup with the cancellation property. As for any commutative semigroup with the cancellation property, and $\Delta_3 - \Delta_4$ are considered equal if $\Delta_1 + \Delta_4 = \Delta_2 + \Delta_3$. This group is called the group of *virtual convex bodies*.

2. (Multiplication of a convex body by a non-negative scalar): For a convex body Δ and $\lambda \ge 0$, the set $\{\lambda a : a \in \Delta\}$ is a convex body denoted by $\lambda\Delta$. This scalar multiplication can be extended to the virtual convex bodies and makes the group of virtual convex bodies into a real (infinite dimensional) vector space.

Remark 2.1. It is important in the above definition of scalar multiplication (for convex bodies) to assume that λ is non-negative. If we define $\lambda\Delta$ for any real λ as above, then it will not agree with the Minkowski sum in a good way. For example, if Δ contains more than one point and $\lambda > 0$ then $\lambda\Delta + (-\lambda)\Delta$ contains more than one point (i.e., is not zero).

Convex bodies form a convex cone in the vector space of virtual convex bodies.⁴ On this cone there is a volume function Vol which assigns to each convex body Δ , its volume Vol(Δ) with respect to the standard Euclidean measure in \mathbb{R}^n . The function Vol is a homogeneous polynomial of degree n on the cone of convex bodies. That is, its restriction to each finite dimensional section of the cone is a homogeneous polynomial of degree n. More precisely: let \mathbb{R}^k_+ be the positive octant in \mathbb{R}^k consisting of all $\lambda = (\lambda_1, \ldots, \lambda_k)$ with $\lambda_1 \ge 0, \ldots, \lambda_k \ge 0$. The polynomiality of Vol means that for any choice of the convex bodies $\Delta_1, \ldots, \Delta_k$, the function $P_{\Delta_1,\ldots,\Delta_k}$ defined on \mathbb{R}^k_+ by

$$P_{\Delta_1,\ldots,\Delta_k}(\lambda_1,\ldots,\lambda_k) = \operatorname{Vol}(\lambda_1\Delta_1 + \cdots + \lambda_k\Delta_k),$$

is a homogeneous polynomial of degree n.

By definition the mixed volume of $V(\Delta_1, \ldots, \Delta_n)$ of an n-tuple $(\Delta_1, \ldots, \Delta_n)$ of convex bodies in \mathbb{R}^n is the coefficient of the monomial $\lambda_1 \ldots \lambda_n$ in the polynomial $P_{\Delta_1,\ldots,\Delta_n}$ divided by n!.

³By a convex body in \mathbb{R}^n we mean a compact convex subset of \mathbb{R}^n .

 $^{{}^{4}\}mathrm{A}$ cone in a (real) vector space is a subset which is closed under the addition and multiplication by non-negative scalars.

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This definition implies that the mixed volume is the *polarization* of the volume polynomial, that is, it is the unique function on the *n*-tuples of convex bodies which satisfies the following:

- (i) (Symmetry) V is symmetric with respect to permutations of the bodies $\Delta_1, \ldots, \Delta_n$.
- (ii) (Multi-linearity) It is linear in each argument with respect to the Minkowski sum. The linearity in the first argument means that for any choice of convex bodies $\Delta'_1, \Delta''_1, \Delta_2, \ldots, \Delta_n$ and for any $\lambda_1 \ge 0, \lambda_2 \ge 0$, we have:

$$V(\lambda_1 \Delta'_1 + \lambda_2 \Delta''_1, \dots, \Delta_n) = \lambda_1 V(\Delta'_1, \dots, \Delta_n) + \lambda_2 V(\Delta''_1, \dots, \Delta_n).$$

(iii) On the diagonal V coincides with the volume, i.e., for any convex body Δ we have $V(\Delta, \ldots, \Delta) = Vol(\Delta)$.

The above three properties characterize the mixed volume: it is the unique function satisfying (i)–(iii).

By the multi-linearity, the volume and mixed volume functions can be extended to the vector space of virtual convex bodies.

There are many interesting geometric inequalities known concerning the mixed volume. The following two inequalities are easy to verify:

(1) Mixed volume is non-negative, that is, for any *n*-tuple $\Delta_1, \ldots, \Delta_n$ of convex bodies, we have

$$V(\Delta_1, \ldots, \Delta_n) \ge 0.$$

(2) Mixed volume is monotone, that is, for two *n*-tuples of convex bodies $\Delta'_1 \subset \Delta_1, \ldots, \Delta'_n \subset \Delta_n$ we have

$$V(\Delta_1, \ldots, \Delta_n) \ge V(\Delta'_1, \ldots, \Delta'_n).$$

The next inequality is far more complicated. It is known as the *Alexandrov–Fenchel* inequality.

(3) For any *n*-tuple of convex bodies $\Delta_1, \ldots, \Delta_n \subset \mathbb{R}^n$ one has:

$$V(\Delta_1, \Delta_2, \Delta_3, \dots, \Delta_n)^2 \ge V(\Delta_1, \Delta_1, \Delta_3, \dots, \Delta_n)V(\Delta_2, \Delta_2, \Delta_3, \dots, \Delta_n).$$

Below we mention some formal corollaries of the Alexandrov–Fenchel inequality. Let us introduce a notation for the repetition of convex bodies in the mixed volume. Let $2 \leq m \leq n$ be an integer and $k_1 + \cdots + k_r = m$ a partition of m with $k_i \in \mathbb{N}$. Denote by $V(k_1 * \Delta_1, \ldots, k_r * \Delta_r, \Delta_{m+1}, \ldots, \Delta_n)$ the mixed volume of $\Delta_1, \ldots, \Delta_n$, where Δ_1 is repeated k_1 times, Δ_2 is repeated k_2 times, etc. and $\Delta_{m+1}, \ldots, \Delta_n$ appear once.

(4) With the notation as above, the following inequality holds:

$$V(k_1 * \Delta_1, \ldots, k_r * \Delta_r, \Delta_{m+1}, \ldots, \Delta_n)^m \ge \prod_{1 \le j \le r} V(m * \Delta_j, \Delta_{m+1}, \ldots, \Delta_n)^{k_j}.$$

(5) (Generalized Brunn–Minkowski inequality) Fix convex bodies $\Delta_{m+1}, \ldots, \Delta_n$. Then the function F which assigns to a body Δ , the number $F(\Delta) = V^{1/m}(m * \Delta, \Delta_{m+1}, \ldots, \Delta_n)$, is concave, i.e., for any two convex bodies Δ_1, Δ_2 we have

$$F(\Delta_1) + F(\Delta_2) \leqslant F(\Delta_1 + \Delta_2).$$

The n = m case of the above Property (5) was discovered by H. Brunn at the end of the 19th century. It is called the *Brunn–Minkowski inequality*. This inequality was discovered before the Alexandrov–Fenchel inequality, and its proof is much simpler than that of the Alexandrov–Fenchel.

2.2. Mixed volume and the Bernstein–Kushnirenko theorem. The beautiful Bernstein–Kushnirenko theorem computes the number of solutions in $(\mathbb{C}^*)^n$ of a sufficiently general system of n equations $P_1 = \cdots = P_n = 0$, where the P_i are Laurent polynomials, in terms of the Newton polytopes of these polynomials. In this section we discuss this theorem.

Let us identify the lattice \mathbb{Z}^n with Laurent monomials in $(\mathbb{C}^*)^n$: to each integral point $k = (k_1, \ldots, k_n) \in \mathbb{Z}^n$, we associate the monomial $z^k = z_1^{k_1} \ldots z_n^{k_n}$. A Laurent polynomial $P = \sum c_k z^k$ is a finite linear combination of Laurent monomials with complex coefficients. The support supp(P) of a Laurent polynomial P, is the set of exponents k for which $c_k \neq 0$. We denote the convex hull of a finite subset $A \subset \mathbb{Z}^n$ by $\Delta_A \subset \mathbb{R}^n$. The Newton polytope $\Delta(P)$ of a Laurent polynomial P is the convex hull $\Delta_{\text{supp}(P)}$ of its support. To each non-empty finite subset $A \subset \mathbb{Z}^n$ one can associate a finite dimensional vector space L_A consisting of the Laurent polynomials P with supp $(P) \subset A$.

Definition 2.2. We say that a property holds for a *generic element* of a vector space L, if there is a proper algebraic set Σ such that the property holds for all the elements in $L \setminus \Sigma$.

Problem. For a given n-tuple of non-empty finite subsets $A_1, \ldots, A_n \subset \mathbb{Z}^n$, find the number $[L_{A_1}, \ldots, L_{A_n}]$ of solutions in $(\mathbb{C}^*)^n$ of a generic system of equations $P_1 = \cdots = P_n = 0$, where $P_1 \in L_1, \ldots, P_n \in L_n$ (i.e., find a formula for the number of solutions of a generic element $(P_1, \ldots, P_n) \in L_{A_1} \times \cdots \times L_{A_n}$).

When the convex hulls of the sets A_i are the same and equal to a polytope Δ , the problem was solved by A.G. Kushnirenko (see [Kush]). He showed that in this case we have

$$[L_{A_1}, \ldots, L_{A_n}] = n! \operatorname{Vol}(\Delta),$$

where Vol is the standard *n*-dimensional volume in \mathbb{R}^n . In other words, if P_1, \ldots, P_n are sufficiently general Laurent polynomials with given Newton polytope Δ , the number of solutions in $(\mathbb{C}^*)^n$ of the system $P_1 = \cdots = P_n = 0$ is equal to $n! \operatorname{Vol}(\Delta)$.

When the convex hulls of the sets A_i are not necessarily the same, the answer was given by D. Bernstein (see [Ber]). He showed that:

$$[L_{A_1},\ldots,L_{A_n}]=n!\,V(\Delta_{A_1},\ldots,\Delta_{A_n}),$$

where V is the mixed volume of convex bodies in \mathbb{R}^n . In other words, if P_1, \ldots, P_n are sufficiently general Laurent polynomials with Newton polytopes $\Delta_1, \ldots, \Delta_n$ respectively, the number of solutions in $(\mathbb{C}^*)^n$ of the system $P_1 = \cdots = P_n = 0$ is equal to $n! V(\Delta_1, \ldots, \Delta_n)$.

Next, let us discuss the Bernstein–Kushnirenko theorem from a point of view which later will allow generalizations. For two non-zero finite dimensional subspaces L_1, L_2 of regular functions in $(\mathbb{C}^*)^n$, define the product L_1L_2 as the subspace spanned by the products fg, where $f \in L_1$, $g \in L_2$. Clearly the multiplication of monomials corresponds to the addition of their exponents, i.e., $z^k z^\ell = z^{k+\ell}$. This implies that $L_{A_1}L_{A_2} = L_{A_1+A_2}$.

Among the subspaces of regular functions in $(\mathbb{C}^*)^n$, there is a natural family consisting of subspaces stable under the action of the multiplicative group $(\mathbb{C}^*)^n$. It is easy to see that any such non-zero subspace is of the form L_A for some nonempty finite subset $A \subset \mathbb{Z}^n$ of monomials. As mentioned above, $L_A L_B = L_{A+B}$, which implies that the collection of stable subspaces is closed under the product of subspaces.

For a finite set $A \subset \mathbb{Z}^n$, let $\overline{A} = \Delta_A \cap \mathbb{Z}^n$. To a subspace L_A we can associate the bigger subspace $L_{\overline{A}}$. From the Bernstein–Kushnirenko theorem it follows that for any (n-1)-tuple of finite subsets $A_2, \ldots A_n \in \mathbb{Z}^n$ we have

$$[L_A, L_{A_2}, \ldots, L_{A_n}] = [L_{\overline{A}}, L_{A_2}, \ldots, L_{A_n}].$$

That is, (surprisingly!) enlarging $L_A \mapsto L_{\overline{A}}$ does not change any of the intersection indices. In other words, in counting the number of solutions of a system, instead of the support of a polynomial, its convex hull plays the main role. We denote the subspace $L_{\overline{A}}$ by $\overline{L_A}$, and call it the *completion of* L_A .

Recall that the semigroup of convex bodies with Minkowski sum has the cancellation property. It implies that the following cancellation property holds for the finite subsets of \mathbb{Z}^n : if for finite subsets $A, B, C \in \mathbb{Z}^n$ we have $\overline{A} + \overline{C} = \overline{B} + \overline{C}$ then $\overline{A} = \overline{B}$. And the same cancellation property holds for the corresponding semigroup of subspaces L_A . That is, if $\overline{L_A} \ \overline{L_C} = \overline{L_B} \ \overline{L_C}$ then $\overline{L_A} = \overline{L_B}$.

