

Strong Markov property of Brownian motion

$B_t, t \geq 0$ be a Brownian motion with respect to $\mathcal{F}_t, t \geq 0$

τ a bounded stopping time.

$$\tilde{B}_t = B_{t+\tau} - B_\tau.$$

Then \tilde{B}_t is a Brownian motion independent of \mathcal{F}_τ .

In other words, Brownian motion starts afresh at every stopping time.

Proof.

optional stopping + martingale characterization of Brownian motion □

Reflection Principle

For all $x > 0$, $t \geq 0$,

$$P\left(\sup_{0 \leq s \leq t} B_s \geq x\right) = 2P(B_t \geq x)$$

In particular $\sup_{0 \leq s \leq t} B_s \stackrel{d}{=} |B_t|$

Proof.

$$\tau_x = \inf\{t \geq 0 : B_t \geq x\}$$

$$P\left(\sup_{0 \leq s \leq t} B_s \geq x\right) = P(B_t \geq x) + P\left(\sup_{0 \leq s \leq t} B_s \geq x, B_t < x\right) = P(\tau_x \leq t)$$

$$P\left(\sup_{0 \leq s \leq t} B_s \geq x, B_t < x\right) = P(\tau_x \leq t, B_{\tau_x+(t-\tau_x)} - B_{\tau_x} < 0) = \frac{1}{2}P(\tau_x \leq t)$$



$$P(\tau_X \leq t) = 2 \int_x^\infty \frac{1}{\sqrt{2\pi t}} e^{-\frac{y^2}{2t}} dy$$

Differentiate in t to see that τ_X has density

$$\begin{aligned} f_X(t) &= \frac{1}{\sqrt{2\pi}} \left(-\frac{1}{t^{3/2}} \int_x^\infty e^{-\frac{y^2}{2t}} dy + \frac{1}{t^{5/2}} \int_x^\infty y^2 e^{-\frac{y^2}{2t}} dy \right) \\ &= \frac{x}{\sqrt{2\pi t^3}} e^{-\frac{x^2}{2t}} \end{aligned}$$

In particular $E[\tau_X] = \infty$

$$\tau_X = \inf\{t \geq 0 : x^{-1} B_t = 1\} = \inf\{x^2 t : \tilde{B}_t = x^{-1} B_{x^2 t} = 1\} = x^2 \tilde{\tau}_1$$

Note τ_X has stationary, independent increments, i.e. it is a **Lévy process**

Law of the iterated logarithm (Khinchine)

$B_t, t \geq 0$ Brownian motion

$$\limsup_{t \rightarrow 0} \frac{B_t}{\sqrt{2t \log \log t^{-1}}} = 1 \quad \text{a.s.}$$

Proof

To simplify expressions let $h(t) = \sqrt{2t \log \log t^{-1}}$

Step 1. Is to show $\limsup_{t \rightarrow 0} \frac{B_t}{h(t)} \leq 1$ a.s.

Applying Doob's inequality to the martingale $\exp\{aX_t - a^2 t/2\}$

$$P\left(\sup_{0 \leq s \leq t} \{B_s - as/2\} \geq \lambda\right) \leq e^{-a\lambda}$$

Let $\epsilon > 0$ $0 < \theta < 1$ $t_n = \theta^n$ $a_n = (1 + \epsilon)\theta^{-n}h(\theta^n)$ $\lambda_n = h(\theta^n)/2$

Borel-Cantelli: $P(\sup_{0 \leq s \leq t_n} B_s \geq a_n t_n/2 + \lambda_n \text{ i.o.}) = 0$

Proof of LIL

Step 2. Is to show $\limsup_{t \rightarrow 0} \frac{B_t}{h(t)} \geq 1$ a.s.

