

Stochastic differential equations

$\sigma(x, t)$, $b(x, t)$ mble

Definition

A stochastic process X_t is a solution of a stochastic differential equation

$$dX_t = b(X_t, t)dt + \sigma(X_t, t)dB_t, \quad X_0 = x_0$$

on $[0, T]$ if X_t is progressively measurable with respect to \mathcal{F}_t , $\int_0^T |b(X_t, t)|dt < \infty$, $\int_0^T |\sigma(X_t, t)|^2 dt < \infty$ a.s. and

$$X_t = x_0 + \int_0^t b(X_s, s)ds + \int_0^t \sigma(X_s, s)dB_s \quad 0 \leq t \leq T$$

The main point is that $\sigma(\omega, t) = \sigma(X_t, t)$, $b(\omega, t) = b(X_t, t)$

If $B(t)$ is a d -dimensional Brownian motion and $f(t, x)$ is a function on $[0, \infty) \times \mathbf{R}^d$ which has one continuous derivative in t and two continuous derivatives in x , then Ito's formula reads

$$df(t, B(t)) = \frac{\partial f}{\partial t}(t, B(t))dt + \nabla f(t, B(t)) \cdot dB(t) + \frac{1}{2} \Delta f(t, B(t))dt.$$

Bessel process ($d = 2$)

Let $B_t = (B_t^1, B_t^2)$ be 2d Brownian motion starting at 0,

$$r_t = |B_t| = \sqrt{(B_t^1)^2 + (B_t^2)^2}.$$

By Ito's lemma,

$$dr_t = \frac{B_t^1}{|B_t|} dB_t^1 + \frac{B_t^2}{|B_t|} dB_t^2 + \frac{1}{2} \frac{1}{|B_t|} dt.$$

This is *not* a stochastic differential equation.

$$Y(t) = \int_0^t \frac{B^1}{|B|} dB^1 + \int_0^t \frac{B^2}{|B|} dB^2$$

Let $f(t, y)$ be a smooth function Use Itô's lemma. Intuitively

$$df(t, Y_t) = \partial_t f dt + \partial_y f dY + \frac{1}{2} \partial_y^2 f (dY)^2$$

$$\begin{aligned} (dY)^2 &= \left(\frac{B^1}{|B|} dB^1 + \frac{B^2}{|B|} dB^2 \right)^2 \\ &= \left(\frac{B^1}{|B|} \right)^2 (dB^1)^2 + 2 \frac{B^1 B^2}{|B|^2} dB^1 dB^2 + \left(\frac{B^2}{|B|} \right)^2 (dB^2)^2 \\ &= dt \end{aligned}$$

$$\begin{aligned} f(t, Y_t) &= f(0, Y_0) + \int_0^t (\partial_t f + \frac{1}{2} \partial_y^2 f)(s, Y_s) ds \\ &\quad + \int_0^t \partial_y f \frac{B^1}{|B|} dB^1 + \int_0^t \partial_y f \frac{B^2}{|B|} dB^2 \end{aligned}$$

Itô's lemma

$$dX_t = \sigma(t, X_t)dB_t + b(t, X_t)dt$$

$$f(t, X_t) = f(0, X_0) + \int_0^t \left\{ \partial_s f(s, X_s) + \mathcal{L}f(s, X_s) \right\} ds \\ + \int_0^t \sum_{i,j=1}^d \sigma_{ij}(s, X_s) \frac{\partial}{\partial X_i} f(s, X_s) dB_s^j$$

$$\mathcal{L}f(t, x) = \frac{1}{2} \sum_{i,j=1}^d a_{ij}(t, x) \frac{\partial^2 f}{\partial X_i \partial X_j}(t, x) + \sum_{i=1}^d b_i(t, x) \frac{\partial f}{\partial X_i}(t, x)$$

$$a_{ij} = \sum_{k=1}^d \sigma_{ik} \sigma_{jk} \quad a = \sigma \sigma^T$$

$$dr_t = \frac{B^1}{|B|} dB^1 + \frac{B^2}{|B|} dB^2 + \frac{1}{2} \frac{1}{|B|} dt = dY_t + \frac{1}{2} r_t^{-1} dt$$

$$\begin{aligned} f(t, Y_t) &= f(0, Y_0) + \int_0^t (\partial_t f + \frac{1}{2} \partial_y^2 f)(s, Y_s) ds \\ &\quad + \int_0^t \partial_y f \frac{B^1}{|B|} dB^1 + \int_0^t \partial_y f \frac{B^2}{|B|} dB^2 \end{aligned}$$

In particular $e^{\lambda Y_t - \lambda^2 t/2}$ is a martingale

So Y_t is a Brownian motion.