The Bernstein–Kushnirenko theorem defines an intersection index on *n*-tuples of subspaces of type L_A (for non-empty finite subsets $A \subset \mathbb{Z}^n$), and computes it in terms of the mixed volume of polytopes. It follows that this intersection index should enjoy the same properties as the mixed volume, namely: 1) positivity, 2) monotonicity, 3) multi-linearity, 4) the Alexandrov–Fenchel inequality and its corollaries. Moreover, we have 5) the subspaces L_A and $L_{\overline{A}}$ have the same intersection indices.

3. Bernstein–Kushnirenko Theorem for Rational Functions and Virtual Polytopes

Let R = P/Q be a rational function on $(\mathbb{C}^*)^n$.

Definition 3.1. We define the virtual Newton polytope Δ_R of R to be $\Delta_P - \Delta_Q$, the formal difference of the Newton polytopes of the polynomials P and Q.

The above definition is well-defined, that is, if $P_1/Q_1 = P_2/Q_2$ then $\Delta_{P_1} + \Delta_{Q_2} = \Delta_{P_2} + \Delta_{Q_1}$ and hence $\Delta_{P_1} - \Delta_{Q_1} = \Delta_{P_2} - \Delta_{Q_2}$.

Unlike the case of Laurent polynomials and Newton polytopes, the family of rational functions with a given virtual polytope $\Delta = \Delta' - \Delta''$ usually can not be described by finitely many parameters.

Example 3.2. Let n = 1 and take $\Delta = \{0\}$. For any k > 0 take two polynomials (in one variable) P and Q such that $\deg(P) = \deg(Q) = k$ and $P(0) \neq 0$ and $Q(0) \neq 0$. Then the Newton segments of P and Q are both equal to the segment [0, k] and hence the rational function R = P/Q has $\{0\}$ as its virtual segment. For

each k, the rational function R = P/Q depends on 2k + 1 parameters and k can be chosen to be arbitrarily large.

Definition 3.3. For two non-empty finite subsets $A, B \subset \mathbb{Z}^n$, let the formal quotient L_A/L_B denote the collection of all the rational functions R = P/Q where P, Q are Laurent polynomials with $P \in L_A$ and $Q \in L_B$. We call L_A/L_B a virtual subspace.

Take finite subsets $A_i, B_i \subset \mathbb{Z}^n, i = 1, ..., n$. We want to associate a number

 $[L_{A_1}/L_{B_1},\ldots,L_{A_n}/L_{B_n}]$

to the virtual subspaces L_{A_i}/L_{B_i} which computes the intersection number of the *principal divisors* of generic functions $R_i \in L_{A_i}/L_{B_i}$: take a partition of $\{1, \ldots, n\}$ into two subsets $I = \{i_1, \ldots, i_r\}$ and $J = \{j_1, \ldots, j_s\}$. To this partition associate the number

$$N(I) = [L_{A_{i_1}}, \ldots, L_{A_{i_r}}, L_{B_{j_1}}, \ldots, L_{B_{j_s}}].$$

That is, N(I) is the number of solutions $x \in (\mathbb{C}^*)^n$ of a generic system $P_{i_1} = \cdots = P_{i_r} = Q_{j_1} = \cdots = Q_{j_s} = 0$, with $P_{i_k} \in L_{A_{i_k}}$ and $Q_{j_k} \in L_{B_{j_k}}$.

Definition 3.4. For virtual subspaces $L_{A_1}/L_{B_1}, \ldots, L_{A_n}/L_{B_n}$, define the number $[L_{A_1}/L_{B_1}, \ldots, L_{A_n}/L_{B_n}]$ by

$$[L_{A_1}/L_{B_1}, \dots, L_{A_n}/L_{B_n}] = \sum_{I \subset \{1,\dots,n\}} (-1)^{n-|I|} N(I)$$

If $B_1 = \cdots = B_n = \{0\}$, then each virtual subspace L_{A_i}/L_{B_i} is equal to L_{A_i} and the number $[L_{A_1}/L_{B_1}, \ldots, L_{A_n}/L_{B_n}]$ is just the number of solutions in $(\mathbb{C}^*)^n$ of a generic system $P_1 = \cdots = P_n = 0$ of Laurent polynomials $P_i \in L_{A_i}$. Unlike $[L_{A_1}, \ldots, L_{A_n}]$, the number $[L_{A_1}/L_{B_1}, \ldots, L_{A_n}/L_{B_n}]$ can be negative. But it is still multi-linear, and symmetric i.e. invariant under the permutation of its arguments.

The following theorem is the extension of Bernstein–Kushnirenko theorem to rational functions and virtual polytopes. For each i, let Δ_i denote the virtual polytope $\Delta_{A_i} - \Delta_{B_i}$.

Theorem 3.5 (Bernstein–Kushnirenko for rational functions).

$$[L_{A_1}/L_{B_1},\ldots,L_{A_n}/L_{B_n}]=n!\,V(\Delta_1,\ldots,\Delta_n).$$

Proof. By multi-linearity of mixed volume for virtual convex bodies, we have:

$$n! V(\Delta_1, \dots, \Delta_n) = n! V(\Delta_{A_1} - \Delta_{B_1}, \dots, \Delta_{A_n} - \Delta_{B_n})$$

= $n! \sum_{I \subset \{1, \dots, n\}} (-1)^{n-|I|} V(\Delta_{A_{i_1}}, \dots, \Delta_{A_{i_r}}, \Delta_{B_{j_1}}, \dots, \Delta_{B_{j_s}}), \quad (*)$

where as above $I = \{i_1, \ldots, i_r\}$ and $J = \{j_1, \ldots, j_s\} = \{1, \ldots, n\} \setminus I$. Now by the Bernstein–Kushnirenko theorem

 $n! V(\Delta_{A_{i_1}}, \ldots, \Delta_{A_{i_r}}, \Delta_{B_{j_1}}, \ldots, \Delta_{B_{j_s}}) = [L_{A_{i_1}}, \ldots, L_{A_{i_r}}, L_{B_{j_1}}, \ldots, L_{B_{j_s}}],$

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and from (*) we have

$$n! V(\Delta_1, \dots, \Delta_n) = \sum_{I \subset \{1, \dots, n\}} (-1)^{n-|I|} [L_{A_{i_1}}, \dots, L_{A_{i_r}}, L_{B_{j_1}}, \dots, L_{B_{j_s}}],$$

ch is just the definition of $[L_{A_1}/L_{B_1}, \dots, L_{A_n}/L_{B_n}].$

which is just the definition of $[L_{A_1}/L_{B_1}, \ldots, L_{A_n}/L_{B_n}]$.

4. An Intersection Index for Subspaces of Regular Functions

4.1. Semigroup of subspaces of an algebra of functions. In this section we define the intersection index of a collection of finite dimensional subspaces L_1, \ldots, L_n of rational functions on an *n*-dimensional variety X, and prove its main properties. Roughly speaking, this intersection index is the number of solutions of a generic system $f_1 = \cdots = f_n$, where $f_i \in L_i$.

For convenience, we restrict ourselves to regular functions and smooth varieties. Later, we will generalize the situation to rational functions on arbitrary varieties.

We start with some general definitions. A set equipped with an algebra of functions is a set X, with an algebra R(X) consisting of complex valued functions on X, and containing all the constants. To a pair (X, R(X)) one can associate the set VR(X) whose elements are vector subspaces of R(X).

Any subspace $L \in VR(X)$ gives rise to a natural map $\tilde{\Phi}_L \colon X \to L^*$, where L^* denotes the vector space dual of L, as follows: for $x \in X$ let $\tilde{\Phi}_L(x) \in L^*$ be the linear function defined by

$$\tilde{\Phi}_L(x)(f) = f(x),$$

for all $f \in L$.

There is a natural multiplication in VR(X):

Definition 4.1. For any two subspaces $L_1, L_2 \subset R(X)$ define the product L_1L_2 to be the linear span of the functions fg, where $f \in L_1$ and $g \in L_2$. With this product the set VR(X) becomes a commutative semigroup. The space L_1L_2 can be considered as a factor of the tensor product $L_1 \otimes L_2$ and there is a natural projection $\pi: L_1 \otimes L_2 \to L_1 L_2$: for $v \in L_1 \otimes L_2$, where $v = \sum_i f_i \otimes g_i$ with $f_i \in L_1$, $g_i \in L_2$, define $\pi(v) = \sum_i f_i g_i$. The projection π is onto but can have non-zero kernel.

Let us say that a subspace L has no base locus on X if for each $x \in X$ there is a function $f \in L$ with $f(x) \neq 0$. The following is easy to verify:

Proposition 4.2. Let L_1, L_2 be vector subspaces of R(X). If L_1, L_2 are finite dimensional (respectively, if L_1 , L_2 have no base locus on X), then the space L_1L_2 is finite dimensional (respectively, has no base locus on X).

According to Proposition 4.2, the finite dimensional subspaces of R(X) with no base locus, form a semigroup in VR(X) which we will denote by KR(X).

Assume that $Y \subset X$ and that the restriction of every function $f \in R(X)$ to Y belongs to an algebra R(Y). We will denote the restriction of a subspace $L \subset R(X)$ to Y again by L. Clearly, if $L \in KR(X)$ then $L \in KR(Y)$.

In this paper we will not use general sets equipped with algebras of functions. Instead, the following case plays the main role.

Definition 4.3. Let X be a variety and let $R(X) = \mathcal{O}(X)$ be the algebra of regular functions on X. In this case to simplify the notation we will not mention the algebra R(X) explicitly and the semigroup KR(X) will be denoted by $\mathbf{K}_{reg}(X)$.

As above any subspace $L \in \mathbf{K}_{reg}(X)$ gives a natural map $\tilde{\Phi}_L \colon X \to L^*$. Since by assumption L has no base locus, for all $x \in X$, we have $\tilde{\Phi}_L(x) \neq 0$.

Definition 4.4 (Kodaira map). For any $x \in X$, let $\Phi_L(x)$ be the point in $\mathbb{P}(L^*)$ represented by $\tilde{\Phi}_L(x) \in L^*$. We call $\Phi_L \colon X \to \mathbb{P}(L^*)$, the Kodaira map of the subspace L. It is a morphism from X to $\mathbb{P}(L^*)$.

Fix a basis $\{f_1, \ldots, f_d\}$ for L. One verifies that, in the homogeneous coordinates in $\mathbb{P}(L^*)$ corresponding to the dual basis to the f_i , the map Φ_L is given by

$$\Phi_L(x) = (f_1(x) : \dots : f_d(x))$$

Finally let us define the notion of an integral element.

Definition 4.5. Let us say that a regular function $f \in \mathcal{O}(X)$ is *integral over a subspace* $L \in \mathbf{K}_{reg}(X)$, if f satisfies an equation

$$^{m} + a_{1}f^{m-1} + \dots + a_{m} = 0,$$

where m > 0 and $a_i \in L^i$, for each $i = 1, \ldots, m$.

 f^{γ}

4.2. Preliminaries on algebraic varieties. In this section, we discuss some well-known results which we need to define an intersection index in the semigroup $K_{\text{reg}}(X)$. We will need the particular cases of the following results:

- (1) An algebraic variety has a *finite* topology.
- (2) There are finitely many topologically different varieties in an algebraic family of algebraic varieties.
- (3) In such a family the set of parameters for which the corresponding members have the same topology, is a complex semi-algebraic subset in the space of parameters.
- (4) A complex semi-algebraic subset in a vector space either covers almost all of the space, or covers only a very small part of it.

Let us give precise statements of these results and their particular cases we will use. Let X, Y be algebraic varieties and let $\pi: X \to Y$ be a morphism. Consider the family of algebraic varieties $X_y = \pi^{-1}(y)$ parameterized by the points $y \in Y$. The following is well-known.

Theorem 4.6. Each variety X_y has the homotopy type of a finite CW-complex. There is a finite stratification of the variety Y into complex semi-algebraic strata Y_{α} such that for any two points y_1 , y_2 in the same stratum Y_{α} , the varieties X_{y_1} , X_{y_2} , are homeomorphic. (In particular, in the family X_y there are only finitely many topologically different varieties.)

When X, Y are real algebraic varieties and $\pi: X \to Y$ is a (real) morphism, a similar statement holds. There are also extensions of the above to some other cases (see [Dri]). We will need only the following simple corollary of this theorem.

Let L_1, \ldots, L_n be finite dimensional subspaces of regular functions on an *n*dimensional algebraic variety X. For $\mathbf{f} = (f_1, \ldots, f_n) \in \mathbf{L} = L_1 \times \cdots \times L_n$, let $X_{\mathbf{f}}$ denote the subvariety of X, defined by the system of equations $f_1 = \cdots = f_n = 0$. In the space \boldsymbol{L} of parameters consider the subset \boldsymbol{F} consisting of all the parameters \boldsymbol{f} for which the set $X_{\boldsymbol{f}}$ consists of isolated points only.