Let $\epsilon > 0$ $\theta = \epsilon^2/16$

$$A_n = \{B_{\theta^n} - B_{\theta^{n+1}} \geq (1 - \sqrt{\theta})h(\theta^n)\} \quad A_n \text{ independent}$$

If $\sum P(A_n) = \infty$ by Borel-Cantelli lemma $P(A_n \text{ i.o.}) = 1$
i.e. with probability one there are infinitely many n for which

$$B_{\theta^n} \geq (1 - \sqrt{\theta})h(\theta^n) + B_{\theta^{n+1}}$$

Step 1 $\Rightarrow \forall n \geq N, B_{\theta^{n+1}} < 2h(\theta^{n+1}) \stackrel{\text{symmetry}}{\Rightarrow} B_{\theta^{n+1}} > -2h(\theta^{n+1})$

so $B_{\theta^n} \geq (1 - \sqrt{\theta})h(\theta^n) - 2h(\theta^{n+1}) \geq (1 - \epsilon)h(\theta^n)$

so $\limsup_{t \rightarrow 0} B_t/h(t) \geq (1 - \epsilon)$

Hence it suffices to prove that $\sum P(A_n) = \infty$

Proof of LIL

$$\begin{aligned} P(B_{\theta^n} - B_{\theta^{n+1}} \geq (1 - \sqrt{\theta})h(\theta^n)) &= \int_{\frac{(1-\sqrt{\theta})h(\theta^n)}{\sqrt{\theta^n - \theta^{n+1}}}}^{\infty} \frac{e^{-\frac{x^2}{2}}}{\sqrt{2\pi}} dx \\ &\geq C(\log n)^{-1/2} n^{-\frac{(1-\sqrt{\theta})^2}{1-\theta}} \end{aligned}$$

by

$$\int_a^{\infty} \frac{e^{-\frac{x^2}{2}}}{\sqrt{2\pi}} dx \geq \frac{1}{a + a^{-1}} \frac{e^{-\frac{a^2}{2}}}{\sqrt{2\pi}}$$

Since $(1 - \sqrt{\theta})^2 = 1 - 2\sqrt{\theta} + \theta < 1 - \theta$, the series diverges

QED

Prop

$|\{t : B_t = 0\}| = 0$ and $\{t : B_t = 0\}$ is perfect

Proof.

Recall *perfect* = *closed* and *any point is a limit point*
closed is obvious

$$E\left[\int_0^1 1_{\{t: B_t=0\}}(s) ds\right] = \int_0^1 P(0, 0, s, \{0\}) ds = 0 \quad \Rightarrow \quad |\{t : B_t = 0\}| = 0$$

LIL $\Rightarrow 0$ is a limit point of $\{t : B_t = 0\}$

$B_s = 0 \Rightarrow B_{t+s} - B_s$ Brownian motion so s is a limit point of $\{t : B_{t+s} - B_s = 0\}$



so $\{t : B_t = 0\}$ is like a Cantor set. $\{t : B_t = 0\} = \bigcup_{n=1}^{\infty} I_n$, I_n disjoint intervals

B_t , $t \in I_n$ is called a **Brownian excursion**

If f_t is a continuous function on $[0, \infty)$ and $\tau_x = \inf\{t : f_t \geq x\}$ then τ_x is continuous on $[a, b]$ iff $\sup_{0 \leq s \leq t} f_t$ is strictly increasing on $[\tau_a, \tau_b]$

Prop

$\{\tau_x\}_{x \geq 0}$ is not continuous in any interval

Proof.

LIL \Rightarrow

$$P(\tau_x \text{ continuous on } [a, b]) = 0$$

Hence

$$P\left(\bigcup_{a < b \in \mathbb{Q}} \{\tau_x \text{ continuous on } [a, b]\}\right) = 0$$



So $\{\tau_x\}_{x \geq 0}$ is a non-decreasing, discontinuous Lévy process

Another way to compute the distribution of τ_x , $x \geq 0$

$M_t = e^{\lambda B_t - \frac{1}{2}\lambda^2 t}$ is a martingale

Optional stopping $\Rightarrow E[e^{\lambda B_{\min(\tau_x, B)} - \frac{1}{2}\lambda^2 \min(\tau_x, B)}] = 1$