Therefore

$$dr_t = dY_t + \frac{1}{2} r_t^{-1} dt$$

is a stochastic differential equation for the new Brownian motion Y_t

Itô's lemma

$$f(t, X_t) - f(0, X_0) = \int_0^t \left\{ \partial_s + \mathcal{L} \right\} f(s, X_s) ds + \int_0^t \nabla f(s, X_s) \cdot \sigma dB_s$$

Proof

$$\begin{aligned} &= \sum_i f(t_{i+1}, X_{t_{i+1}}) - f(t_i, X_{t_i}) \\ &= \sum_i \frac{\partial f}{\partial t}(t_i, X_{t_i})(t_{i+1} - t_i) + \nabla f(t_i, X_{t_i}) \cdot (X_{t_{i+1}} - X_{t_i}) \\ &\quad + \frac{1}{2} \sum_{j,k=1}^d \frac{\partial^2 f}{\partial X_j \partial X_k}(t_i, X_{t_i})(X_{t_{i+1}}^j - X_{t_i}^j)(X_{t_{i+1}}^k - X_{t_i}^k) \\ &\quad + \text{higher order terms} \end{aligned}$$

Proof continued

$$\sum_i \frac{\partial f}{\partial t}(t_i, X_{t_i})(t_{i+1} - t_i) \rightarrow \int_0^t \frac{\partial f}{\partial t}(s, X_s) ds$$

$$\sum_i \nabla f(t_i, X_{t_i}) \cdot (X_{t_{i+1}} - X_{t_i})$$

$$= \sum_i \nabla f(t_i, X_{t_i}) \cdot \left(\int_{t_i}^{t_{i+1}} \sigma(s, X_s) dB_s \right) \rightarrow \int_0^t \nabla f \cdot \sigma dB$$

$$+ \sum_i \nabla f(t_i, X_{t_i}) \cdot \left(\int_{t_i}^{t_{i+1}} b(s, X_s) ds \right) \rightarrow \int_0^t \nabla f \cdot b ds$$

$$\sum_i \frac{\partial^2 f}{\partial x_j \partial x_k}(t_i, X_{t_i})(X_{t_{i+1}}^j - X_{t_i}^j)(X_{t_{i+1}}^k - X_{t_i}^k) \rightarrow \int_0^t \frac{\partial^2 f}{\partial x_j \partial x_k}(s, X_s) a_{jk}(s, X_s) ds$$

Proof continued

To show the last convergence, ie

$$\sum_i g(t_i, X_{t_i})(X_{t_{i+1}}^j - X_{t_i}^j)(X_{t_{i+1}}^k - X_{t_i}^k) \rightarrow \int_0^t g(s, X_s) a_{jk}(s, X_s) ds$$

$$\begin{aligned} Z(t_i, t_{i+1}) &= \left(\int_{t_i}^{t_{i+1}} \sum_l \sigma_{jl}(s, X_s) dB_s^l \right) \left(\int_{t_i}^{t_{i+1}} \sum_m \sigma_{km}(s, X_s) dB_s^m \right) \\ &\quad - \int_{t_i}^{t_{i+1}} \sum_l \sigma_{jl} \sigma_{kl}(s, X_s) ds \end{aligned}$$

$$E[|Z(t_i, t_{i+1})|^2] = \mathcal{O}((t_{i+1} - t_i)^2)$$

Proof continued

$$\sum_i g(t_i, X_{t_i}) E\left[\int_{t_i}^{t_{i+1}} a_{jk}(s, X_s) ds\right] \rightarrow \int_0^t g(s, X_s) a_{ij}(s, X_s) ds$$