Corollary 4.7. (1) For every $f \in F$ the set X_f is finite.

(2) Denote the number of points in $X_{\mathbf{f}}$ by $k(\mathbf{f})$, then there is a finite stratification of the set \mathbf{F} with complex semi-algebraic strata Y_{α} such that the function $k(\mathbf{f})$ is constant on each stratum. In particular, the subset $\mathbf{F}_{\max} \subset \mathbf{F}$ where $k(\mathbf{f})$ attains its maximum is a complex semi-algebraic set.

The above corollary can be proved without using Theorem 4.6. The semialgebraicity of the set \mathbf{F} and its subsets $\mathbf{F}_m = \{\mathbf{f} \in \mathbf{F} : k(\mathbf{f}) = m\}$ follow from the complex version of the Tarski theorem. An analogous fact in the real case can also be proved using the (real) Tarski theorem. An elementary proof of the Tarski theorem and its complex version can be found in [BK]. An elementary theory of real algebraic varieties can be found in [Whi].

We will need the following simple property of complex semi-algebraic sets.

Proposition 4.8. Let $F \subset L$ be a complex semi-algebraic subset in a (complex) vector space L. Then either there is an algebraic hypersurface $\Sigma \subset L$ which contains F, or F contains a Zariski open set $U \subset L$.

We will use this proposition in the following form.

Corollary 4.9. Let $F \subset L$ be a complex semi-algebraic subset in a (complex) vector space L. In either of the following cases, F contains a Zariski open subset $U \subset L$: (1) F is an everywhere dense subset of L, or (2) F does not have zero measure.

4.3. An intersection index in semigroup $K_{reg}(X)$

Definition 4.10. Let X be a smooth (not necessarily connected) complex n-dimensional variety and let $L_1, \ldots, L_n \in \mathbf{K}_{reg}(X)$. The *intersection index* $[L_1, \ldots, L_n]$ is the maximum number of roots of a system $f_1 = \cdots = f_n = 0$ over all the points $\mathbf{f} = (f_1, \ldots, f_n) \in L_1 \times \cdots \times L_n = \mathbf{L}$ for which the corresponding system has finitely many solutions.

By Corollary 4.7 the maximum is attained and the previous definition is welldefined. The following is a straightforward corollary of the definition.

Theorem 4.11 (Obvious properties of the intersection index). Let $L_1, \ldots, L_n \in \mathbf{K}_{reg}(X)$, then:

- (1) $[L_1, \ldots, L_n]$ is a symmetric function of the n-tuple L_1, \ldots, L_n (i.e., takes the same value under a permutation of L_1, \ldots, L_n).
- (2) The intersection index is monotone (i.e., if $L'_1 \subseteq L_1, \ldots, L'_n \subseteq L_n$, then $[L_1, \ldots, L_n] \ge [L'_1, \ldots, L'_n]$).
- (3) The intersection index is non-negative (i.e., $[L_1, \ldots, L_n] \ge 0$).

Let X be a smooth (not necessary connected) complex *n*-dimensional variety, and let $L_1, \ldots, L_k \in \mathbf{K}_{reg}(X)$. Put $\mathbf{L}(k) = L_1 \times \cdots \times L_k$.

Proposition 4.12. There is a non-empty Zariski open set U in L(k) such that either for any point $f = (f_1, \ldots, f_k)$ in U the system of equations $f_1 = \cdots = f_k = 0$ has no solution in X, or the system is consistent⁵ and non-degenerate (i.e., at every root of the system the differentials df_1, \ldots, df_k are linearly independent).

Proof. Fix a basis $\{g_{ij}\}$ for each of the spaces L_i . Consider all the k-tuples $g_i =$ $(g_{1j_1}, \ldots, g_{kj_k})$, where $\mathbf{j} = (j_1, \ldots, j_k)$, containing exactly one vector from each of the bases $\{g_{ij}\}$ for the L_i . Denote by V_j the Zariski open subset in X defined by the system of inequalities $g_{1,j_1} \neq 0, \ldots, g_{k,j_k} \neq 0$. (Note that since X can be reducible, the set V_j might be empty.) Since L_1, \ldots, L_k are in $K_{reg}(X)$, the union of the sets V_j equals X. When the set V_j is non-empty, rewrite the system $f_1 = \cdots = f_k = 0$ as follows: represent each function f_i in the form $f_i = \bar{f}_i + c_i g_{ij_i}$, where \bar{f}_i belongs to the linear span of the g_{ij} excluding g_{ij_i} . Now, in V_j , the system can be rewritten as $\frac{\bar{f}_1}{g_{1,j_1}} = -c_1, \ldots, \frac{\bar{f}_k}{g_{k,j_k}} = -c_k$. According to Sard's theorem, for almost all the $\boldsymbol{c} = (c_1, \ldots, c_k)$ the system is non-degenerate. Denote by W_j the subset in $\boldsymbol{L}(k)$, consisting of all the f for which the system $f_1 = \cdots = f_k = 0$ is non-degenerate in V_j . The set W_j splits into the union of the complex semi-algebraic subsets W_j^1 and W_{i}^{2} , containing the consistent or non-consistent systems respectively. Thus by Corollary 4.9, exactly one of the sets W_j^1 or W_j^2 contains a non-empty Zariski open subset U_j . The intersection U of the sets U_j is a Zariski open subset in L(k)which satisfies all the requirements of the proposition. \square

Proposition 4.13. The number of isolated roots, counted with multiplicity, of a system $f_1 = \cdots = f_n = 0$, where $f_i \in L_i$, is less than or equal to $[L_1, \ldots, L_n]$.

Proof. Suppose A is a subset of the isolated roots of the system such that k(A), the sum of multiplicities of the roots in A, is bigger than $[L_1, \ldots, L_n]$. According to Proposition 4.12 one can slightly perturb the system to make it non-degenerate. Under such a perturbation the roots belonging to the set A will split into $k(A) > [L_1, \ldots, L_n]$ simple roots while all other roots are also simple. But by Corollary 4.7 the number of these roots can not be bigger than $[L_1, \ldots, L_n]$. The contradiction proves the proposition.

Now we prove that if a system of equations is in general position then in Proposition 4.13, instead of inequality we have an equality. As before let $L = L_1 \times \cdots \times L_n$.

Proposition 4.14. There is a non-empty Zariski open set U in L such that for any point $f = (f_1, \ldots, f_n)$ in U the system of equations $f_1 = \cdots = f_n = 0$ on Xis non-degenerate and has exactly $[L_1, \ldots, L_n]$ solutions.

Proof. Firstly, if the number of isolates roots of a system is equal to $[L_1, \ldots, L_n]$ then it is non-degenerate (otherwise its number of roots, counting with multiplicity, would be bigger than $[L_1, \ldots, L_n]$, which is impossible by Proposition 4.13). So there must be a non-degenerate system which has $[L_1, \ldots, L_n]$ roots. Secondly, any system which is close enough to this system has exactly the same number of isolated roots and almost all such systems are non-degenerate. So the set of non-degenerate systems which have exactly $[L_1, \ldots, L_n]$ roots is not a set of measure

⁵A system is consistent if its set of solutions is non-empty.

zero. But since this set is complex semi-algebraic, by Corollary 4.9, it should contain a (non-empty) Zariski open subset.

Let Y be an *m*-dimensional quasi-projective smooth subvariety of X. For any *m*-tuple of subspaces $L_1, \ldots, L_m \in \mathbf{K}_{reg}(X)$ let $[L_1, \ldots, L_m]_Y$ denote the intersection index of the restrictions of these subspaces to Y.

Consider an *n*-tuple $L_1, \ldots, L_n \in \mathbf{K}_{reg}(X)$. As before, for $k \leq n$ put $\mathbf{L}(k) = L_1 \times \cdots \times L_k$. According to Proposition 4.12, there is a non-empty Zariski open subset $\mathbf{U}(k)$ in $\mathbf{L}(k)$ such that for $\mathbf{f}(k) = (f_1, \ldots, f_k) \in \mathbf{U}(k)$, either the system $f_1 = \cdots = f_k = 0$ has no solutions or it defines a smooth subvariety $X_{\mathbf{f}(k)}$ in X.

Theorem 4.15. If the system $f_1 = \cdots = f_k = 0$ has no solution then $[L_1, \ldots, L_n] = 0$. If the system is consistent, then the following holds:

(1) For any point $f(k) \in U(k)$ we have:

$$[L_1, \dots L_n]_X \ge [L_{k+1}, \dots L_n]_{X_{f(k)}}.$$
(**)

(2) Moreover, there is a Zariski open subset $V(k) \subset U(k)$ such that for any $f(k) \in V(k)$, the inequality (******) is in fact an equality.

Proof. The statement about non-consistent systems is obvious. Let us prove the other statements. (1) If (**) does not hold for a point $\mathbf{f}(k)$, then there are $f_{k+1} \in L_{k+1}, \ldots, f_n \in L_n$ such that the system $f_1 = \cdots = f_n = 0$ has more isolated solution on X than the intersection index $[L_1, \ldots, L_n]$, which is impossible. (2) According to Proposition 4.12 the collection of systems $\mathbf{f} = (f_1, \ldots, f_n) \in \mathbf{L}$ which belong to the Zariski open set \mathbf{U} in Proposition 4.14 and for which the subsystem $f_1 = \cdots = f_k = 0$ is non-degenerate, contains a Zariski open set $\mathbf{V} \subset \mathbf{U}$. Let $\pi: \mathbf{L} \to \mathbf{L}(k)$ be the projection $(f_1, \ldots, f_n) \mapsto (f_1, \ldots, f_k)$. Now we can take $\mathbf{V}(k)$ to be any (non-empty) Zariski open subset in $\mathbf{L}(k)$ contained in $\pi(\mathbf{V})$.

Theorem 4.15 allows us to reduce the computation of the intersection index on a higher dimensional smooth quasi-projective variety to the computation of the intersection index on a lower dimensional smooth subvariety. As we will see, it is not hard to establish the main properties of the intersection index for affine curves. Using Theorem 4.15 we then easily obtain the corresponding properties for the intersection index on smooth varieties of arbitrary dimension.

4.4. Preliminaries on algebraic curves. Here we recall some basic facts about algebraic curves which we will use later. Let X be a smooth quasi-projective curve (not necessarily irreducible or complete).

Theorem 4.16 (Normalization of algebraic curves). There is a unique (up to isomorphism) smooth compactification \overline{X} of X. The complement $A = \overline{X} \setminus X$, is a finite set, and any regular function on X has a meromorphic extension to \overline{X} .

One can find a proof of this classical result in most of the text books in algebraic geometry (e.g., [Har, Chapter 1]). This theorem allows us to find the number of zeros of a regular function g on X with a prescribed behavior at infinity, i.e., $\overline{X} \setminus X$. Indeed if g is not identically zero on some irreducible component of the curve X,

then the order $\operatorname{ord}_a(g)$ of its meromorphic extension at a point $a \in \overline{X}$ is welldefined. The function g on the projective curve \overline{X} has the same number of roots as the number of poles (counting with multiplicity). Thus we have the following:

Proposition 4.17. For every regular function g on a smooth quasi-projective curve X (which is not identically zero on any irreducible component of X) the number of roots, counting with multiplicity, is equal to $-\sum_{a \in A} \operatorname{ord}_a(g)$, where $\operatorname{ord}_a(g)$ is the order of the meromorphic extension of the function g to \overline{X} at the point a.

4.5. Intersection index in semigroup $K_{reg}(X)$ of an algebraic curve X. Let $L \in K_{reg}(X)$ and let $B = \{f_i\}$ be a basis for L such that none of the f_i are identically zero on any irreducible component of the curve X. For each point $a \in A = \overline{X} \setminus X$ denote by $ord_a(L)$ the minimum, over all functions in B, of the numbers $ord_a(f_i)$. Clearly, for every $g \in L$ we have $ord_a(g) \ge ord_a(L)$. The collection of functions $g \in L$ whose order at the point a is strictly bigger than $ord_a(L)$ form a proper subspace L_a of L.

Definition 4.18. Define the *degree* of a subspace $L \in \mathbf{K}_{reg}(X)$ to be

$$\sum_{a \in A} -\operatorname{ord}_a(L)$$

and denoted it by $\deg(L)$.

For each irreducible component X_i of the curve X, denote the subspace of L, consisting of all the functions identically equal to zero on X_i , by L_{X_i} . The subspace L_{X_i} is a proper subspace of L because L has no base locus.

