## MAT 1061: notes on Nonlinear Ground States

We study solutions ${ }^{1} u \in H^{1}\left(\mathbb{R}^{n}\right)$ of the equation

$$
\begin{equation*}
-\Delta u+\lambda u-|u|^{p-2} u=0 \quad \text { in } \mathbb{R}^{n} \tag{1}
\end{equation*}
$$

We will restrict our attention to dimensions $n \geq 3$; similar results hold in dimensions $n=1,2$, with small modifications.

We will study (1) using variational methods. Thus we define the functional

$$
\begin{equation*}
I[u]:=\int_{\mathbb{R}^{n}} \frac{|D u|^{2}}{2}+\lambda \frac{|u|^{2}}{2}-\frac{|u|^{p}}{p} d x . \tag{2}
\end{equation*}
$$

It will be useful to give a name to each of the 3 terms that make up $I$. Thus we use the notation $I_{D}$ for the Dirichlet energy,

$$
I_{D}[u]=\int_{\mathbb{R}^{n}} \frac{|D u|^{2}}{2}
$$

and for $q \geq 1$ we write

$$
I_{q}[u]:=\int_{\mathbb{R}^{n}} \frac{|u|^{q}}{q} d x
$$

so that $I=I_{D}+\lambda I_{2}-I_{p}$.
We will first establish existence of solutions of (1) by a variational argument. We will then go on to establish some interesting properties of the specific solutions found by our variational technique.

## 1. existence

In this section we prove
Theorem 1. For $\Lambda>0$, define

$$
\mathcal{A}_{\Lambda}:=\left\{v \in H^{1}\left(\mathbb{R}^{n}\right): \lambda I_{2}[v]-I_{p}[v]=-\Lambda\right\} .
$$

Then for every $\Lambda>0$, there exists $u \in \mathcal{A}_{\Lambda}$ such that $u$ is positive and radial, and

$$
I_{D}[u]=\min _{v \in \mathcal{A}_{\Lambda}} I_{D}[v] .
$$

Moreover, there exists a number $\Lambda_{*}$ for which every minimizer of $I_{D}$ in $\mathcal{A}_{\Lambda_{*}}$ is a solution of (1) (including in particular the minimizer found above.)

To say that $u$ is radial means that there exists some function $\tilde{u}:[0, \infty) \rightarrow[0, \infty)$ such that $u(x)=\tilde{u}(|x|)$ a.e..

[^0]1.1. some lemmas. We will need the following deep fact from analysis, which we will accept without proof:

Proposition 1 (Symmetrization decreases the Dirichlet energy). Suppose that $u \in$ $L^{p}\left(\mathbb{R}^{n} ; \mathbb{C}\right)$ for some $p$, and that $D u \in L^{2}\left(\mathbb{R}^{n}\right)$. Define the Schwarz symmetrization of $u$ to be the unique nonnegative, radial function in $L^{2}\left(\mathbb{R}^{n}\right)$, denoted $u^{*}$, with the property that

$$
\mathcal{L}^{n}\left(\left\{x \in \mathbb{R}^{n}: u^{*}(x) \geq \lambda\right\}\right)=\mathcal{L}^{n}\left(\left\{x \in \mathbb{R}^{n}: u(x) \geq \lambda\right\}\right)
$$

for every $\lambda \in \mathbb{R}$, and as a result

$$
\left\|u^{*}\right\|_{L^{q}\left(\mathbb{R}^{n}\right)}=\|u\|_{L^{q}\left(\mathbb{R}^{n}\right)}
$$

for every $q \in[1, \infty]$ (where it is possible that both sides equal $+\infty$ for some $q$ ). Then $D u^{*} \in L^{2}$, and

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}\left|D u^{*}\right|^{2} d x \leq \int_{\mathbb{R}^{n}}|D u|^{2} d x \tag{3}
\end{equation*}
$$

Remarks about the proof.
Next, we have the following
Lemma 1. Let $H_{r a d}^{1}\left(\mathbb{R}^{n}\right):=\left\{v \in H^{1}\left(\mathbb{R}^{n}\right): v\right.$ is radial $\}$. Then $H_{r a d}^{1}\left(\mathbb{R}^{n}\right)$ is compactly embedded in $L^{p}\left(\mathbb{R}^{n}\right)$ for every $p \in\left(2,2^{*}\right)$.

The lemma is interesting because Rellich's compactness theorem fails on $\mathbb{R}^{n}$. For example, if $u \in H^{1}\left(\mathbb{R}^{n}\right)$ is any nonzero function and $x_{k}$ is any sequence of points tending to $\infty$, then the sequence $u_{k}(x):=u\left(x-x_{k}\right)$ is bounded in $H^{1}\left(\mathbb{R}^{n}\right)$ but does not have any convergent sequence in $L^{p}\left(\mathbb{R}^{n}\right)$ for any $p$.