$$E\left[\left(\sum_i g(t_i, X_{t_i}) Z(t_i, t_{i+1})\right)^2\right] = \sum_{i,j} E[g(t_i, X_{t_i}) Z(t_i, t_{i+1}) g(t_j, X_{t_j}) Z(t_j, t_{j+1})]$$

$$i < j \quad E[E[g(t_i, X_{t_i}) Z(t_i, t_{i+1}) g(t_j, X_{t_j}) Z(t_j, t_{j+1}) \mid \mathcal{F}_{t_j}]] = 0$$

$$\begin{aligned} i = j \quad & E[E[g^2(t_i, X_{t_i}) Z^2(t_i, t_{i+1}) \mid \mathcal{F}_{t_i}]] \\ & = E[g^2(t_i, X_{t_i}) E[Z^2(t_i, t_{i+1}) \mid \mathcal{F}_{t_i}]] \\ & = \mathcal{O}((t_{i+1} - t_i)^2) \end{aligned}$$

$$f(t, X_t) - f(0, X_0) - \int_0^t \left\{ \partial_s + \mathcal{L} \right\} f(s, X_s) ds = \int_0^t \nabla f(s, X_s) \cdot \sigma dB_s$$

$$\mathcal{L} = \frac{1}{2} \sum_{i,j=1}^d a_{ij}(t, x) \frac{\partial^2}{\partial x_i \partial x_j} + \sum_{i=1}^d b_i(t, x) \frac{\partial}{\partial x_i} = \text{generator}$$

$M_t = f(t, X_t) - \int_0^t \left\{ \partial_s + \mathcal{L} \right\} f(s, X_s) ds$ is a martingale

$$0 = E[f(t, X_t) - f(s, X_s) - \int_s^t \left\{ \partial_u + \mathcal{L} \right\} f(u, X_u) du \mid \mathcal{F}_s]$$

$$= \int f(t, y) p(s, x, t, y) dy - f(s, x)$$

$$- \int_s^t \int \left\{ \partial_u + \mathcal{L} \right\} f(u, y) p(s, x, u, y) dy du, \quad X_s = x$$

For any f ,

$$\begin{aligned} 0 &= \int f(t, y) p(s, x, t, y) dy - f(s, x) \\ &\quad - \int_s^t \int \left\{ \partial_u + \mathcal{L} \right\} f(u, y) p(s, x, u, y) dy du \end{aligned}$$

Fokker-Planck (Forward) Equation

$$\begin{aligned} \frac{\partial}{\partial t} p(s, x, t, y) &= \frac{1}{2} \sum_{i,j=1}^d \frac{\partial^2}{\partial y_i \partial y_j} (a_{i,j}(t, y) p(s, x, t, y)) \\ &\quad - \sum_{i=1}^d \frac{\partial}{\partial y_i} (b_i(t, y) p(s, x, t, y)) \\ &= L_y^* p(s, x, t, y) \end{aligned}$$

$$\lim_{t \downarrow s} p(s, x, t, y) = \delta(y - x).$$

Kolmogorov (Backward) Equation

$$\begin{aligned} -\frac{\partial}{\partial s} p(s, x, t, y) &= \frac{1}{2} \sum_{i,j=1}^d a_{ij}(s, x) \frac{\partial^2 p(s, x, t, y)}{\partial x_i \partial x_j} \\ &\quad + \sum_{i=1}^d b_i(s, x) \frac{\partial p(s, x, t, y)}{\partial x_i} \\ &= L_x p(s, x, t, y) \end{aligned}$$

$$\lim_{s \uparrow t} p(s, x, t, y) = \delta(y - x).$$

Proof.