The following is a corollary of Proposition 4.17.

Proposition 4.19. If a function $f \in L$ does not belong to the union of the subspaces L_{X_i} , then f has finitely many roots on X. The number of roots of the function f (counting with multiplicity) is less than or equal to deg(L). If f is not in the union of the subspaces L_a , $a \in A$, then the equality holds.

Proposition 4.20. For $L, M \in \mathbf{K}_{reg}(X)$ we have [L] + [M] = [LM].

Proof. For any point $a \in A$ and any two functions $f \in L$, $g \in M$ the identity $\operatorname{ord}_a(f) + \operatorname{ord}_a(g) = \operatorname{ord}_a(fg)$ holds. Thus we have $\operatorname{ord}_a(L) + \operatorname{ord}_a(M) = \operatorname{ord}_a(LM)$, which implies $\deg(L) + \deg(M) = \deg(LM)$, and hence [L] + [M] = [LM].

Consider the map $-\operatorname{Ord}$ which associates to a subspace $L \in \mathbf{K}_{\operatorname{reg}}(X)$ an integer valued function on the set A: the value of $-\operatorname{Ord}(L)$ at $a \in A$ equals $-\operatorname{ord}_a(L)$. The map $-\operatorname{Ord}$ is a homomorphism from the multiplicative semigroup $\mathbf{K}_{\operatorname{reg}}(X)$ to the additive group of integer valued functions on the set A. Clearly the number [L] can be computed in terms of the homomorphism $-\operatorname{Ord}$ because $[L] = \deg(L) = \sum_{a \in A} -\operatorname{ord}_a L$.

Proposition 4.21. Assume that a regular function g on the curve X is integral over a subspace $L \in \mathbf{K}_{reg}(X)$. Then at each point $a \in A$ we have

 $\operatorname{ord}_a g \ge \operatorname{ord}_a L.$

Proof. Let $g^n + f_1 g^{n-1} + \dots + f_n = 0$, where $f_i \in L^i$. Suppose $\operatorname{ord}_a g = k < \operatorname{ord}_a L$. Since $g^n = -f_1g^{n-1} - \cdots - f_n$ we have $nk = \operatorname{ord}_a(g^n) \ge \min\{\operatorname{ord}_a(f_1g^{n-1}), \ldots,$ $\operatorname{ord}_a(f_n)$. That is, for some $i, nk \ge \operatorname{ord}_a(f_i) + k(n-i)$. But for every i, $\operatorname{ord}_a(f_ig^{n-i}) = \operatorname{ord}_a(f_i) + \operatorname{ord}_a(g^{n-i}) > i \cdot \operatorname{ord}_a(L) + k(n-i) > nk.$ The contradiction proves the claim.

Corollary 4.22. Assume that a regular function g on the curve X is integral over a subspace $L \in \mathbf{K}_{reg}(X)$. Consider the subspace $M \in \mathbf{K}_{reg}(X)$ spanned by g and L. Then:

- (1) At each point $a \in A$ the equality $\operatorname{ord}_a(L) = \operatorname{ord}_a(M)$ holds.
- (2) [L] = [M].
- (3) For each subspace $N \in \mathbf{K}_{reg}(X)$ we have [LN] = [MN].

4.6. Properties of the intersection index which can be deduced from the curve case.

Theorem 4.23 (Multi-linearity). Let $L'_1, L''_1, L_2, \ldots, L_n \in \mathbf{K}_{reg}(X)$ and put $L_1 =$ $L'_1L''_1$. Then [

$$L_1, \ldots, L_n] = [L'_1, \ldots, L_n] + [L''_1, \ldots, L_n].$$

Proof. Consider three *n*-tuples $(L'_1, \ldots, L_n), (L''_1, \ldots, L_n)$ and $(L'_1L''_1, \ldots, L_n)$ of elements of the semigroup $K_{reg}(X)$. If a generic system $f_2 = \cdots = f_n = 0$, where $f_2 \in L_2, \ldots, f_n \in L_n$ is non-consistent then the three indices appeared in the theorem are equal to zero. Thus the theorem holds in this case. Otherwise, according to Theorem 4.15 there is an (n-1)-tuple $f_2 \in L_2, \ldots, f_n \in L_n$ such that the system $f_2 = \cdots = f_n = 0$ is non-degenerate and defines a curve $Y \subset X$ such that $[L'_1, \ldots, L_n] = [L'_1]_Y, [L''_1, \ldots, L_n] = [L''_1]_Y$ and $[L'_1L''_1, \ldots, L_n] = [L'_1L''_1]_Y$. Using Proposition 4.20 we obtain $[L'_1L''_1]_Y = [L'_1]_Y + [L''_1]_Y$ and theorem is proved. \Box

Corollary 4.24. Let $L_1, L_2, \ldots, L_n \in \mathbf{K}_{reg}(X)$, then for any k > 0 we have

$$[L_1^k, L_2, \ldots, L_n] = k[L_1, L_2, \ldots, L_n].$$

By the above corollary, given some k > 0, if we know the intersection index of the space L_1^k and any (n-1)-tuple of subspaces L_2, \ldots, L_n , we can recover the intersection index of L_1 and $L_2, \ldots L_n$. The computation of the intersection index of L_1^k might be easier since it contains more functions.

Theorem 4.25 (Addition of integral elements). Let $L_1 \in \mathbf{K}_{reg}(X)$ and let $M_1 \in$ $\mathbf{K}_{reg}(X)$ be a subspace spanned by $L_1 \in \mathbf{K}_{reg}(X)$ and a regular function g which is integral over L_1 . Then for any (n-1)-tuple $L_2, \ldots, L_n \in \mathbf{K}_{reg}(X)$ we have

$$[M_1, L_2, \ldots, L_n] = [L_1, L_2, \ldots, L_n].$$

Proof. Consider two n-tuples (L_1, L_2, \ldots, L_n) , (M_1, L_2, \ldots, L_n) of $K_{reg}(X)$. If a generic system $f_2 = \cdots = f_n = 0$, where $f_2 \in L_2, \ldots, f_n \in L_n$ is non-consistent, then the two indices appearing in the theorem are equal to zero. Thus the theorem holds this case. Otherwise, according to Theorem 4.15 there is an (n-1)-tuple $(f_2, \ldots, f_n), f_i \in L_i$ such that the system $f_2 = \cdots = f_n = 0$ is non-degenerate and defines a curve $Y \subset X$ with $[L_1, L_2, \ldots, L_n] = [L_1]_Y$ and $[G_1, L_2, \ldots, L_n] =$ $[G_1]_Y$. Using Corollary 4.22 we obtain $[L_1]_Y = [M_1]_Y$ as required. \square

4.7. Properties of the intersection index which can be deduced from the surface case. Motivated by the terminology of line bundles, let us say that a subspace $L \in \mathbf{K}_{reg}(X)$ is very ample if the Kodaira map $\Phi_L \colon X \to \mathbb{P}(L^*)$ is an embedding. Note that L is very ample if and only if for any k > 0, L^k is very ample. The very ample subspaces form a subsemigroup of $\mathbf{K}_{reg}(X)$. Let $Y \subset X$ be a smooth algebraic subvariety of a smooth variety X and let $L \in \mathbf{K}_{reg}(X)$ be a very ample subspace. Then the restriction of L to Y is a very ample space in $\mathbf{K}_{reg}(Y)$.

Theorem 4.26 (A version of the Bertini–Lefschetz theorem). Let X be a smooth irreducible n-dimensional quasi-projective variety and let $L_1, \ldots, L_k \in \mathbf{K}_{reg}(X)$, k < n, be very ample subspaces. Then there is a Zariski open set $\mathbf{U}(k)$ in $\mathbf{L}(k) = L_1 \times \cdots \times L_k$ such that for each point $\mathbf{f}(k) = (f_1, \ldots, f_k) \in \mathbf{U}(k)$ the variety defined in X by the system of equations $f_1 = \cdots = f_k = 0$ is smooth and irreducible.

A proof of the Bertini–Lefschetz theorem can be found in [Har, Theorem 8.18]

Theorem 4.27 (A version of Hodge inequality). Let X be a smooth irreducible surface and let $L_1, L_2 \in \mathbf{K}_{reg}(X)$ be very ample subspaces. Then we have $[L_1, L_2]^2 \ge [L_1, L_1][L_2, L_2]$.

To make the present paper self-contained we give a proof of Theorem 4.27 using the usual Hodge theory in the appendix. Also as mentioned in the introduction, the authors have found an elementary proof of Theorem 4.27 using only the isoperimetric inequality for planar convex bodies and the Hilbert theorem on degree of a subvariety in the projective space. This has appeared in a separate paper (see [KKh1, Theorem 5.9] for a preliminary version, and [KKh2, Part IV] for the detailed version).

Theorem 4.28 (Algebraic analogue of the Alexandrov–Fenchel inequality). Let X be an irreducible n-dimensional smooth quasi-projective variety and let $L_1, \ldots, L_n \in \mathbf{K}_{reg}(X)$ be very ample subspaces. Then the following inequality holds

$$[L_1, L_2, L_3, \dots, L_n]^2 \ge [L_1, L_1, L_3, \dots, L_n][L_2, L_2, L_3, \dots, L_n].$$

Proof. Consider *n*-tuples $(L_1, L_2, L_3, \ldots, L_n)$, $(L_1, L_1, L_3, \ldots, L_n)$ and $(L_2, L_2, L_3, \ldots, L_n)$ of subspaces in the semigroup $\mathbf{K}_{\text{reg}}(X)$. According to the Bertini–Lefschetz theorem and Theorem 4.15 there is an (n-2)-tuple of functions $f_3 \in L_3, \ldots, f_n \in L_n$ such that the system $f_3 = \cdots = f_n = 0$ is non-degenerate and defines an irreducible surface $Y \subset X$ for which we have:

$$[L_1, L_2, L_3, \dots, L_n] = [L_1, L_2]_Y,$$

$$[L_1, L_1, L_3, \dots, L_n] = [L_1, L_1]_Y,$$

$$[L_2, L_2, L_3, \dots, L_n] = [L_2, L_2]_Y.$$

By Theorem 4.27,

$$[L_1, L_2]_Y^2 \ge [L_1, L_1]_Y [L_2, L_2]_Y$$

which proves the theorem.

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The above theorem, in a slightly different form, was proved at the beginning of 1980's by Teissier and the second author. A survey and a list of references can be found in [Kh1].

Similar to Section 2.1, let us introduce a notation for the repetition of subspaces in the intersection index. Let $2 \leq m \leq n$ be an integer and $k_1 + \cdots + k_r = m$ a partition of m with $k_i \in \mathbb{N}$. Consider the subspaces $L_1, \ldots, L_n \in \mathbf{K}_{reg}(X)$. Denote by $[k_1 * L_1, \ldots, k_r * L_r, L_{m+1}, \ldots, L_n]$ the intersection index of these subspaces where L_1 is repeated k_1 times, L_2 is repeated k_2 times, etc. and L_{m+1}, \ldots, L_n appear once. The following inequalities follow from Theorem 4.28 exactly in the same way as the analogous geometric inequalities follow from the Alexandrov– Fenchel inequality.

Corollary 4.29 (Corollaries of the algebraic analogue of Alexandrov–Fenchel inequality). Let X be an n-dimensional smooth irreducible quasi-projective variety.

(1) Let $2 \leq m \leq n$ and $k_1 + \cdots + k_r = m$ with $k_i \in \mathbb{N}$. Take very ample subspaces of regular functions $L_1, \ldots, L_n \in \mathbf{K}_{reg}(X)$. Then

$$[k_1 * L_1, \ldots, k_r * L_r, L_{m+1}, \ldots, L_n]^m \ge \prod_{1 \le j \le r} [m * L_j, L_{m+1}, \ldots, L_n]^{k_j}.$$

(2) (Generalized Brunn–Minkowski inequality) For any fixed very ample subspaces $L_{m+1}, \ldots, L_n \in \mathbf{K}_{reg}(X)$, the function

$$F: L \mapsto [m * L, L_{m+1}, \ldots, L_n]^{1/m},$$

is a concave function on the semigroup of very ample subspaces.

5. Intersection Index for Subspaces of Rational Functions

In this section we extend the definitions and results in the previous section to the following general situation: instead of a smooth *n*-dimensional quasi-projective variety we take any quasi-projective variety X (possibly singular) such that all its irreducible components have the same dimension n. And instead of a finite dimensional subspace of regular functions with no base locus, we take any finite dimensional subspace of rational functions on X such that its restriction to any irreducible component of X is a non-zero subspace.