Proof. 1. We first claim that if $v \in H_{r a d}^{1}\left(\mathbb{R}^{n}\right)$, then

$$
|x|^{\frac{n-1}{2}}|v(x)| \leq C\|v\|_{L^{2}}\|D v\|_{L^{2}} \quad \text { for } \text { a.e. } x \in \mathbb{R}^{n} \text {. }
$$

To prove this, note if $v \in H_{r a d}^{1}\left(\mathbb{R}^{n}\right)$ is smooth with compact support, then

$$
\begin{aligned}
r^{n-1}|v(r)|^{2} & =-\int_{r}^{\infty} \frac{d}{d s}\left(s^{n-1}|v(s)|^{2}\right) d s \\
& \leq-2 \int_{r}^{\infty} s^{n-1} v(s) v^{\prime}(s) d s \\
& \leq C\left(\int_{r}^{\infty} s^{n-1}|v(s)|^{2} d s\right)^{1 / 2}\left(\int_{r}^{\infty} s^{n-1}\left|v^{\prime}(s)\right|^{2} d s\right)^{1 / 2} \\
& \leq C\|v\|_{L^{2}}\|D v\|_{L^{2}} .
\end{aligned}
$$

Since $C_{c}^{\infty}\left(\mathbb{R}^{n}\right)$ is dense in $H^{1}\left(\mathbb{R}^{n}\right)$, it follows that the claim holds for all $v \in H_{r a d}^{1}$.
2. Now suppose that $\left\{u_{k}\right\} \subset H^{1}\left(\mathbb{R}^{n}\right)$ is a sequence such that $\left\|u_{k}\right\|_{H^{1}} \leq C$. After passing to a subsequence, we may assume that there exists some $u \in H^{1}\left(\mathbb{R}^{n}\right)$ such that

$$
u_{k} \rightharpoonup u \text { weakly in } L^{2}\left(\mathbb{R}^{n}\right), \quad D u_{k} \rightharpoonup D u \text { weakly in } L^{2}\left(\mathbb{R}^{n}\right)
$$

Note that $\|u\|_{H^{1}} \leq \sup _{k}\left\|u_{k}\right\|_{H^{1}} \leq C$ To complete the proof we will show that for $p \in\left(2,2^{*}\right)$ and arbitrary $\varepsilon>0$, there exists some $\ell=\ell(\varepsilon)$ such that $\left\|u_{k}-u\right\|_{L^{p}}<\varepsilon$ for all $k \geq \ell$. Then for $R$ to be chosen,

$$
\begin{aligned}
\left\|u-u_{k}\right\|_{L^{p}} & =\left\|u-u_{k}\right\|_{L^{p}\left(B_{R}\right)}+\left\|u-u_{k}\right\|_{L^{p}\left(\mathbb{R}^{n} \backslash B_{R}\right)} \\
& \leq\left\|u-u_{k}\right\|_{L^{p}\left(B_{R}\right)}+\left\|u-u_{k}\right\|_{L^{2}\left(\mathbb{R}^{n} \backslash B_{R}\right)}^{2 / p}\left\|u-u_{k}\right\|_{L^{\infty}\left(\mathbb{R}^{n} \backslash B_{R}\right)}^{(p-2) / p}
\end{aligned}
$$

Clearly $\left\|u-u_{k}\right\|_{L^{2}\left(\mathbb{R}^{n} \backslash B_{R}\right)}^{2 / p} \leq C$, and in view of Step 1, if $v \in H_{r a d}^{1}$ then

$$
\|v\|_{L^{\infty}\left(\mathbb{R}^{n} \backslash B_{R}\right)} \leq C R^{\frac{1-n}{2}}\|v\|_{H^{1}}
$$

Thus by taking $R$ large enough, we can arrange that

$$
\left\|u-u_{k}\right\|_{L^{2}\left(\mathbb{R}^{n} \backslash B_{R}\right)}^{2 / p}\left\|u-u_{k}\right\|_{L^{\infty}\left(\mathbb{R}^{n} \backslash B_{R}\right)}^{(p-2) / p} \leq \frac{\varepsilon}{2} .
$$

Having fixed $R$, we note that since $B_{R}$ is bounded, Rellich's Compactness Theorem and the weak convergence $u_{k} \rightharpoonup u$ imply that $u_{k} \rightarrow u$ in $L^{p}\left(B_{R}\right)$ for $p<2^{*}$. Thus there exists some $\ell$ such that $\left\|u-u_{k}\right\|_{L^{p}\left(B_{R}\right)}<\frac{\varepsilon}{2}$ if $k \geq \ell$.
1.2. proof of Theorem 1. Using the above results, we present the proof of the theorem.
proof of Theorem 1. 1. Fix $\Lambda>0$, and let $\left\{v_{k}\right\} \subset \mathcal{A}_{\Lambda}$ be a sequence such that

$$
I_{D}\left[v_{k}\right] \rightarrow \inf _{\mathcal{A}_{\Lambda}} I_{D}
$$

Let $u_{k}$ denote the Schwarz symmetrization $v_{k}^{*}$ of $v_{k}$.
It is clear that $u_{k} \in \mathcal{A}_{\Lambda}$, and it follows from Proposition 1 that $I_{D}\left[u_{k}\right] \rightarrow \inf _{\mathcal{A}_{\Lambda}} I_{D}$.
Next, note that for every $v \in \mathcal{A}_{\Lambda}$,