$f(x)$ smooth

$$-\frac{\partial}{\partial s}u = L_s u \quad 0 \leq s < t \quad u(t, x) = f(x)$$

Ito's formula: $u(s, X(s))$ martingale up to time t

$$u(s, x) = E_{s,x}[u(s, X(s))] = E_{s,x}[u(t, X(t))] = \int f(z)p(s, x, t, z)dz$$

Let $f_n(z)$ smooth functions tending to $\delta(y - z)$. We get in the limit that p satisfy the backward equations. □

Example. Brownian motion $d = 1$

$$\mathcal{L} = \frac{1}{2} \frac{\partial^2}{\partial x^2}$$

$$\text{Forward} \quad \frac{\partial p(s, x, t, y)}{\partial t} = \frac{1}{2} \frac{\partial^2 p(s, x, t, y)}{\partial y^2}, \quad t > s$$

$$p(s, x, s, y) = \delta(y - x)$$

$$\text{Backward} \quad - \frac{\partial p(s, x, t, y)}{\partial s} = \frac{1}{2} \frac{\partial^2 p(s, x, t, y)}{\partial x^2}, \quad s < t,$$

$$p(t, x, t, y) = \delta(y - x)$$

Example. Ornstein-Uhlenbeck Process

$$\mathcal{L} = \frac{\sigma^2}{2} \frac{\partial^2}{\partial x^2} - \alpha x \frac{\partial}{\partial x}$$

$$\text{Forward} \quad \frac{\partial p(s, x, t, y)}{\partial t} = \frac{1}{2} \frac{\partial^2 p(s, x, t, y)}{\partial y^2} + \frac{\partial}{\partial y} (\alpha y p(s, x, t, y)), \quad t > s,$$

$$p(s, x, s, y) = \delta(y - x)$$

$$\text{Backward} \quad -\frac{\partial p(s, x, t, y)}{\partial s} = \frac{1}{2} \frac{\partial^2 p(s, x, t, y)}{\partial x^2} - \alpha x \frac{\partial p(s, x, t, y)}{\partial x}, \quad s < t,$$

$$p(t, x, t, y) = \delta(y - x)$$

Existence and Uniqueness Theorem

$\sigma : \mathbb{R}^d \times [0, T] \rightarrow \mathbb{R}^{d \times d}$, $b : \mathbb{R}^d \times [0, T] \rightarrow \mathbb{R}^d$ be Borel measurable, $\exists A < \infty$,

$$\|\sigma(x, t)\| + |b(x, t)| \leq A(1 + |x|) \quad x \in \mathbb{R}^d, 0 \leq t \leq T$$

and *Lipschitz*;

$$\|\sigma(x, t) - \sigma(y, t)\| + |b(x, t) - b(y, t)| \leq A|x - y|.$$

$x_0 \in \mathbb{R}^d$ indep of B_t , $E[|x_0|^2] < \infty$.

Then there exists a unique solution X_t on $[0, T]$ to

$$dX_t = b(X_t, t)dt + \sigma(X_t, t)dB_t, \quad X_0 = x_0$$

and $E[\int_0^T |X_t|^2 dt] < \infty$.

Uniqueness means that if X_t^1 and X_t^2 are two solutions then

$$P(X_t^1 = X_t^2, 0 \leq t \leq T) = 1$$

Proof of Uniqueness

Suppose X_t^1 and X_t^2 are solutions

$$X_t^1 - X_t^2 = \int_0^t (b(X_s^1, s) - b(X_s^2, s)) ds + \int_0^t (\sigma(X_s^1, s) - \sigma(X_s^2, s)) dB_s + x_0^1 - x_0^2$$

$$E[|X_t^1 - X_t^2|^2] \leq 4E\left[\left|\int_0^t (b(X_s^1, s) - b(X_s^2, s)) ds\right|^2\right] + 4E\left[\left|\int_0^t (\sigma(X_s^1, s) - \sigma(X_s^2, s)) dB_s\right|^2\right] + 4E[|x_0^1 - x_0^2|^2]$$

$$E\left[\left|\int_0^t (b(X_s^1, s) - b(X_s^2, s)) ds\right|^2\right] \leq A^2 \int_0^t E[|X_s^1 - X_s^2|^2] ds$$

$$E\left[\int_0^t |\sigma(X_s^1, s) - \sigma(X_s^2, s)|^2 ds\right] = E\left[\int_0^t (\sigma(X_s^1, s) - \sigma(X_s^2, s))^2 ds\right] \leq A^2 \int_0^t E[|X_s^1 - X_s^2|^2] ds$$