Let us start with the following lemma dealing with subspaces of regular functions. Recall that $\mathbf{K}_{reg}(X)$ denotes the collection of all the finite dimensional subspaces of regular functions on X with no base locus.

Lemma 5.1. Let X be an n-dimensional quasi-projective variety (not necessarily smooth) and let $L_1, \ldots, L_n \in \mathbf{K}_{reg}(X)$. Then for any subvariety $\Sigma \subset X$ with $\dim(\Sigma) < n$, there is a non-empty Zariski open subset $\mathbf{U}_{\Sigma} \subset \mathbf{L} = L_1 \times \cdots \times L_n$ such that for any $\mathbf{f} = (f_1, \ldots, f_n) \in \mathbf{U}_{\Sigma}$ the system $f_1 = \cdots = f_n = 0$ has no solution in Σ .

Proof. As in Proposition 4.12 let us fix a basis g_{ij} for each subspace L_i . Consider all the *n*-tuples $g_j = (g_{1j_1}, \ldots, g_{nj_n})$, where $j = (j_1, \ldots, j_n)$, which contain one function from each basis $\{g_{ij}\}$. Let V_j be the Zariski open subset in X defined by the inequalities $g_{ij_i} \neq 0, i = 1, \ldots, n$. Since $L_1, \ldots, L_n \in \mathbf{K}_{reg}(X)$, the union of

the sets V_j is X. Represent each function f_i in the form $f_i = \bar{f}_i + c_i g_{ij_i}$, where \bar{f}_i is the linear combination of all the basis functions g_{ik} except g_{i,j_i} . When V_j is non-empty the system can be written as

$$\frac{\bar{f}_1}{g_{1,j_1}} = -c_1, \ \dots, \ \frac{\bar{f}_n}{g_{n,j_n}} = -c_n.$$

In other words in the open set V_j each solution of the system $f_1 = \cdots = f_n = 0$ is a preimage of the point $-\mathbf{c} = (-c_1, \ldots, -c_n)$ in \mathbb{C}^n under the map $\phi_j \colon V_j \to \mathbb{C}^n$ given by

$$\phi_{\boldsymbol{j}} = \left(\frac{\bar{f}_1}{g_{1,j_1}}, \ldots, \frac{\bar{f}_n}{g_{n,j_n}}\right).$$

Let $\Sigma_{j} = \Sigma \cap V_{j}$. The set $\phi(\Sigma_{j})$, has dimension smaller than n and hence there is a Zariski open subset $U_{j} \in L$ such that for $f = (f_{1}, \ldots, f_{n}) \in U_{j}$ the system $f_{1} = \cdots = f_{n} = 0$ has no solutions in Σ_{j} . Now take U_{Σ} to be the intersection of all the U_{j} .

Definition 5.2. Let X be a quasi-projective variety such that all its irreducible components have the same dimension n. Denote by $\mathbf{K}_{rat}(X)$ the collection of all the finite dimensional subspaces L of rational functions on X such that the restriction of L to any irreducible component of X is a non-zero subspace.

A rational function is not necessarily defined everywhere on X. Nevertheless we can still define a multiplication on $\mathbf{K}_{rat}(X)$ exactly as we did for $\mathbf{K}_{reg}(X)$, and with this multiplication $\mathbf{K}_{rat}(X)$ becomes a (commutative) semigroup. We now define a birationally invariant intersection index on the semigroup $\mathbf{K}_{rat}(X)$.

Definition 5.3. Let $L \in \mathbf{K}_{rat}(X)$. We say that a closed subvariety $\Sigma \subset X$ is said to be *admissible* for (X, L) if it satisfies the following properties:

- (i) Σ contains the singular locus of X and hence $X \setminus \Sigma$ is smooth.
- (ii) $\dim(\Sigma) < n$.
- (iii) Σ contains the supports of all the irreducible divisors on which a function from L has a pole.
- (iv) Σ contains the base locus of L, i.e., the set of points where all the functions in L vanish.

A closed subvariety $\Sigma \subset X$ is said to be *admissible* for a finite collection $L_1, \ldots, L_k \in \mathbf{K}_{rat}(X)$ if it is admissible for each $L_i, i = 1, \ldots, k$.

Remark 5.4. Take a subspace $L \in \mathbf{K}_{rat}(X)$ and an admissible subvariety Σ for L. The Kodaira map Φ_L is defined and regular on $X \setminus \Sigma$. Thus for $L \in \mathbf{K}_{rat}(X)$, we can talk about the Kodaira map Φ_L as a rational map from X to $\mathbb{P}(L^*)$.

Let X be a quasi-projective variety such that all its irreducible components have dimension n. Consider $L_1, \ldots, L_n \in \mathbf{K}_{rat}(X)$. Take any subvariety Σ which is admissible for X and L_1, \ldots, L_n .

Definition 5.5. Let $L_1, \ldots, L_n \in \mathbf{K}_{rat}(X)$. The birationally invariant intersection index (or for short the intersection index) of the subspaces L_1, \ldots, L_n is the intersection index $[L_1, \ldots, L_n]_{X \setminus \Sigma}$ of the restrictions of the subspaces L_i to the smooth variety $X \setminus \Sigma$. We denote it by the symbol $[L_1, \ldots, L_n]_X$, or simply by $[L_1, \ldots, L_n]$ when there is no confusion about the variety X.

Proposition 5.6. The birationally invariant index is well-defined.

Proof. The index $[L_1, \ldots, L_n]_{X \setminus \Sigma}$ is defined because L_i are finite dimensional subspaces of regular function without base locus on $X \setminus \Sigma$. Let us show that the index $[L_1, \ldots, L_n]_{X \setminus \Sigma}$ is independent of the choice of an admissible set Σ . Let Σ_1, Σ_2 be two admissible subvarieties and put $\Sigma = \Sigma_1 \cup \Sigma_2$. Then Σ is also admissible. Now by Lemma 5.1 we have:

$$[L_1,\ldots,L_n]_{X\setminus\Sigma_1}=[L_1,\ldots,L_n]_{X\setminus\Sigma},$$

and

$$[L_1,\ldots,L_n]_{X\setminus\Sigma_2}=[L_1,\ldots,L_n]_{X\setminus\Sigma},$$

which proves the proposition.

Let $\tau \colon X \to Y$ be a birational isomorphism between the *n*-dimensional varieties X and Y.

Proposition 5.7. For each n-tuple $L_1, \ldots, L_n \in \mathbf{K}_{rat}(Y)$ we have

$$[L_1, \ldots, L_n]_Y = [\tau^* L_1, \ldots, \tau^* L_n]_X.$$

Proof. Since τ is a birational isomorphism one can find subvarieties $\Sigma \subset X$ and $\Gamma \subset Y$ such that τ is an isomorphism from $X \setminus \Sigma$ to $Y \setminus \Gamma$. By enlarging Σ and Γ we can assume that they are admissible for $\tau^*L_1, \ldots, \tau^*L_n$ on X and L_1, \ldots, L_n on Y respectively. It is clear that $[L_1, \ldots, L_n]_{Y \setminus \Gamma} = [\tau^*L_1, \ldots, \tau^*L_n]_{X \setminus \Sigma}$. Since

$$[L_1,\ldots,L_n]_Y=[L_1,\ldots,L_n]_{Y\setminus\Gamma},$$

and

$$[\tau^*L_1,\ldots,\tau^*L_n]_X=[\tau^*L_1,\ldots,\tau^*L_n]_{X\setminus\Sigma},$$

we are done.

Proposition 5.8. Let $L_1 \in \mathbf{K}_{rat}(X)$ be a one dimensional subspace of rational functions. Then for any (n-1)-tuple of subspaces $L_2, \ldots, L_n \in \mathbf{K}_{rat}(X)$ we have $[L_1, \ldots, L_n] = 0.$

Proof. Suppose L_1 is spanned by a rational function f. An admissible subvariety Σ for L_1, \ldots, L_n contains the hypersurface $\{f = 0\}$. But then no function in L_1 vanishes on $X \setminus \Sigma$ and hence

$$[L_1, \ldots, L_n] = [L_1, \ldots, L_n]_{X \setminus \Sigma} = 0.$$

Theorem 5.9. (1) $[L_1, \ldots, L_n]$ is symmetric function of $L_1, \ldots, L_n \in \mathbf{K}_{rat}(X)$ (*i.e.*, takes the same value under a permutation of the elements L_1, \ldots, L_n).

(2) The birationally invariant index is monotone (i.e., if $L'_1 \subseteq L_1, \ldots, L'_n \subseteq L_n$, then $[L_1, \ldots, L_n] \ge [L'_1, \ldots, L'_n]$).

(3) The birationally invariant index is non-negative (i.e., $[L_1, \ldots, L_n] \ge 0$).

Proof. Follows from Theorem 4.11.

Theorem 5.10 (Multi-linearity). Let $L'_1, L''_1, L_2, \ldots, L_n \in \mathbf{K}_{rat}(X)$ and put $L_1 = L'_1L''_1$. Then

$$[L_1, \ldots, L_n] = [L'_1, \ldots, L_n] + [L''_1, \ldots, L_n].$$

Proof. Follows from Theorem 4.23.

Corollary 5.11. Let $L_1, \ldots, L_n \in \mathbf{K}_{rat}(X)$. Take 1-dimensional subspaces $L'_1, \ldots, L'_n \in \mathbf{K}_{rat}(X)$. Then

$$[L_1, \ldots, L_n] = [L'_1 L_1, \ldots, L'_n L_n]$$

Proof. Follows from Proposition 5.8 and Theorem 5.10.

Definition 5.12. As before let us say that $f \in \mathbb{C}(X)$ is *integral over a subspace* $L \in \mathbf{K}_{rat}(X)$ if f satisfies an equation

$$f^m + a_1 f^{m-1} + \dots + a_m = 0,$$

where m > 0 and $a_i \in L^i$, for each $i = 1, \ldots, m$.

Theorem 5.13 (Addition of integral elements). Let $L_1 \in \mathbf{K}_{rat}(X)$ and let $M_1 \in \mathbf{K}_{rat}(X)$ be the subspace spanned by L_1 and a rational function g integral over L_1 . Then for any (n-1)-tuple $L_2, \ldots, L_n \in \mathbf{K}_{rat}(X)$ we have

$$[L_1, L_2, \ldots, L_n] = [M_1, L_2, \ldots, L_n]$$

Proof. Follows form Theorem 4.25.

Definition 5.14. It is well-known that the collection of all integral elements over L is a vector subspace containing L. Moreover if L is finite dimensional then \overline{L} is also finite dimensional (see [ZS, Appendix 4]). It is called the *completion of* L and denoted by \overline{L} .

One can also give a description of the completion \overline{L} of a subspace $L \in \mathbf{K}_{rat}(X)$ purely in terms of the semigroup $\mathbf{K}_{rat}(X)$ (see Theorem 6.2).

Corollary 5.15 (Intersection index and completion). Let $L_1 \in \mathbf{K}_{rat}(X)$ and \overline{L}_1 its completion as defined above. Then for any (n-1)-tuple $L_2, \ldots, L_n \in \mathbf{K}_{rat}(X)$ we have

$$[L_1, L_2, \ldots, L_n] = [\overline{L}_1, L_2, \ldots, L_n].$$

Proof. Follows form Theorem 5.13 and the fact that \overline{L}_1 is finite dimensional and hence can be spanned by L_1 together with a finite number of extra integral elements over L_1 .

Let us say that a subspace $L \in \mathbf{K}_{rat}(X)$ is very big if the Kodaira rational map Φ_L is an embedding restricted to a Zariski open set. We say L is big if L^k is very big for some k > 0.

Theorem 5.16 (A birationally invariant version of Hodge inequality). Let X be an irreducible (possibly singular) surface and let $L_1, L_2 \in \mathbf{K}_{rat}(X)$ be big subspaces. Then we have

$$[L_1, L_2]^2 \ge [L_1, L_1][L_2, L_2].$$

Proof. It follows from the multi-linearity of the intersection index that if we replace each L_i with any power $L_i^{k_i}$ the inequality does not change. Thus it is enough to prove the theorem for very big subspaces, in which case it follows from Theorem 4.27.

Theorem 5.17 (Analogue of the Alexandrov–Fenchel inequality for birationally invariant index). Let X be an irreducible n-dimensional (possibly singular) variety and let $L_1, \ldots, L_n \in \mathbf{K}_{rat}(X)$ be big subspaces. Then the following inequality holds:

$$[L_1, L_2, L_3, \ldots, L_n]^2 \ge [L_1, L_1, L_3, \ldots, L_n][L_2, L_2, L_3, \ldots, L_n].$$

Proof. As above, by the multi-linearity it is enough to prove the theorem for very big subspaces, and the theorem in this case follows from Theorem 4.28. \Box

The same inequalities as in Corollary 4.29 hold for the birationally invariant index.