$$
\frac{\lambda}{2}\|v\|_{2}^{2}=\frac{1}{p}\|v\|_{p}^{p}-\Lambda \leq \frac{1}{p}\|v\|_{p}^{p} \leq \frac{1}{p}\left(\|v\|_{2}^{\theta}\|D v\|_{2}^{1-\theta}\right)^{p}
$$

for $\theta$ as defined in (7), see Lemma 2 below. Upon rearranging we find that

$$
\|v\|_{2}^{2-\theta p} \leq C\|D v\|_{2}^{(1-\theta) p} .
$$

The definition of $\theta$ implies that $2-\theta p=2 p \frac{1-\theta}{2^{*}}>0$, so it follows that $\|v\|_{2} \leq C\|D v\|_{2}^{\alpha}$ for some $\alpha>0$, for $v \in \mathcal{A}_{\Lambda}$.

It follows that $\left\{u_{k}\right\}$ is bounded in $H^{1}\left(\mathbb{R}^{n}\right)$.
2. Next, in view of Lemma 1, we can pass to a subsequence (still labelled $\left\{u_{k}\right\}$ ) such that

$$
\begin{equation*}
u_{k} \rightharpoonup u \text { weakly in } L^{2}, \quad D u_{k} \rightharpoonup D u \text { weakly in } L^{2}, \text { and } \quad u_{k} \rightarrow u \text { strongly in } L^{p} . \tag{4}
\end{equation*}
$$

Upon passing to a further subsequence if necessary, we can also assume that $u_{k} \rightarrow u$ a.e. in $\mathbb{R}^{n}$. Each $u_{k}$ is nonnegative and radial, so the same properties are inherited by $u$.
3. We next show that $u \in \mathcal{A}_{\Lambda}$ It follows from (4) that

$$
\begin{aligned}
\int|u|^{2} & \leq \liminf _{k} \int\left|u_{k}\right|^{2} \\
\int|D u|^{2} & \leq \liminf _{k} \int\left|D u_{k}\right|^{2}=\inf _{\mathcal{A}_{\Lambda}} I_{D} \\
\int|u|^{p} & =\lim _{k} \int\left|u_{k}\right|^{p} .
\end{aligned}
$$

Since each $u_{k}$ belongs to $\mathcal{A}_{\Lambda}$, we deduce that

$$
-\lambda I_{2}[u]+I_{p}[u] \geq \underset{k}{\liminf }\left(-\lambda I_{2}\left[u_{k}\right]+I_{p}\left[u_{k}\right]\right)=\Lambda
$$

Suppose toward a contradiction that strict inequality holds. Then there exists some $a \in(0,1)$ such that $a u \in \mathcal{A}_{\Lambda}$, and clearly $I_{D}[a u]=a^{2} I_{D}[u]<\inf _{\mathcal{A}_{\Lambda}} I_{D}$, which is impossible. Thus $u \in \mathcal{A}_{\Lambda}$.

We conclude that $u$ minimizes $I_{D}$ in $\mathcal{A}_{\Lambda}$, as required.
4. next, we know that the Euler-Lagrange equation for the constrained variational problem satisfied by $u$ is

$$
-\Delta u=\alpha\left(-\lambda u+|u|^{p-2} u\right)
$$

where $\alpha$ is a Lagrange multiplier. Then Lemma 3 proved below (see in particular (20)) implies that there exists a constant $c_{n, p}$ depending only on $n$ and $p$, such that

$$
\int|u|^{p} d x=c_{n, p} \lambda \int|u|^{2} d x .
$$

Since $u \in \mathcal{A}_{\Lambda}$, it follows that

$$
\begin{equation*}
\Lambda=-\frac{\lambda}{2} \int|u|^{2}+\frac{1}{p} \int|u|^{p}=\left(\frac{c_{n, p}}{p}-\frac{1}{2}\right) \lambda \int|u|^{2}=\left(\frac{1}{p}-\frac{1}{2 c_{n, p}}\right) \int|u|^{p} . \tag{5}
\end{equation*}
$$

In addition, Lemma 3 also implies that

$$
\alpha=\frac{\int|D u|^{2}}{\int\left(-\lambda|u|^{2}+|u|^{p}\right)} .
$$

Then it follows from (5) that the Lagrange multiplier $\alpha$ depends only on $\Lambda$ (even if there is more than one minimizer in $\mathcal{A}_{\Lambda}$ ). Thus we will write $\alpha(\Lambda)$ to indicate the unique Lagrange multiplier associated with minimizing in $\mathcal{A}_{\Lambda}$.