Call $\phi(t) = E[|X_t^1 - X_t^2|^2]$

$$\phi(t) \leq 8A^2 \int_0^t \phi(s) ds + 4\phi(0)$$

$$\Phi(t) = \int_0^t \phi(s) ds$$

$$(e^{-8A^2 t} \Phi(t))' = (\Phi'(t) - 8A^2 \Phi(t))e^{-8A^2 t} \leq 4\phi(0)e^{-8A^2 t}$$

$$e^{-8A^2 t} \Phi(t) \leq 4\phi(0)$$

$$\phi(t) \leq 8A^2 \Phi(t) + 4\phi(0) \leq 8e^{8A^2 t} \phi(0)$$

$$E[|X_t^1 - X_t^2|^2] \leq 8e^{8A^2 t} E[|x_0^1 - x_0^2|^2]$$

For each $0 \leq t \leq T$, $X_t^1 = X_t^2$ a.s. so $X_t^1 = X_t^2$ for all rational $t \in [0, T]$ a.s. By continuity this implies that $X_t^1 = X_t^2$ for all $t \in [0, T]$ a.s.

Proof of Existence

$$X_0(t) \equiv x_0$$

$$X_n(t) = x_0 + \int_0^t \sigma(s, X_{n-1}(s)) dB(s) + \int_0^t b(s, X_{n-1}(s)) ds$$

$$E\left[\sup_{0 \leq t \leq T} |X_n(t) - X_{n-1}(t)|^2 \right]$$

Doob's inequality

$$\leq 4E\left[\int_0^T \|\sigma(s, X_{n-1}(s)) - \sigma(s, X_{n-2}(s))\|^2 ds \right]$$

$$+ TE\left[\int_0^T |b(s, X_{n-1}(s)) - b(s, X_{n-2}(s))|^2 ds \right]$$

$$\leq C \int_0^T E[|X_{n-1}(s) - X_{n-2}(s)|^2] ds$$

$$\leq CTE\left[\sup_{0 \leq t \leq T} |X_{n-1}(t) - X_{n-2}(t)|^2 \right]$$

Proof.

$$E\left[\sup_{0 \leq t \leq T} |X_n(t) - X_{n-1}(t)|^2\right] \leq CTE\left[\sup_{0 \leq t \leq T} |X_{n-1}(t) - X_{n-2}(t)|^2\right]$$

$$E\left[\sup_{0 \leq t \leq T} |X_n(t) - X_{n-1}(t)|^2\right] \leq \frac{(CT)^n}{n!}$$

$$P\left(\sup_{0 \leq t \leq T} |X_n(t) - X_{n-1}(t)| > \frac{1}{2^n}\right) \leq 2^{2n} E\left[\sup_{0 \leq t \leq T} |X_n(t) - X_{n-1}(t)|^2\right]$$

summable

$$\text{Borel - Cantelli} \Rightarrow P\left(\sup_{0 \leq t \leq T} |X_n(t) - X_{n-1}(t)| > \frac{1}{2^n} \text{ i.o.}\right) = 0.$$

Hence for almost every ω , $X_n(t) = X_0(t) + \sum_{j=0}^{n-1} (X_{j+1}(t) - X_j(t))$ converges uniformly on $[0, T]$ to a limit $X(t)$ which solves the required stochastic integral equation □

Lipschitz condition is *not* necessary

Theorem

Let $d = 1$ and

$$\begin{aligned} |b(t, x) - b(t, y)| &\leq C|x - y| \\ |\sigma(t, x) - \sigma(t, y)| &\leq C|x - y|^\alpha, \quad \alpha \geq 1/2 \end{aligned}$$

Then there exists a solution of $dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t$ and it is unique

But you do need *some* regularity

$\sigma(x) = \text{sgn}(x)$ and $dX = \sigma(B)dB$ Not a stochastic differential equation

But X is a Brownian motion $dB = \sigma(B)dX$ *is* a stochastic differential equation

But also $d(-B) = \sigma(-B)dX$ so no uniqueness