6. GROTHENDIECK GROUP OF SUBSPACES OF RATIONAL FUNCTIONS AND CARTIER DIVISORS

6.1. Generalities on semigroups of rational functions. Let K be a commutative semigroup (whose operation we denote by multiplication). K is said to have the *cancellation property* if for $x, y, z \in K$, the equality xz = yz implies x = y. Any commutative semigroup K with the cancellation property can be extended to an abelian group G(K) consisting of formal quotients $x/y, x, y \in K$. For $x, y, z, w \in K$ we identify the quotients x/y and w/z, if xz = yw.

Given a commutative semigroup K (not necessarily with the cancellation property), we can get a semigroup with the cancellation property by considering the equivalence classes of a relation \sim on K: for $x, y \in K$ we say $x \sim y$ if there is $z \in K$ with xz = yz. The collection of equivalence classes K/\sim naturally has structure of a semigroup with cancellation property. Let us denote the group of formal quotients of K/\sim again by G(K). It is called the *Grothendieck group of the semigroup* K. The map which sends $x \in K$ to its equivalence class $[x] \in K/\sim$ gives a natural homomorphism $\phi \colon K \to G(K)$.

The Grothendieck group G(K) together with the homomorphism $\phi \colon K \to G(K)$ satisfies the following universal property: for any other group G' and a homomorphism $\phi' \colon K \to G'$, there exists a unique homomorphism $\psi \colon G(K) \to G'$ such that $\phi' = \psi \circ \phi$.

Definition 6.1. For two subspaces $L, M \in \mathbf{K}_{rat}(X)$, we write $L \sim_{rat} M$ if L and M are equivalent as elements of the multiplicative semigroup $\mathbf{K}_{rat}(X)$, that is, if there is $N \in \mathbf{K}_{rat}(X)$ with LN = MN.

From multi-linearity of the intersection index it follows that the intersection index is invariant under the equivalence of subspaces, namely if L_1, \ldots, L_n and $M_1, \ldots, M_n \in \mathbf{K}_{rat}(X)$ are *n*-tuples of subspaces and for each *i*, $L_i \sim_{rat} M_i$ then

$$[L_1,\ldots,L_n]=[M_1,\ldots,M_n]$$

Hence, generalizing the situation in Section 3, one can extend the intersection index to the Grothendieck group of $K_{rat}(X)$. We denote this Grothendieck group by $G_{rat}(X)$.

For $L \in \mathbf{K}_{rat}(X)$ recall that the completion \overline{L} is the collection of all rational functions integral over L (Definition 5.14). The following result describes the completion \overline{L} of a subspace L as the largest subspace equivalent to L (see [ZS, Appendix 4] for a proof).

Theorem 6.2. For $L \in \mathbf{K}_{rat}(X)$, the completion \overline{L} is the largest subspace which is equivalent to L. That is,

- (1) $\overline{L} \sim_{\text{rat}} L$ and
- (2) if for $M \in \mathbf{K}_{rat}(X)$ we have $M \sim_{rat} L$ then $M \subset \overline{L}$.

Theorem 6.2 readily implies that the intersection indices of subspace $L \in \mathbf{K}_{rat}(X)$ and its completion \overline{L} are the same (Corollary 5.15).

Remark 6.3. Let us call a subspace L, complete if $\overline{L} = L$. If L and M are complete subspaces, then LM is not necessarily complete. For two complete subspaces $L, M \in \mathbf{K}_{rat}(X)$, define

$$L * M = \overline{LM}.$$

The collection of complete subspaces together with * is a semigroup with the cancellation property. Theorem 6.2 in fact shows that $L \mapsto \overline{L}$ gives an isomorphism between the quotient semigroup $\mathbf{K}_{rat}(X)/\sim_{rat}$ and the semigroup of complete subspaces (with *).

In analogy with the linear equivalence of divisors, we define the linear equivalence for subspaces of rational functions.

Definition 6.4. Given $L, M \in \mathbf{K}_{rat}(X)$, we say L is *linearly equivalent to* M if there is a rational function which is not identically zero on any irreducible component of X and L = fM. We then write $L \sim_{\text{lin}} M$. For two classes of subspaces $[L], [M] \in \mathbf{K}_{rat}(X)/\sim_{rat}$ we say [L] is *linearly equivalent to* [M] and again write $[L] \sim_{\text{lin}} [M]$ if there are $L' \sim_{rat} L$ and $M' \sim_{rat} M$ such that L' is linearly equivalent to M'.

The following is easy to verify. Part 2 is just Corollary 5.11.

Proposition 6.5. (1) The linear equivalence \sim_{lin} is an equivalence relation on $\mathbf{K}_{\text{rat}}(X)$ which respects the semigroup operation. Similarly, \sim_{lin} is an equivalence relation on the factor semigroup $\mathbf{K}_{\text{rat}}(X)/\sim_{\text{rat}}$ and it respects the semigroup operation. Hence it extends to an equivalence relation on the Grothendieck group $\mathbf{G}_{\text{rat}}(X)$.

(2) The birationally invariant index is preserved under the linear equivalence. and thus induces an intersection index on the factor group $G_{rat}(X)/\sim_{lin}$.

The intersection index $[L_1, \ldots, L_n]_X$ can be computed separately on each irreducible component of the variety X. So without lost of generality we can only consider irreducible varieties.

6.2. Cartier divisor associated to a subspace of rational functions with a regular Kodaira map. A *Cartier divisor* on a projective irreducible variety X is a divisor which can be represented locally as a divisor of a rational function. Any rational function f defines a *principal Cartier divisor* denoted by (f). The Cartier divisors are closed under the addition and form an abelian group which we will denote by Div(X). A dominant morphism $\Phi: X \to Y$ between varieties X and Y gives a pull-back homomorphism $\Phi^*: \text{Div}(Y) \to \text{Div}(X)$. Two Cartier divisors are linearly equivalent if their difference is a principle divisor. The group of Cartier divisors modulo linear equivalence is called the Picard group of X and denoted by Pic(X). One has an intersection theory on Pic(X): for given Cartier divisors D_1, \ldots, D_n on an n-dimensional projective variety there is an intersection index $[D_1, \ldots, D_n]$ which obeys the usual properties (see [Ful]).

Now let us return back to the subspaces of rational functions. For a subspace $L \in \mathbf{K}_{rat}(X)$, in general, the Kodaira map Φ_L is a rational map, possibly not defined everywhere on X.

Definition 6.6. We denote the collection of subspaces $L \in \mathbf{K}_{rat}(X)$ for which the rational Kodaira map $\Phi_L \colon X \dashrightarrow \mathbb{P}(L^*)$ extends to a regular map defined everywhere on X, by $\mathbf{K}_{Cart}(X)$. A subspace $L \in \mathbf{K}_{Cart}(X)$ is called a *subspaces* with regular Kodaira map.

One can verify that the collection $\mathbf{K}_{Cart}(X)$ is closed under the multiplication and under the linear equivalence, i.e., if $L \in \mathbf{K}_{Cart}(X)$ and f is a rational function which is not identically equal to zero on any irreducible component of X, then $fL \in \mathbf{K}_{Cart}(X)$. Moreover, $\Phi_L = \Phi_{fL}$.

Definition 6.7. To a subspace $L \in \mathbf{K}_{Cart}(X)$ there naturally corresponds a Cartier divisor $\mathcal{D}(L)$ as follows: each rational function $h \in L$ defines a hyperplane $H = \{h = 0\}$ in $\mathbb{P}(L^*)$. The divisor $\mathcal{D}(L)$ is the difference of the pull-back divisor $\Phi_L^*(H)$ and the principal divisor (h).

Theorem 6.8. Let X be an irreducible projective variety. Then:

- (1) For any $L \in \mathbf{K}_{Cart}(X)$ the divisor $\mathcal{D}(L)$ is well-defined, i.e., is independent of the choice of a function $h \in L$.
- (2) The map $L \mapsto \mathcal{D}(L)$ is a homomorphism from the semigroup $\mathbf{K}_{Cart}(X)$ to the semigroup Div(X) which respects the linear equivalence.
- (3) Let $\mathbf{G}_{Cart}(X)$ denote the Grothendieck group of the semigroup $\mathbf{K}_{Cart}(X)$. The map $L \mapsto \mathcal{D}(L)$ extends to a homomorphism $\rho: \mathbf{G}_{Cart}(X) \to \text{Div}(X)$.
- (4) The map $L \mapsto \mathcal{D}(L)$ preserves the intersection index, i.e., for $L_1, \ldots, L_n \in \mathbf{K}_{Cart}(X)$ we have

$$[L_1, \ldots, L_n] = [\mathcal{D}(L_1), \ldots, \mathcal{D}(L_n)],$$

where the right-hand side is the intersection index of Cartier divisors.

Proof. Statements 1 and 2 are obvious. Statement 3 follows from 2. Let us prove 4. Since both intersection indices for subspaces and for Cartier divisors are multilinear, it is enough to prove the equality when $L_1 = \cdots = L_n = L$. The divisor $\mathcal{D}(L)$ is linearly equivalent to the pull-back of any hyperplane section in $p(L^*)$. So the self-intersection index of $\mathcal{D}(L)$ is equal to the intersection index of the pull-back of *n*-generic hyperplanes, i.e., $[\mathcal{D}(L), \ldots, \mathcal{D}(L)] = [\Phi_L^*(H_1), \ldots, \Phi_L^*(H_n)]$, where the H_i are arbitrary hyperplanes in $\mathbb{P}(L^*)$. We can choose the hyperplanes H_i in such a way that the divisors $\Phi_L^*(H_i)$ intersect transversally and the intersection points do not belong to the base locus of L as well as the poles of the functions in L. In this case, by the definition, $[L_1, \ldots, L_n]$ is equal to the right-hand side in 4) and the proof of theorem is finished. \Box

Definition 6.9. The subspace $\mathcal{L}(D)$ associated to a Cartier divisor D is the collection of all rational functions f such that the divisor (f) + D is effective (by definition $0 \in L(D)$.)

The following well-known fact can be found in [Har, Chap. 2, Theorem 5.19].

Theorem 6.10. When X is projective $\mathcal{L}(D)$ is finite dimensional.

The next proposition is a direct corollary of the definition.

Proposition 6.11. Let $L \in \mathbf{K}_{Cart}(X)$ and put $D = \mathcal{D}(L)$. Then $L \subset \mathcal{L}(D)$ and $\mathcal{L}(D) \in \mathbf{K}_{Cart}(X)$.

A Cartier divisor D is very ample if the Kodaira map of the space $\mathcal{L}(D)$ gives rise to an embedding of X into the projective space. One verifies that this is equivalent to $\mathcal{D}(\mathcal{L}(D)) = D$. According to the following well-known theorem, the group of Cartier divisors is generated by very ample divisors (see [Laz, Example 1.2.6]).

Theorem 6.12. Let X be a projective variety. Given a very ample Cartier divisor D and a Cartier divisor E, there is an integer N such that for any k > N the divisor $E_k = kD + E$ is a very ample divisor. Thus any Cartier divisor E is the difference of two very ample divisors, namely, $E = E_k - kD$.

For a subspace $L \in \mathbf{K}_{Cart}(X)$ we would like to describe the subspace $\mathcal{L}(\mathcal{D}(L))$. The answer is based on the following theorem. It can be found in slightly different forms in [Har, Chap. 2, Proof of Theorem 5.19] and [ZS, Appendix 4].

Theorem 6.13. Let X be an irreducible projective variety and let $L \in \mathbf{K}_{Cart}(X)$ be such that the Kodaira map $\Phi_L \to \mathbb{P}(L^*)$ is an embedding. Then:

- (1) Every element of $\mathcal{L}(\mathcal{D}(L))$ is integral over L, i.e., $\mathcal{L}(\mathcal{D}(L)) \subset \overline{L}$,
- (2) Moreover if X is normal then $\mathcal{L}(\mathcal{D}(L)) = \overline{L}$.

We use Theorem 6.13 to describe $\mathcal{L}(\mathcal{D}(L))$ in terms of the semigroup $\mathbf{K}_{Cart}(X)$. For $L, M \in \mathbf{K}_{Cart}(X)$ we will write $L \sim_{Cart} M$ if there is $N \in \mathbf{K}_{Cart}(X)$ with LN = MN.