Finally, we wish to adjust $\Lambda$ so that the corersponding Lagrange mutliplier $\alpha(\Lambda)$ equals 1 . To do this, let us define a map $\delta_{a}: H^{1}\left(\mathbb{R}^{n}\right) \rightarrow H^{1}\left(\mathbb{R}^{n}\right)$ by $\delta_{a} u(x)=u(a x)$, $a>0$. Then by a change of variables,

$$
\left\|\delta_{a} u\right\|_{L^{q}}^{q}=a^{-n}\|u\|_{L^{q}}^{q} \quad I_{D}\left[\delta_{a} u\right]=a^{2-n} I_{D}[u]
$$

for every $u \in H^{1}\left(\mathbb{R}^{n}\right)$ and every $a>0$. It is clear that $\delta_{a}$ is invertible, and it follows that $\delta_{a}$ is a bijection of $\mathcal{A}_{\Lambda}$ onto $\mathcal{A}_{a^{-n} \Lambda}$, and that $\inf _{\mathcal{A}_{a^{-n} \Lambda}} I_{D}=\alpha^{2-n} \inf _{\mathcal{A}_{\Lambda}} I_{D}$. We conclude that

$$
\alpha\left(a^{-n} \Lambda\right)=a^{2} \alpha(\Lambda) .
$$

This implies that there is a unique $\Lambda_{*}$ such that $\alpha\left(\Lambda_{*}\right)=1$, which completes the proof.

## 2. A DIFFERENT EXISTENCE PROOF

In this section we give an alternative argument in which we again find solutions of (1) via a different variational problem.

First we recall
Lemma 2. If $v \in W^{1, q}\left(\mathbb{R}^{n}\right)$ for $q<n$, then $v \in L^{s}\left(\mathbb{R}^{n}\right)$ for all $s \in\left(q, q^{*}\right)$, and in addition

$$
\begin{equation*}
\|v\|_{L^{s}\left(\mathbb{R}^{n}\right)} \leq C\|v\|_{L^{q}\left(\mathbb{R}^{n}\right)}^{\theta}\|D v\|_{L^{q}\left(\mathbb{R}^{n}\right)}^{1-\theta} \tag{6}
\end{equation*}
$$

where $\theta$ is defined by

$$
\begin{equation*}
\frac{1}{s}=\frac{\theta}{q}+\frac{1-\theta}{q^{*}} . \tag{7}
\end{equation*}
$$

The proof is an exercise. Inequality (6) is sometimes called the Sobolev-NirenbergGagliardo inequality. It implies that if we define

$$
G[v]:=\frac{\|v\|_{L^{2}\left(\mathbb{R}^{n}\right)}^{\theta}\|D v\|_{L^{2}\left(\mathbb{R}^{n}\right)}^{1-\theta}}{\|v\|_{L^{p}\left(\mathbb{R}^{n}\right)}}
$$

then $G[v] \geq C^{-1}$ for every $v \in H^{1}\left(\mathbb{R}^{n}\right) \backslash\{0\}$. (Here $p$ is the same number appearing in (1), so that $2<p<2^{*}$, and $\theta$ is as in Lemma 6.)

The next theorem shows that at least some solutions of (1) minimize $G[\cdot]$, which means that they are extremal for the Sobolev-Nirenberg-Gagliardo inequality.
Theorem 2. There exists a nonnegative radial function $u \in H^{1}\left(\mathbb{R}^{n}\right)$ such that

$$
\begin{equation*}
G[u] \leq G[v] \quad \text { for all } v \in H^{1}\left(\mathbb{R}^{n}\right) \backslash\{0\} . \tag{8}
\end{equation*}
$$

Moreover, if $u$ is any minimizer of $G$, then

$$
\begin{equation*}
-\alpha \Delta u+\beta u-\gamma|u|^{p-2} u=0 \tag{9}
\end{equation*}
$$

for positive constants $\alpha, \beta, \gamma$. Finally, there exists a minimizer of $G$ that solves (1).
Proof. 1. First, it is easy to check that for any $v \in H^{1}\left(\mathbb{R}^{n}\right)$ and any $a, b>0$, if we define $v_{a, b}(x):=b v(a x)$, then $G\left[v_{a, b}\right]=G[v]$. Indeed, this follows from noting that

$$
\left\|v_{a, b}\right\|_{L^{q}}=b a^{-\frac{n}{q}}\|v\|_{L^{q}} \quad \text { for every } q, \quad\left\|D v_{a, b}\right\|_{L^{2}}=b a^{1-\frac{n}{2}}\|D v\|_{L^{2}\left(\mathbb{R}^{n}\right)}
$$

together with some arithmetic. These identities also imply that, given any nonzero $v \in H^{1}\left(\mathbb{R}^{n}\right)$, we can choose $a, b$ such that $\left\|v_{a, b}\right\|_{L^{2}}=\left\|D v_{a, b}\right\|_{L^{2}}=1$.
2. let $\left\{v_{k}\right\} \subset H^{1}\left(\mathbb{R}^{n}\right) \backslash\{0\}$ be a sequence such that

$$
G\left[v_{k}\right] \rightarrow \inf _{H^{1} \backslash\{0\}} G .
$$

For each $k$, we let $u_{k}:=\left(v_{k}^{*}\right)_{a, b}$, for $a, b$ chosen so that $\left\|u_{k}\right\|_{L^{2}}=\left\|D u_{k}\right\|_{L^{2}}=1$. (That is, $u_{k}$ is obtained from $v_{k}$ by first symmetrizing as in Proposition 1, and then by rescaling as in Step 1 above.) It follows that $G\left[u_{k}\right]=G\left[v_{k}^{*}\right] \leq G\left[v_{k}\right]$, so that $\left\{u_{k}\right\}$ is still a minimizing sequence.

