(1) Let  $V \subset \mathbb{R}^n$  be a vector subspace of dimension n-1. Let  $N \in \mathbb{R}^n$ be a nonzero vector normal to V. Let  $v_1, \ldots, v_{n-1}$  be a basis of V. We'll say that  $(v_1, \ldots, v_{n-1})$  is a positive basis with respect to the orientation of V induced by N if  $det(N, v_1, \ldots, v_{n-1}) > 0$ .

Prove that this defines a well-defined orientation of V. in other words, suppose  $(u_1, \ldots, u_{n-1})$  be another basis of V.

Prove that  $(u_1, \ldots, u_{n-1})$  and  $(v_1, \ldots, v_{n-1})$  have the same orientation if and only if  $det(N, v_1, \ldots, v_{n-1})$  and  $det(N, u_1, \ldots, u_{n-1})$ have the same sign.

(2) Let  $M = \{x^2 + y^2 + z^2 \le 1\}$  in  $\mathbb{R}^3$  with the orientation coming from the canonical orientation on  $\mathbb{R}^3$  . Consider the induced orientation on  $\partial M$  and find a positive basis of  $T_p \partial M$  at p = (1, 0, 0).

Further, let  $N = S_+^2 = \{(x, y, z) | \text{ such that } x^2 + y^2 + z^2 = 1$ and  $z \ge 0\}$ . Consider the orientation on N coinciding with the orientation on  $S^2 = \partial M$ . Consider  $\partial N$  with the induced orientation from N. Find a positive basis of  $T_p \partial N$  for p = (1, 0, 0).

- (3) Let  $M_1 \subset \mathbb{R}^{n_1}, M_2 \subset \mathbb{R}^{n_2}$  be orientable manifolds without boundary. Prove that  $M_1 \times M_2 \subset \mathbb{R}^{n_1+n_2}$  is orientable.
- (4) Let  $M^k \subset \mathbb{R}^n$  be a  $C^{\infty}$  manifold with boundary. Prove that for any  $p \in \partial M$  there exists an open set  $U \subset \partial M$  containing p on which we can construct a  $C^{\infty}$  unit vector filed N tangent to M such that  $N(x) \perp T_x \partial M$  for any  $x \in U$ .

*Hint*: Take a local parametrization  $f: V \to U$  where  $V \subset H^k$ ,  $U \subset M$  and look at the vector fields  $df_x(e_1), \ldots, df_x(e_k)$ . Apply Gramm-Shmidt to those vector fields.

- (5) Let  $M = \{x^2/9 + y^2/4 + z^2 \le 3\}$  in  $\mathbb{R}^3$ . Consider the induced orien-
- (6) Let M = (w / v + y / 1 + x 2 ≤ 0) in R<sup>3</sup>. Consider the induced often tation on ∂M and find a positive basis of T<sub>p</sub>∂M at p = (3, -2, 1).
  (6) Let M = S<sup>2</sup> = {x<sup>2</sup> + y<sup>2</sup> + z<sup>2</sup> = 1} ⊂ ℝ<sup>3</sup> with the orientation induced from the ball {x<sup>2</sup> + y<sup>2</sup> + z<sup>2</sup> ≤ 1}. Let ω = zdx ∧ dy. Compute ∫<sub>M</sub> ω.