Corollary 6.14. Let X be an irreducible projective variety and $L \in \mathbf{K}_{Cart}(X)$. Also assume that $\Phi_L \colon X \to \mathbb{P}(L^*)$ is an embedding. Then:

- (1) $\mathcal{L}(\mathcal{D}(L)) \sim_{\text{Cart}} L$,
- (2) if $M \sim_{\text{Cart}} L$ then $M \subset \mathcal{L}(\mathcal{D}(L))$.
- (3) Finally, let $L_1, L_2 \in \mathbf{K}_{Cart}(X)$ and assume that Φ_{L_1}, Φ_{L_2} are embeddings. Then $L_1 \sim_{Cart} L_2$ if and only if $\mathcal{L}(\mathcal{D}(L_1)) = \mathcal{L}(\mathcal{D}(L_2))$.

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Proof. (1) Let $f \in \mathcal{L}(\mathcal{D}(L))$. By Theorem 6.19 we know that f is integral over L. So, there are elements $a_i \in L^i$ such that $f^m + a_1 f^{m-1} + \cdots + a_m = 0$. Denote by L(f) the vector space spanned by L and f. Denote by P a space $P = f^{m-1}L + \cdots + L^m$. It is easy to see that: (a) the spaces L(f) and P belong to $\mathbf{K}_{Cart}(X)$, (b) the map $\Phi_{L(f)} \colon X \to PF^*$ is am embedding, (c) the inclusion $fP \subset LP$ holds. From (c) we have LP = L(f)P. Because $P, L(f) \in \mathbf{K}_{Cart}(X)$ we showed that $L \sim_{Cart} L(f)$. Now fix basis f_1, \ldots, f_n for $\mathcal{L}(D)$. Denote by L_1 the space $L(f_1)$. As we proved $L_1 \sim_{Cart} L$ and the Kodaira map Φ_{L_1} is an embedding. Applying the same arguments to $L_2 = L_1(f_2)$ we get that $L_2 \sim_{Cart} L_1 \sim_{Cart} L$ and Φ_{L_2} is an embedding. Continuing this process we see that $L \sim_{Cart} \mathcal{L}(\mathcal{D}(L))$.

(2) If $M \sim_{\text{Cart}} L$ then $\mathcal{D}(M) = \mathcal{D}(L)$ (see Theorem 6.8)). Since $M \subset L(\mathcal{D}(M))$ we have that $M \subset \mathcal{L}(\mathcal{D}(L))$.

Part 3 of the corollary follows from (1) and (2).

The last statement in the corollary shows that the spaces L for which the Kodaira map is an embedding behave especially well with respect to the map $L \mapsto \mathcal{D}(L)$. One easily verifies the following.

Lemma 6.15. Let $P \in \mathbf{K}_{Cart}(X)$ be such that the Kodaira map Φ_P is an embedding. ding. If $M \in \mathbf{K}_{Cart}(X)$ and $P \subset M$, or if $L \in \mathbf{K}_{Cart}(X)$ and M = PL, then Φ_M is also an embedding.

Let X be a projective variety. Consider the group homomorphism ρ from the Grothendieck group $G_{Cart}(X)$ to the group Div(X) (see Theorem 6.8).

Theorem 6.16. For an irreducible projective variety X the homomorphism

 $\rho \colon \boldsymbol{G}_{\operatorname{Cart}}(X) \to \operatorname{Div}(X),$

is an isomorphism which preserves the intersection index.

Proof. By Theorem 6.8 we know that ρ is a homomorphism which preserves the intersection index. The group Div(X) is generated by very ample divisors which belong to the image of $\mathbf{K}_{\text{Cart}}(X)$ under the map ρ (see Theorem 6.12). So the homomorphism ρ is onto. Take two spaces L_1 and L_2 from $\mathbf{K}_{\text{Cart}}(X)$ for which the Kodaira maps Φ_{L_1} , Φ_{L_2} are embeddings. According to the last statement in Corollary 6.14 the map $\rho(L_1) = \rho(L_2)$ if and only if the subspaces L_1 and L_2 define the same element in the Grothendieck group $\mathbf{G}_{\text{Cart}}(X)$. From this and Lemma 6.15 one can see that ρ has no kernel.

Recall that for two subspaces L, M we write $L \sim_{\text{lin}} M$ if there is a rational function f which is not identically equal to zero on any irreducible component of X with L = fM.

Corollary 6.17. For an irreducible projective variety X the isomorphism ρ induces the isomorphism

$$\tilde{\rho}: \mathbf{G}_{\operatorname{Cart}}(X)/\sim_{\operatorname{lin}} \to \operatorname{Pic}(X),$$

which preserves the intersection index.

Remark 6.18. Theorem 6.16 shows that for a projective variety X the Grothendieck group of the semigroup $\mathbf{K}_{Cart}(X)$ can naturally be identified with the group Div(X) of Cartier divisors. From this one can show that the Grothendieck group $\mathbf{G}_{rat}(X)$, of the semigroup $\mathbf{K}_{rat}(X)$, can naturally be identified with the direct limit of the groups Div(Y) of Cartier divisors on projective birational models Y of X.

Remark 6.19. If X is not only projective but also normal then using Theorem 6.13 one proves that: (a) $\mathbf{K}_{Cart}(X)$ is closed under completion, i.e., if $L \in \mathbf{K}_{Cart}(X)$ then $\overline{L} \in \mathbf{K}_{Cart}(X)$ and moreover $L \sim_{Cart} \overline{L}$. (b) Let $L, M \in \mathbf{K}_{Cart}(X)$. Then $L \sim_{rat} M$ if and only if $L \sim_{Cart} M$.

7. Topological and Algebro-Geometric Proofs of Properties of Intersection Index

In this section we provide alternative proofs for the main properties of the birationally invariant intersection index. The proofs are essentially based on differential geometry techniques. These techniques fit into the context of differential geometry in a specially nice way when the variety X is smooth and compact (or more generally if it is normal and complete) and when the subspaces of rational functions $L_i \in \mathbf{K}_{rat}(X)$, appearing in the intersection index, give rise to regular Kodaira maps $\Phi_{L_i}: X \to \mathbb{P}(L_i^*)$. But as we will see the topological arguments are also applicable in the general case. Note that a similar construction allows one to prove the properties of the intersection index (for subspaces of rational functions) using standard intersection theory for Cartier divisors on a complete variety.

We also provide a proof of the Hodge inequality for the birationally invariant index which relies on Hodge theory and other well-known methods of algebraic geometry. In particular, the proof of algebraic analogue of the Alexandrov–Fenchel inequality mostly follows its proof in [Kh1]. (As mentioned in the introduction we recently found an elementary and unusual proof of this inequality; see [KKh1] for a preliminary version.)

We first recall the necessary statements from complex geometry.

All smooth complex varieties have standard orientation coming from the complex structure. Let Y be a complete *n*-dimensional algebraic subvariety in a smooth projective algebraic variety M. Let $Y^{\rm sm}$ be the locus of smooth points of the variety Y. It is possible to apply the results in differential geometry to singular algebraic varieties because of the following: the variety $Y^{\rm sm}$ defines a 2*n*-dimensional cycle in the manifold M.

Theorem 7.1 (see [GH]). For every smooth 2n-form τ on M its integral along the manifold Y^{sm} with its complex orientation is well defined. Moreover, for exact forms τ this integral vanishes.

The complex projective space has a standard Kaehler 2-form. We recall its definition: take a positive definite hermitian form H on a complex vector space L. Then we can define a form $\tilde{\omega}_H$ on $L \setminus \{0\}$ by the formula

$$\tilde{\omega}_H = \frac{\imath}{2\pi} \partial \bar{\partial} \log H.$$

Let $\pi: L \setminus \{0\} \to \mathbb{P}(L)$ be the canonical projection. The following is well-known.

Theorem 7.2 (see [GH]). There exists a unique form ω_H on $\mathbb{P}(L)$ such that $\tilde{\omega}_H = \pi^* \omega_H$. This form ω_H is closed and its cohomology class generates the cohomology ring of $\mathbb{P}(L)$. The integral of ω_H on any projective line $\mathbb{P}^1 \subset \mathbb{P}(L)$ is equal to 1. The form ω_H is the Poincaré dual to any hyperplane in $\mathbb{P}(L)$.

The form ω_H is called the Kähler form on $\mathbb{P}(L)$ associated to the Hermitian form H on L. (The Hermitian form H on L also defines the Fubini–Study metric on $\mathbb{P}(L)$ and the form ω_H can be recovered uniquely from the Fubini–Study metric.) For a one-dimensional space L the form ω_H is equal to zero as $\mathbb{P}(L)$ consists of a single point.

We now go back to our case of interest. Let X be an irreducible n-dimensional quasi-projective variety. A model of the variety X is a complete algebraic variety which is birationally isomorphic to X. For the topological description of the intersection indices of n-tuples of subspaces in the semigroup $\mathbf{K}_{rat}(X)$ we will consider models of the variety X. For different n-tuples of elements of the semigroup $\mathbf{K}_{rat}(X)$ different models may be needed. In particular, when X is normal and projective, and for all the subspaces $L \in \mathbf{K}_{Cart}(X)$ with regular Kodaira map, it suffices to take X itself as a model.

In general, there exists a common model for all the *n*-tuples of subspaces chosen from a fixed finite set. We now describe the construction of this model. Fix a finite sequence L_1, \ldots, L_k of subspaces. For convenience we allow repetition of subspaces in the sequence.

Let Σ be an admissible set for X and the sequence L_1, \ldots, L_k of subspaces from the semigroup $\mathbf{K}_{\mathrm{rat}}(X)$. Let $\Phi_{L_i} \colon X \setminus \Sigma \to \mathbb{P}(L_i)^*$ be the Kodaira map associated to L_i . Let the quasi-projective variety X be embedded in \mathbb{P}^N . Denote the product $\mathbb{P}(L_1^*) \cdots \times \mathbb{P}(L_k^*)$ by $\mathbb{P}(\mathbf{L}^*)$. Consider the mapping $\Phi_{\mathbf{L}} \colon X \setminus \Sigma \to \mathbb{P}(\mathbf{L}^*)$ which is the product of the Kodaira maps Φ_{L_i} . Let $\Gamma \subset \mathbb{P}^N \times \mathbb{P}(\mathbf{L}^*)$ be the graph of this mapping, i.e., Γ is the set of points (x, y_1, \ldots, y_k) , where $x \in X \setminus \Sigma$ and $y_i = \Phi_{L_i}(x), i = 1, \ldots, k$. Define $\overline{\Gamma}$ to be the closure of the graph Γ in $\mathbb{P}^N \times \mathbb{P}(\mathbf{L}^*)$. Let $\rho \colon \overline{\Gamma} \to \mathbb{P}^N$ be the restriction of the projection $\mathbb{P}^N \times \mathbb{P}(\mathbf{L}^*) \to \mathbb{P}^N$ to the complete subvariety $\overline{\Gamma}$. The mapping ρ is a birational isomorphism between the complete variety $\overline{\Gamma}$ and the variety X.

Definition 7.3. The complete variety $\overline{\Gamma} \subset \mathbb{P}^N \times \mathbb{P}(\boldsymbol{L}^*)$ is called the model of the variety X associated to the sequence of spaces L_1, \ldots, L_k .

Lemma 7.4. If X is normal and complete and $L_1, \ldots, L_k \in \mathbf{K}_{Cart}(X)$ are subspaces with regular Kodaira maps, then the model of X corresponding to L_1, \ldots, L_k is isomorphic to X.

Proof. Under the assumptions of the lemma the graph Γ is defined over the whole X. Since X is complete, Γ is closed and thus $\overline{\Gamma} = \Gamma$ is isomorphic to X. \Box

Remark 7.5. Using intersection theory of Cartier divisors on a model $\overline{\Gamma}$ of a variety X corresponding to a sequence L_1, \ldots, L_k of subspaces of rational functions, one can prove all the properties of the intersection index discussed before, for the *n*-tuples L_{i_1}, \ldots, L_{i_n} taken from the sequence L_1, \ldots, L_k .

In the variety $\overline{\Gamma}$ there is a Zariski open subset $W = \rho^{-1}(X \setminus \Sigma)$ isomorphic to $X \setminus \Sigma$. If we identify W with $X \setminus \Sigma$ using the map ρ , then the restriction of the projection $\pi_i \colon \mathbb{P}^N \times \mathbb{P}(\boldsymbol{L}^*) \to \mathbb{P}(L_i^*)$ to W is the Kodaira map Φ_{L_i} .

Choose an arbitrary collection of n subspaces from the sequence L_1, \ldots, L_k . Without loss of generality, assume that it is L_1, \ldots, L_n .

Below we will give an integral formula for the intersection index (see Corollary 7.7).