Then owing to Lemma 1, we can pass to a subsequence (still labelled $\left\{u_{k}\right\}$ ) such that
$u_{k} \rightharpoonup u$ weakly in $L^{2}, \quad D u_{k} \rightharpoonup D u$ weakly in $L^{2}$, and $\quad u_{k} \rightarrow u$ strongly in $L^{p}$,
for every $p \in\left(2,2^{*}\right)$. Upon passing to a further subsequence if necessary, we can also assume that $u_{k} \rightarrow u$ a.e. in $\mathbb{R}^{n}$. Each $u_{k}$ is nonnegative and radial, so the same properties are inherited by $u$.

Because of (10), standard weak lowersemicontinuity arguments imply that (8) holds.
3. A calculation reveals that $(9)$ is the Euler-Lagrange equation for $G$, with

$$
\alpha=\frac{1-\theta}{\|D u\|_{L^{2}}^{2}}, \beta=\frac{\theta}{\|u\|_{L^{2}}^{2}}, \gamma=\frac{1}{\|u\|_{L^{p}}^{p}} .
$$

4. It follows from Step 1 that if $u$ is a minimizer, then so is $u_{a, b}$. Thus, starting with the minimizer found in Step 2 above, we can select $a, b$ so for the associated constants $\alpha, \beta, \gamma$, one has $\beta / \alpha=\lambda$ and $\gamma / \alpha=1$. This is a minimizer of $G$ that is also a solution of (1).

## 3. PROPERTIES OF SOLUTIONS

In this section we give some further properties of solutions of (1) and related equations, some with proofs and some without.

Proposition 2 (regularity and decay). Assume that $u \in H^{1}\left(\mathbb{R}^{n}\right)$ is a weak solution of

$$
\begin{equation*}
-\Delta u+a u-b|u|^{p-2} u=0 \quad \text { in } \mathbb{R}^{n} \tag{11}
\end{equation*}
$$

Then:
a. For every $q \in[2, \infty)$, there exists a constant $C$, depending on $n, p, q$ and $\|u\|_{H^{1}}$, such that

$$
u \in W^{3, q}\left(\mathbb{R}^{n}\right), \quad \text { and }\|u\|_{W^{3, q}} \leq C
$$

In particular, $\left|D^{\alpha} u\right| \rightarrow 0$ uniformly as $|x| \rightarrow \infty$ for all $|\alpha| \leq 2$.
b. There exist $C, \varepsilon>0$ such that

$$
e^{\varepsilon|x|}(|u(x)|+|D u(x)|) \leq C
$$

for all $x \in \mathbb{R}^{n}$.
The proof of Proposition 2 uses the Calderon-Zygmund estimates. The version of these estimates that is most convenient for our purposes states that for $1<p<\infty$ and $a>0$, there exists a constant $C$ (depending on $p, a$ and $n$, such that if $u \in$ $H^{1}\left(\mathbb{R}^{n}\right)$ and $-\Delta u+a u=f \in L^{q}\left(\mathbb{R}^{n}\right)$, then

$$
\begin{equation*}
u \in W^{2, q}\left(\mathbb{R}^{n}\right), \quad \text { and }\|u\|_{W^{2, q}} \leq C\|f\|_{L^{q}} \tag{12}
\end{equation*}
$$

We assume this result, and we sketch the
proof of Proposition 2. 1. Let $u$ solve (11).
Recall that $2<p<2^{*}$, so that $1<2^{*} /\left(2^{*}-1\right)<2^{*} /(p-1)<2^{*}$. By the Sobolev embedding theorem

$$
\left\||u|^{p-2} u\right\|_{2^{*} /(p-1)}=\|u\|_{2^{*}}^{p-1} \leq C\|u\|_{H^{1}}^{p-1}
$$

Then (11) and the Calderon-Zygmund estimate (12) imply that

$$
\begin{equation*}
u \in W^{2,2^{*} /(p-1)}, \text { with } \quad\|u\|_{W^{2,2^{*} /(p-1)}} \leq C\|u\|_{H^{1}}^{p-1} \tag{13}
\end{equation*}
$$

Since $2^{*} /(p-1)>2$, we have gained regularity.
Note that if we know that $u \in W^{2, q}$ for $q<n / 2$, then almost exactly the same argument, using the Sobolev embedding $W^{2, q} \hookrightarrow L^{q^{* *}}$ and the Calderon-Zygmund estimate, implies that

$$
\begin{equation*}
u \in W^{2, q^{* *} /(p-1)}, \text { with }\|u\|_{W^{2, q^{* *} /(p-1)}} \leq C\|u\|_{W^{2, q}}^{p-1} \tag{14}
\end{equation*}
$$

