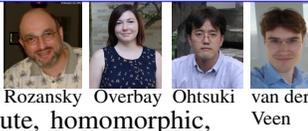


**Cars, Interchanges, Traffic Counters, and some Pretty Darned Good Knot Invariants**

More at ωεβ/APAI

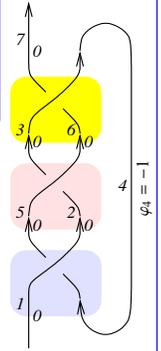


**Abstract.** Reporting on joint work with Roland van der Veen, I'll tell you some stories about  $\rho_1$ , an easy to define, strong, fast to compute, homomorphic, and well-connected knot invariant.  $\rho_1$  was first studied by Rozansky and Overbay [Ro1, Ro2, Ro3, Ov] and Ohtsuki [Oh2], it has far-reaching generalizations, it is elementary and dominated by the coloured Jones polynomial, and I wish I understood it.



**Jones:**

Formulas stay; interpretations change with time.

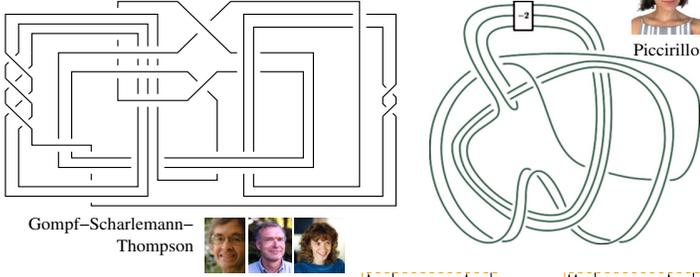


**Common misconception.** Dominated, elementary  $\Rightarrow$  lesser.

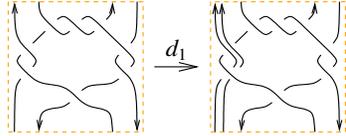
**We seek** strong, fast, homomorphic knot and tangle invariants.

**Strong.** Having a small "kernel".

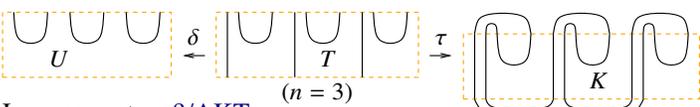
**Fast.** Computable even for large knots (best: poly time).



**Homomorphic.** Extends to tangles and behaves under tangle operations; especially gluings and doublings:



**Why care for "Homomorphic"?** **Theorem.** A knot  $K$  is ribbon iff there exists a  $2n$ -component tangle  $T$  with skeleton as below such that  $\tau(T) = K$  and where  $\delta(T) = U$  is the *untangle*:



Hear more at ωεβ/AKT.

**Acknowledgement.** This work was supported by NSERC grant RGPIN-2018-04350 and by the Chu Family Foundation (NYC).

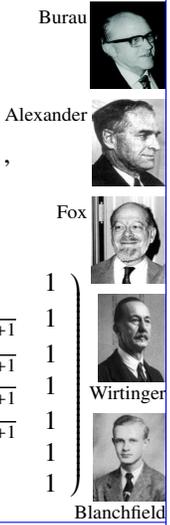
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**Formulas.** Draw an  $n$ -crossing knot  $K$  as on the right: all crossings face up, and the edges are marked with a running index  $k \in \{1, \dots, 2n + 1\}$  and with rotation numbers  $\varphi_k$ . Let  $A$  be the  $(2n + 1) \times (2n + 1)$  matrix constructed by starting with the identity matrix  $I$ , and adding a  $2 \times 2$  block for each crossing:

$$\begin{array}{c}
 s = +1 \qquad s = -1 \\
 \begin{array}{c} j+1 \uparrow \\ i \downarrow \end{array} \begin{array}{c} i+1 \uparrow \\ j \downarrow \end{array} \quad \begin{array}{c} i+1 \uparrow \\ j \downarrow \end{array} \begin{array}{c} j+1 \uparrow \\ i \downarrow \end{array} \quad \longrightarrow \quad \begin{array}{c|cc} A & \text{col } i+1 & \text{col } j+1 \\ \hline \text{row } i & -T^s & T^s - 1 \\ \text{row } j & 0 & -1 \end{array}
 \end{array}$$

Let  $G = (g_{\alpha\beta}) = A^{-1}$ . For the trefoil example, it is:

$$A = \begin{pmatrix} 1 & -T & 0 & 0 & T-1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -T & 0 & 0 & T-1 \\ 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & T-1 & 0 & 1 & -T & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}, \quad G = \begin{pmatrix} 1 & T & 1 & T & 1 & T & 1 \\ 0 & 1 & \frac{1}{T^2-T+1} & \frac{T}{T^2-T+1} & \frac{T}{T^2-T+1} & \frac{T^2}{T^2-T+1} & 1 \\ 0 & 0 & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & 1 \\ 0 & 0 & \frac{1-T}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & 1 \\ 0 & 0 & \frac{1-T}{T^2-T+1} & -\frac{(T-1)T}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$



**Note.** The Alexander polynomial  $\Delta$  is given by

$$\Delta = T^{(-\varphi-w)/2} \det(A), \quad \text{with } \varphi = \sum_k \varphi_k, \quad w = \sum_c s.$$

**Classical Topologists:** This is boring. Yawn.

**Formulas, continued.** Finally, set

$$R_1(c) := s(g_{ji}(g_{j+1,j} + g_{j,j+1} - g_{ij}) - g_{ii}(g_{j,j+1} - 1) - 1/2)$$

$$\rho_1 := \Delta^2 \left( \sum_c R_1(c) - \sum_k \varphi_k (g_{kk} - 1/2) \right).$$

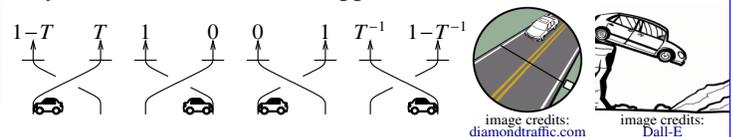
In our example  $\rho_1 = -T^2 + 2T - 2 + 2T^{-1} - T^{-2}$ .

**Theorem.**  $\rho_1$  is a knot invariant. Proof: later.

**Classical Topologists:** Whiskey Tango Foxtrot?

**Cars, Interchanges, and Traffic Counters.**

Cars always drive forward. When a car crosses over a bridge it goes through with (algebraic) probability  $T^s \sim 1$ , but falls off with probability  $1 - T^s \sim 0^*$ . At the very end, cars fall off and disappear. See also [Jo, LTW].



\* In algebra  $x \sim 0$  if for every  $y$  in the ideal generated by  $x$ ,  $1 - y$  is invertible.