Recall basic facts from the topology of the product of projective spaces $M = \mathbb{P}^N \times \mathbb{P}(\mathbf{L}^*)$. Since the Kähler form ω_{H_i} on $\mathbb{P}(L_i^*)$ is the Poincaré dual to the hypersurface $P_i \subset \mathbb{P}(L_i^*)$, the form $\pi_i^* \omega_{H_i}$ on M is Poincaré dual to the hypersurface $\pi^{-1}P_i$, and the intersection $Z = \pi_1^{-1}P_1 \cap \cdots \cap \pi_n^{-1}P_n$ is the Poincaré dual to the form $\pi_1^* \omega_{H_1} \wedge \cdots \wedge \pi_n^* \omega_{H_n}$. It means that for an arbitrarily small tubular neighborhood U of the manifold Z equipped with a smooth projection $g: U \to Z$ there is a closed 2n-form Ω_U on the manifold M having the following properties:

- (1) the support of the form Ω_U is contained in the tubular neighborhood U_Z .
- (2) The form Ω_U is cohomologous to the form $\pi_1^* \omega_{H_1} \wedge \cdots \wedge \pi_n^* \omega_{H_n}$.
- (3) Let $g: U \to Z$ be the smooth projection in the definition of the tubular neighborhood U, and let $F_a = g^{-1}a$ be the fiber of this projection over an arbitrary point $a \in Z$, oriented compatible with the natural coorientation of the submanifold Z in M. Then $\int_{F_a} \Omega_U = 1$.

Theorem 7.6. Let L_1, \ldots, L_n be an n-tuple of subspaces taken from a sequence of $k \ge n$ subspaces from $\mathbf{K}_{rat}(X)$. Let $\overline{\Gamma}$ be a model of the variety X associated to this sequence. Suppose that the cycle $Z = \pi_1^{-1}P_1 \cap \cdots \cap \pi_n^{-1}P_n$ does not intersect the singular set O of the variety $\overline{\Gamma}$, and intersects its non-singular part $Y = \overline{\Gamma} \setminus O$ transversally. Then the number $\#(Z \cap Y)$ of intersection points of the cycle Z with the manifold Y is

$$\int_Y \pi_1^* \omega_{H_1} \wedge \cdots \wedge \pi_n^* \omega_{H_n}.$$

Proof. The variety Z does not intersect the closed set O, and hence the set $Z \cap Y$ does not contain the limit points of O. It follows from the transversality condition that the set $Z \cap Y$ is finite. Choose a sufficiently small tubular neighborhood U of the cycle Z so that for every point $a \in Z \cap Y$ the connected component Y_a of the intersection of Y with the closure of the tubular neighborhood \overline{U} defines the same relative cycle in the homology group of the pair $(\overline{U}, \partial \overline{U})$ as the fiber F_a . Then

$$\int_{Y} \pi_1^* \omega_{H_1} \wedge \dots \wedge \pi_n^* \omega_{H_n} = \int_{Y} \Omega_U = \sum_{a \in Z \cap Y} \int_{Y_a} \Omega_U = \#(Z \cap Y),$$

as required.

This theorem not only gives an alternative proof of the well-definedness of the definition of the intersection index $[L_1, \ldots, L_n]$, but also gives an explicit formula for it:

Corollary 7.7. The birationally invariant index $[L_1, \ldots, L_n]$ is well-defined and is equal to

$$[L_1, \ldots, L_n] = \int_Y \pi_1^* \omega_{H_1} \wedge \cdots \wedge \pi_n^* \omega_{H_n}$$
$$= \int_{X \setminus \Sigma} (\pi_1 \circ \rho^{-1})^* \omega_{H_1} \wedge \cdots \wedge (\pi_n \circ \rho^{-1})^* \omega_{H_n}$$

Proof. Every function $f_i \in L_i$ defines a linear functional on the vector space L_i^* , and moreover, a non-zero f_i defines a hyperplane L_{f_i} in L_i^* on which this functional vanishes. Let $P_{f_i} \subset \mathbb{P}(L_i^*)$ be the projectivization of L_{f_i} . By the Bertini theorem there is a Zariski open subset $U \subset L_1 \times \cdots \times L_n$ consisting of $\mathbf{f} = (f_1, \ldots, f_n)$ such that the hyperplanes $P_{f_i} \subset \mathbb{P}(L_i^*)$ have the following properties:

- (1) the cycle $Z = \pi_1^{-1} P_{f_1} \cap \cdots \cap \pi_n^{-1} P_{f_n}$ satisfies the conditions of Theorem 7.6,
- (2) all the intersection points of the cycle Z with the variety $\overline{\Gamma}$ belong to the set $\rho^{-1}(X \setminus \Sigma) \subset \overline{\Gamma}$.

According to the theorem, for $\mathbf{f} \in U$ the system $f_1 = \cdots = f_n = 0$ in $X \setminus \Sigma$ has only non-degenerate roots. Their number does not depend on the choice of the set of equations $\mathbf{f} \in U$ and is equal to $\int_Y \pi_1^* \omega_{H_1} \wedge \cdots \wedge \pi_n^* \omega_{H_n}$. The latter integral is equal to $\int_{\rho^{-1}(X \setminus \Sigma)} \pi_1^* \omega_{H_1} \wedge \cdots \wedge \pi_n^* \omega_{H_n}$ (and hence the last integral is well-defined). This proves the corollary.

The above formula for the index provides a different proof of its multi-linearity. Let L_1 , L_2 be two spaces of regular functions on some algebraic variety and let L_1L_2 be their product. The space L_1L_2 is a factor space of the tensor product $L_1 \otimes L_2$ and hence the space $(L_1L_2)^*$ is a subspace of $(L_1 \otimes L_2)^*$. Denote by $\tau: (L_1L_2)^* \to (L_1 \otimes L_2)^*$ the corresponding embedding. Let H_1 , H_2 be positivedefinite Hermitian forms on the spaces L_1^* , L_2^* and $H_1 \otimes H_2$ be the positive-definite form on $(L_1 \otimes L_2)^*$ whose value on the product $l_1 \otimes l_2$ of two vectors l_1 , l_2 is $H_1(l_1)H_2(l_2)$.

Definition 7.8. We call the form H_1H_2 on the space $(L_1L_2)^*$, induced by the form $H_1 \otimes H_2$ and the embedding $\tau : (L_1L_2)^* \to (L_1 \otimes L_2)^*$, the product of the forms H_1 and H_2 .

Lemma 7.9. Let $L_1, L_2 \in \mathbf{K}_{rat}(X)$. Let H_1, H_2 be positive-definite Hermitian forms on the spaces L_1^*, L_2^* respectively, and let H_1H_2 be their product defined on $(L_1L_2)^*$. Then

$$\ddot{K}_{L_1}^*\omega_{H_1} + \ddot{K}_{L_2}^*\omega_{H_2} = \ddot{K}_{L_1L_2}^*\omega_{H_1H_2}.$$

Proof. Since $\tau \circ \Phi_{L_1L_2} = \Phi_{L_1} \otimes \Phi_{L_2}$, for every $x \in X$ we have $H_1H_2(\Phi_{L_1L_2}(x)) = H_1(\Phi_{L_1}(x))H_2(\Phi_{L_2}(x))$. It follows that

$$\frac{i}{2\pi}\partial\bar{\partial}\log H_1H_2(\Phi_{L_1L_2}(x)) = \frac{i}{2\pi}\partial\bar{\partial}\log H_1(\Phi_{L_1}(x)) + \frac{i}{2\pi}\partial\bar{\partial}\log H_2(\Phi_{L_2}(x)).$$

Corollary 7.10. The index $[L_1, \ldots, L_n]$ is multi-linear. That is, if $L_1 = L'_1 L''_2$, then

 $[L_1, L_2, \ldots, L_n] = [L'_1, L_2, \ldots, L_n] + [L''_1, L_2, \ldots, L_n].$

Proof. Build a model $\overline{\Gamma}$ of the variety X associated to the sequence of subspaces $L'_1, L''_1, L_1, \ldots, L_n$. Let $H'_1, H''_1, H_2, \ldots, H_n$ be Hermitian forms on the spaces $L'_1^*, L''_1^*, L^*_2, \ldots, L^*_n$ respectively. Also let π'_1, π''_1 denote the projections corresponding to the subspaces L'_1, L''_1 respectively. Let $H_1 = H'_1H''_1$ be the product form on L^*_1 . Denote by Y the set of non-singular points on the variety $\overline{\Gamma}$. It follows from the lemma that the restrictions of the forms $\pi_1^*\omega_{H_1}$ and $\pi'_1^*\omega_{H'_1} + \pi''_1^*\omega_{H''_1}$ to the manifold Y coincide. Hence the restrictions to Y of the products of these forms by the form $\pi_2^*\omega_{H_2} \wedge \cdots \wedge \pi_n^*\omega_{H_n}$ also coincide. The claim now follows from the integral formula for the index.

We will need the following corollary from Hodge theory. Let Y be a smooth projective surface. Consider the symmetric form $B(\omega_1, \omega_2) = \int_Y \omega_1 \wedge \omega_2$, defined on the space of real-valued smooth (1, 1)-forms. Also, in the space $H^{1,1}(Y)$, consider the non-negative cone C consisting of the forms ω whose value at each point of the surface Y on each pair of the vectors (v, iv) is non-negative.

Corollary 7.11 (Corollary of the Hodge index theorem). For any two forms $\omega_1, \omega_2 \in C$ the following inequality holds:

$$B^{2}(\omega_{1}, \omega_{2}) \geqslant B(\omega_{1}, \omega_{1})B(\omega_{2}, \omega_{2}).$$

$$(1)$$

Proof. According to the Hodge index theorem, the quadratic form $B(\omega, \omega)$, defined on the (1, 1)-component of the cohomology of the surface Y, is positive-definite on a one-dimensional subspace and negative-definite on its orthogonal compliment. The positive closed (1, 1)-forms lie in a connected component $B(\omega, \omega) \ge 0$. Now (as in the proof of the classical Cauchy–Schwartz inequality) consider the line $\ell =$ $\{t\omega_1 + \omega_2: t \in \mathbb{R}\}$ passing through ω_2 and parallel to ω_1 . The line ℓ does not completely lie outside the positive cone C and hence the quadratic polynomial $Q(t) = B(t\omega_1 + \omega_2, t\omega_1 + \omega_2)$ attains both positive and negative (or possibly zero) values. It follows that the discriminant of Q is non-negative. But discriminant of Q is equal to $4(B(\omega_1, \omega_2)^2 - B(\omega_1, \omega_1)B(\omega_2, \omega_2))$, which proves the inequality (1). \Box

Finally, we recall the following classical theorem about the resolution of singularities for surfaces:

Theorem 7.12 (Resolution of singularities for surfaces). For every complete projective surface $\overline{\Gamma}$ there exists a complete non-singular projective surface Y and a morphism $g: Y \to \overline{\Gamma}$ which is a birational isomorphism between Y and $\overline{\Gamma}$.

Theorem 7.13 (A version of Hodge inequality). Let X be a quasi-projective irreducible surface and $L_1, L_2 \in \mathbf{K}_{rat}(X)$. Then the following inequality holds:

$$[L_1, L_2]^2 \ge [L_1, L_1][L_2, L_2].$$

Proof. Let $\overline{\Gamma}$ be a complete model for the surface X associated to the subspaces L_1, L_2 . Consider the non-singular projective surface Y with the morphism $g: Y \to \overline{\Gamma}$ from Theorem 7.12. Consider the subspaces $F = (\rho \circ g)^* L_1$ and $G = (\rho \circ g)^* L_2$ of rational functions on the surface Y. We have Kodaira maps Φ_F and Φ_G corresponding to these subspaces. Fix Kähler forms $\omega_{H_1}, \omega_{H_2}$ on the spaces $\mathbb{P}(F^*), \mathbb{P}(G^*)$, then we can associate non-negative smooth closed (1, 1)-forms $\omega_1 = (\pi_1 \circ g)^* \omega_{H_1}$ and

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 $\omega_2 = (\pi_2 \circ g)^* \omega_{H_2}$ (on the surface Y) to the subspaces F and G respectively. From the integral formula for the index we have $[F, F] = \int_Y \omega_1 \wedge \omega_1, [F, G] = \int_Y \omega_1 \wedge \omega_2$ and $[G, G] = \int_Y \omega_2 \wedge \omega_2$. Corollary 7.11 now implies that $[F, G]^2 \ge [F, F][G, G]$. But $[F, G] = [L_1, L_2], [F, F] = [L_1, L_1], [G, G] = [L_2, L_2]$, so the theorem is proved.

From the version of Hodge inequality proved above we get an analogue of the Alexandrov–Fenchel inequality for the intersection index (see [Kh1]).

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