Here $q^{* *}=\left(q^{*}\right)^{*}$, where ( $)^{*}$ denotes the Sobolev exponent for (), so that $\frac{1}{q^{* *}}=\frac{1}{q}-\frac{2}{n}$, or equivalently $q^{* *}=\frac{n q}{n-2 q}$. One can easily check that if $q \geq q_{0}=2^{*} /(p-1)$ then there exists some $\alpha>1$ (depending on $p$ and $n$ ) such that $q^{* *} /(p-1)>\alpha q$. Thus by starting from (13) and iterating (14) a finite number of times, one finds that $u \in W^{2, q}$ for some $q>n / 2$, which implies that $u \in L^{\infty}$. Then $|u|^{p-1} u$ belongs to $L^{q}$ for every $q \in[2, \infty)$, and (12) implies that $u \in W^{2, q}$ for every $q \in[2, \infty)$.
2. To get higher regularity, we argue as follows: multiply (11) by $v_{x_{i}}$ for some $v \in H^{1}\left(\mathbb{R}^{n}\right)$ and some $i$. Then after integrating by parts and using Step 1 , we find that $w:=u_{x_{i}}$ satisfies

$$
\int D w \cdot D v+a w v-b\left(|u|^{p-2} u\right)_{x_{i}} v=0
$$

Since this holds for every $v \in H^{1}$, we conclude that $w$ is a weak solution of

$$
-\Delta w+a w=b\left(|u|^{p-2} u\right)_{x_{i}} .
$$

From Step 1 we deduce that the right-hand side belongs to $L^{q}$ for every $q \in[2, \infty)$. Hence (12) implies that $w \in W^{2, q}$ for the same $q$. This in turn implies that $u \in W^{3, q}$ for the same range of $q$, and so $u \in W^{2, \infty}$, and moreover the second derivatives of $u$ are $C^{0, \gamma}$ for every $\gamma<1$.
(Note that by continuing in this fashion. we can easily show tat that $u \in W^{k, q}$ for every positive integer $k$ and for all $q \in[u, \infty)$, so that in fact $u$ is $C^{\infty}$.)
3. Fix some multiindex $\alpha$ with $|\alpha| \leq 2$. Since $D^{\alpha} u$ is $C^{0,1 / 2}$, one check that given any $\varepsilon>0$, there exists $\delta>0$ such that

$$
\text { if } \int_{B_{1}(x)}\left|D^{\alpha} u\right|^{2}<\delta, \quad \text { then }\left|D^{\alpha} u(x)\right| \leq \varepsilon
$$

(Perhaps the easiest way to see this is to prove the contrapositive; see a similar argument in Step 6 below.) Then we can select $R$ so large that

$$
\int_{\mathbb{R}^{n} \backslash B_{R}(0)}\left|D^{\alpha} u\right|^{2}<\delta .
$$

It follows that $\left|D^{\alpha} u(x)\right|<\varepsilon$ for all $|x| \leq R+1$. Thus $\left|D^{\alpha} u(x)\right| \rightarrow 0$ uniformly as $|x| \rightarrow \infty$.

This completes the proof of part a of the Proposition.
4. We now start the proof of $\mathbf{b}$. For convenience we normalize (1) by assuming that $a=b=1$; the general case follows by a small modification to our arguments,, or by rescaling.

For $\sigma>0$, let $\eta_{\sigma}(x):=e^{\frac{|x|}{1+\sigma|x|}}$. This is a bounded, Lipschitz function. Since $u$ is a solution of (11),

$$
\begin{equation*}
\int D u \cdot D\left(u \eta_{\sigma}\right)+\int u^{2} \eta_{\sigma}=\int|u|^{p} \eta_{\sigma} . \tag{15}
\end{equation*}
$$

Elementary estimates, using the fact (easy to check) that $\left|D \eta_{\sigma}(x)\right| \leq\left|\eta_{\sigma}(x)\right|$ for all $x$, show that

$$
D u \cdot D\left(u \eta_{\sigma}\right) \geq \eta_{\sigma}|D u|^{2}-|u||D u|\left|D \eta_{\sigma}\right| \geq \frac{1}{2} \eta_{\sigma}|D u|^{2}-\frac{1}{2} \eta_{\sigma} u^{2}
$$

everywhere in $\mathbb{R}^{n}$. So (15) implies that

$$
\begin{equation*}
\int \eta_{\sigma}\left(|D u|^{2}+u^{2}\right) \leq 2 \int|u|^{p} \eta_{\sigma} . \tag{16}
\end{equation*}
$$

5. Now in view of Step 3, there exists $R>0$ such that $|u|^{p-2} \leq \frac{1}{4}$ for $|x| \geq R$. As a result,

$$
\int|u|^{p} \eta_{\sigma} \leq \int_{B_{R}(0)}|u|^{p} \eta_{\sigma}+\frac{1}{4} \int_{\mathbb{R}^{n} \backslash B_{R}(0)}|u|^{2} \eta_{\sigma}
$$

By combining this with (16) we find that

$$
\int \eta_{\sigma}\left(|D u|^{2}+u^{2}\right) \leq 8 \int_{B_{R}(0)}|u|^{p} \eta_{\sigma} \leq 8 \int_{B_{R}(0)} e^{|x|}|u|^{p} .
$$

