

# MAT1342/MAT464: Assignment I

Due in class Wednesday, January 21st 2009

1. We denote by  $\mathbb{P}^n\mathbb{C}$  the space of complex lines of  $\mathbb{C}^{n+1}$  passing by the origin. In other words,  $\mathbb{P}^n\mathbb{C}$  is the set of equivalence classes of points in  $\mathbb{C}^{n+1} \setminus \{0\}$  with equivalence given by

$$x \sim y \iff \exists \lambda \in \mathbb{C}^* \text{ such that } x = \lambda y.$$

(a) Show that  $\mathbb{P}^n\mathbb{C}$  with its induced topology is a Hausdorff space and show that it is naturally a smooth manifold of (real) dimension  $2n$  by exhibiting an atlas of class  $\mathcal{C}^\infty$ .

(b) Let  $[z_0 : z_1 : z_2] \in \mathbb{P}^2\mathbb{C}$  denote the equivalence class of  $(z_0, z_1, z_2) \in \mathbb{C}^3 \setminus \{0\}$ , where  $z_k = x_k + iy_k \in \mathbb{C}$ . Show that the set

$$\mathcal{Q} = \{[z_0 : z_1 : z_2] \in \mathbb{P}^2\mathbb{C} \mid z_0^2 + z_1^2 + z_2^2 = 0\}$$

is a submanifold of  $\mathbb{P}^2\mathbb{C}$  of dimension 2.

2. Consider the set  $H$  of matrices of the form

$$\begin{pmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{pmatrix}$$

where  $x, y, z \in \mathbb{R}$ .

(a) Show that  $H$  is a Lie group (it is called the Heisenberg group). Determine its Lie algebra and show that its exponential map is a diffeomorphism from its Lie algebra to  $H$ .

(b) Show with a counter example that the exponential map is not always a (global) homeomorphism from the Lie algebra of a Lie group onto this Lie group.

3. The algebra of Quaternions  $\mathbb{H}$  is a non-commutative algebra of dimension 4 over  $\mathbb{R}$ . It admits a basis of 4 elements  $1, i, j, k$  where 1 is the unit satisfying the relations

$$ij = k = -ji, \quad ki = j = -ik, \quad jk = i = -kj, \quad i^2 = j^2 = k^2 = -1.$$

A general element is of the form  $q = q_0 + q_1i + q_2j + q_3k$  where  $q_0, q_1, q_2, q_3$  are real numbers. We denote by

$$\bar{q} := q_0 - q_1i - q_2j - q_3k$$

the conjugate of  $q$ , and by  $|q|$  the norm of  $q$  defined by

$$|q|^2 := \sum_{m=0}^3 q_m^2.$$

Using the basis  $1, i, j, k$ , we can identify  $\mathbb{H}$  with  $\mathbb{R}^4$  as real vector spaces.

(a) Show that the set of unit quaternions defined by<sup>1</sup>

$$\mathbb{S}^3 = \{q \in \mathbb{H} \mid |q| = 1\}.$$

is a Lie group with group law induced by the product of  $\mathbb{H}$ . (*Hint*: Show first that  $|q|^2 = q\bar{q}$  and  $p \cdot q = \bar{q} \cdot \bar{p}$  for  $p, q \in \mathbb{H}$ .)

(b) Describe the Lie algebra and the left invariant vector fields of the Lie group  $\mathbb{S}^3$ . What can you say about the tangent bundle of  $\mathbb{S}^3$ ?

(c) Show that the map

$$q = q_0 + q_1i + q_2j + q_3k \mapsto \begin{pmatrix} q_0 + iq_1 & q_2 + iq_3 \\ -q_2 + iq_3 & q_0 - q_1i \end{pmatrix}$$

induces a diffeomorphism  $\Psi : \mathbb{S}^3 \rightarrow \text{SU}(2)$  which is at the same time a group homomorphism. Thus, as Lie groups,  $\mathbb{S}^3$  and  $\text{SU}(2)$  are equivalent.

(d) Denote by  $\text{Im}(\mathbb{H}) = \{q \in \mathbb{H} \mid q_0 = 0\} \cong \mathbb{R}^3$  the space of imaginary quaternions. Show that  $\mathbb{S}^3$  acts by conjugation on  $\text{Im}(\mathbb{H})$ ,

$$\Phi(q)\xi := q\xi\bar{q}, \quad q \in \mathbb{S}^3, \xi \in \text{Im}(\mathbb{H}).$$

Under the identification  $\text{Im}(\mathbb{H}) \cong \mathbb{R}^3$ , show that this induces a group homomorphism  $\Phi : \mathbb{S}^3 \rightarrow \text{SO}(3)$ .

(e) Show that the map  $\Phi : \mathbb{S}^3 \rightarrow \text{SO}(3)$  is a submersion and an immersion. Show also it is surjective (you may assume  $\text{SO}(3)$  is compact and connected if needed) and that  $\Phi(q_1) = \Phi(q_2)$  if and only if  $q_1 = \pm q_2$ . This shows that  $\mathbb{S}^3 \cong \text{SU}(2)$  is the double cover of the group  $\text{SO}(3)$ . The group  $\mathbb{S}^3 \cong \text{SU}(2)$  is also called the spin group of dimension 3 and is denoted  $\text{Spin}(3)$ .

4. Show that the definition of the differential of a smooth map given in 1.36 of [1] does not depend on the choice of charts.

## REFERENCES

- [1] S. Gallot, D. Hulin, and J. Lafontaine, *Riemannian geometry*, Springer-Verlag, Berlin, 1993.

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<sup>1</sup>The notation is chosen to indicate that under the identification  $\mathbb{H} \cong \mathbb{R}^4$ ,  $\mathbb{S}^3$  corresponds to the sphere of dimension 3.