Now we let $\sigma \rightarrow 0$. The Monotone Convergence Theorem then yields

$$
\int_{\mathbb{R}^{n}} e^{|x|}\left(|D u|^{2}+u^{2}\right) \leq 8 \int_{B_{R}(0)} e^{|x|}|u|^{p}<\infty
$$

6. Let $f:=|D u|^{2}+u^{2}$. It follows from part a of the Proposition that $f$ is Lipschitz continuous. Let $L$ denote the Lipschitz constant. Then for every $x, y \in \mathbb{R}^{n}$,

$$
f(x) \geq \frac{1}{2} f(y) \quad \text { if } \quad|x-y| \leq f(y) / 2 L
$$

As a result, for every $y \in \mathbb{R}^{n}$,

$$
\int e^{|x|} f(x) \geq \frac{f(y)}{2} \int_{\{x:|x-y| \leq f(y) / 2 L\}} e^{|x|} d x
$$

And clearly $e^{|x|} \geq e^{|x|-\frac{f(y)}{2 L}}$ in $\{x:|x-y| \leq f(y) / 2 L\}$. Since $f$ is bounded, this implies that

$$
\int_{\{x:|x-y| \leq f(y) / 2 L\}} e^{|x|} d x \geq c\left(\frac{f(y)}{2 L}\right)^{n} e^{|x|-\frac{f(y)}{2 L}} \geq c\left(\frac{f(y)}{2 L}\right)^{n} e^{|x|}
$$

By combining all these inequalities, we conclude that

$$
f(y)^{n+1} \leq C e^{-|x|}
$$

for some constant $C$ (depending on $u$ ). This implies conclusion $\mathbf{b}$ (when $\mathrm{a}=\mathrm{b}=1$ ).

Lemma 3. Suppose that $u \in H^{1}\left(\mathbb{R}^{n}\right)$ solves

$$
\begin{equation*}
-\Delta u+a u-b|u|^{p-2} u=0 \quad \text { in } \mathbb{R}^{n} \tag{17}
\end{equation*}
$$

for some $a>0$ and $b \in \mathbb{R}$. Then

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}|D u|^{2} d x+a \int_{\mathbb{R}^{n}}|u|^{2} d x=b \int_{\mathbb{R}^{n}}|u|^{p} d x \tag{18}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{n-2}{2} \int_{\mathbb{R}^{n}}|D u|^{2} d x+a \frac{n}{2} \int_{\mathbb{R}^{n}}|u|^{2} d x=b \frac{n}{p} \int_{\mathbb{R}^{n}}|u|^{p} d x \tag{19}
\end{equation*}
$$

Proof. 1. Since $u$ solves (1),

$$
\int D u \cdot D v+a u v-b|u|^{p-2} u v=0
$$

for every $v \in H^{1}\left(\mathbb{R}^{n}\right)$. We deduce (18) by substituting $u$ for $v$.
2. To prove (19), we multiply both sides of (17) by $x \cdot D u$ and integrate to obtain

$$
-\int_{\mathbb{R}^{n}} \Delta u(x \cdot D u)+a \int_{\mathbb{R}^{n}} u(x \cdot D u)=b \int_{\mathbb{R}^{n}}|u|^{p-2} u(x \cdot D u) .
$$

We consider each term separately.
2a. One can check that

$$
\begin{aligned}
\Delta u(x \cdot D u) & =\sum_{i, j} u_{x_{i} x_{i}} u_{x_{j}} x_{j} \\
& =\sum_{i, j}\left(u_{x_{i}} u_{x_{j}} x_{j}\right)_{x_{i}}-\frac{1}{2} \sum_{j}\left(|D u|^{2} x_{j}\right)_{x_{j}}+\frac{n-2}{2}|D u|^{2} .
\end{aligned}
$$

(Simply expand the right-hand side.) The regularity and decay results proved above then imply that

$$
\begin{aligned}
\int_{\mathbb{R}^{n}} \Delta u(x \cdot D u) & =\lim _{R \rightarrow \infty} \int_{B_{R}} \Delta u(x \cdot D u) \\
& =\lim _{R \rightarrow \infty} \int_{B_{R}} \sum_{i, j}\left(u_{x_{i}} u_{x_{j}} x_{j}\right)_{x_{i}}-\frac{1}{2} \sum_{j}\left(|D u|^{2} x_{j}\right)_{x_{j}}+\frac{n-2}{2}|D u|^{2} \\
& =\frac{n-2}{2} \int_{\mathbb{R}^{n}}|D u|^{2}+\lim _{R \rightarrow \infty} \int_{\partial B_{R}} \sum_{i, j}\left(u_{x_{i}} u_{x_{j}} x_{j}\right) \nu_{i}-\frac{1}{2} \sum_{j}\left(|D u|^{2} x_{j}\right) \nu_{j} d \sigma \\
& =\frac{n-2}{2} \int_{\mathbb{R}^{n}}|D u|^{2} .
\end{aligned}
$$

2b. Similarly

$$
u(x \cdot D u)=\sum_{i} u x_{i} u_{x_{i}}=\sum_{i} \frac{1}{2} x_{i}\left(u^{2}\right)_{x_{i}}=\sum_{i} \frac{1}{2}\left(x_{i} u^{2}\right)_{x_{i}}-\frac{n}{2}|u|^{2}
$$

which implies that $\int_{\mathbb{R}^{n}} u(x \cdot D u)=-\int_{\mathbb{R}^{n}} \frac{n}{2}|u|^{2}$.

2c. And in exactly the same way,

$$
|u|^{p-2} u(x \cdot D u)=\sum_{i} \frac{1}{p} x_{i}|u|_{x_{i}}^{p}=\sum_{i} \frac{1}{p}\left(x_{i}|u|^{p}\right)_{x_{i}}-\frac{n}{p}|u|^{p},
$$

so that $\int_{\mathbb{R}^{n}}|u|^{p-2} u(x \cdot D u)=-\int_{\mathbb{R}^{n}} \frac{n}{p}|u|^{p}$. By combining these facts, we arrive at (19).

Remark 1. a slightly different way of carrying out the above computations starts from the fact that (17) is the Euler-Lagrange equation for the a functional involving a Lagrangian $L(D u, u)=\frac{1}{2}|D u|^{2}+\frac{a}{2}|u|^{2}-\frac{b}{p}|u|^{p}$ that does not depend on $x$ (and hence exhibits "symmetry with respect to translations in the $x_{j}$ variable, for $j=1, \ldots, n$." Thus we know on general ground that solutions of (17) have conservation laws associated to these symmetries. Concretely, in this case one can check that for any smooth function $u$,

$$
\left(-\Delta u+a u-b|u|^{p-2} u\right) u_{x_{i}}=\left[\sum_{j}\left(-u_{x_{i}} u_{x_{j}}\right)_{x_{j}}\right]+\frac{1}{2}\left(|D u|^{2}\right)_{x_{i}}+\left(\frac{|u|^{2}}{2}-\frac{|u|^{p}}{p}\right)_{x_{i}} .
$$

Thus the right-hand side equals zero for any smooth solution of (17). This can be thought of as a "conservation law", since the right-hand side is entirely in divergence form. One can obtain (19) by multiplying this conservation law

$$
\left[\sum_{j}\left(-u_{x_{i}} u_{x_{j}}\right)_{x_{j}}\right]+\frac{1}{2}\left(|D u|^{2}\right)_{x_{i}}+\left(\frac{|u|^{2}}{2}-\frac{|u|^{p}}{p}\right)_{x_{i}}=0
$$

by $x_{i}$, summing from $i=1, \ldots, n$ and integrating by parts. On some level of course this is exactly the same argument.

Note that Lemma 3 implies that

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}|D u|^{2} d x=b\left(\frac{n}{2}-\frac{n}{p}\right) \int_{\mathbb{R}^{n}}|u|^{p} d x=a n \frac{p-2}{2 p-n p+2 n} \int_{\mathbb{R}^{n}}|u|^{2} d x \tag{20}
\end{equation*}
$$

Next we state
Theorem 3 (symmetry and uniqueness). If $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is a positive solution of (1), then there exists some $x_{0} \in \mathbb{R}^{n}$ such that $x \mapsto u\left(x+x_{0}\right)$ is radial.

Moreover, there is a unique positive, radial solution $u_{0}: \mathbb{R}^{n} \rightarrow(0, \infty)$ of (1).
Thus every positive solution $u$ of (1) has the form $u(x)=u_{0}\left(x-x_{0}\right)$.
The proof that every positive solution is radial uses a sophisticated form of the "method of moving planes". An easier example of the method of moving planes can be found in Evans, Section 9.5.2. A separate ingredient in the proof of Theorem 3 is a result establishing uniqueness for the radial problem.

We are interested in least-energy solutions of (1), and so we define $\mathcal{G}:=\left\{u \in H^{1}\left(R^{n}\right): u\right.$ solves (1), and $I[u] \leq I[v]$ if $v \in H^{1}\left(R^{n}\right)$ is any other solution of (1) $\}$ A solution of (1) is sometimes called a nonlinear bound state, and a solution $u \in \mathcal{G}$ is called a nonlinear ground state.

Using the above one can prove

Theorem 4. $\mathcal{G}$ is nonempty, and in fact
(21) $u \in \mathcal{G} \Longleftrightarrow u$ minimizes $I_{D}$ in $\mathcal{A}_{\Lambda_{*}}$

$$
\begin{equation*}
\Longleftrightarrow u(x)= \pm u_{0}\left(x-x_{0}\right) \quad \text { for some } x_{0} \in \mathbb{R}^{n} \tag{22}
\end{equation*}
$$

$\Longrightarrow u$ minimizes $G[\cdot]$.
where $\mathcal{A}_{\Lambda_{*}}$ denotes the set defined in Theorem 1.
The proof of this theorem uses all the results described above, but no additional ingredients.


[^0]:    ${ }^{1}$ It turns out that every weak solution is in fact $C^{\infty}$, so we will mostly not distinguish carefully between solutions and weak solutions, except when it is necessary.