BCT $\Rightarrow E[e^{\lambda B_{\tau_x} - \frac{1}{2}\lambda^2 \tau_x}] = 1, \quad \lambda \geq 0$

so $E[e^{-\lambda \tau_x}] = e^{-\sqrt{2\lambda}x}, \quad \lambda \geq 0$

In particular if τ_x and $\tilde{\tau}_y$ are independent then $\tau_x + \tilde{\tau}_y \stackrel{\text{dist}}{=} \tau_{x+y}$

Stable laws

X has stable distribution if for each n there is $0 < \alpha \leq 2$ and μ_n such that if X_1, X_2, \dots are iid with $X_i \stackrel{\text{dist}}{=} X$ then

$$\frac{X_1 + \dots + X_n - \mu_n}{n^{1/\alpha}} \stackrel{\text{dist}}{=} X$$

Examples: Gaussian $\alpha = 2$; Cauchy $\alpha = 1$; τ_1 $\alpha = 1/2$

Subordinator means X_t non-decreasing (so it can be used as a **time**).

τ_x , $x \geq 0$ is a **stable subordinator** eg. $B_{\tau_x} = x$

$\tau = \inf\{t \geq 0 : B_t \text{ hits } b + mt\}$, $b, m > 0$. What is $P(\tau < \infty)$?

$$E[e^{\lambda B_{\min(\tau, N)} - \frac{1}{2}\lambda^2 \min(\tau, N)}] = 1$$

$B_{\min(\tau, N)} \leq b + m \min(\tau, N)$ so if $\lambda m \leq \frac{1}{2}\lambda^2$ we can let $N \rightarrow \infty$ to get

$$E[e^{\lambda(b+m\tau) - \frac{1}{2}\lambda^2 \tau} \mathbf{1}_{\tau < \infty}] + \lim_{N \rightarrow \infty} E[e^{\lambda B_{\min(\tau, N)} - \frac{1}{2}\lambda^2 \min(\tau, N)} \mathbf{1}_{\tau = \infty}] = 1$$

$$\begin{aligned} & \lim_{N \rightarrow \infty} E[e^{\lambda B_{\min(\tau, N)} - \frac{1}{2}\lambda^2 \min(\tau, N)} \mathbf{1}_{\tau = \infty}] \\ & \leq \lim_{N \rightarrow \infty} E[e^{\lambda(b+m \min(\tau, N)) - \frac{1}{2}\lambda^2 \min(\tau, N)} \mathbf{1}_{\tau = \infty}] \\ & = 0 \end{aligned}$$

so

$$E[e^{(\lambda m - \frac{1}{2}\lambda^2)\tau} \mathbf{1}_{\tau < \infty}] = e^{-\lambda b}$$

Let $\lambda \downarrow 2m$ to get

$$P(\tau < \infty) = e^{-2mb}$$

Brownian motion starting at x : $B_t + x$, $B_0 = 0$

$$P_x(A) = P(A \mid B_0 = x)$$

$a < x < b$ What is $P_x(\tau_a < \tau_b)$?

If $B_0 = x$ then B_t is still a martingale

$$E_x[B_{\min(\tau_a, \tau_b, N)}] = x$$

$$N \rightarrow \infty, \text{ BCT} \Rightarrow E_x[B_{\min(\tau_a, \tau_b)}] = x = E_x[B_{\tau_a} 1_{\tau_a < \tau_b}] + E_x[B_{\tau_b} 1_{\tau_a > \tau_b}] \\ = aP_x(\tau_a < \tau_b) + bP_x(\tau_a > \tau_b)$$

$$f(x) = P_x(\tau_a < \tau_b) \quad af(x) + b(1 - f(x)) = x$$

$$f(x) = P_x(\tau_a < \tau_b) = \frac{b-x}{b-a}$$

Brownian motion in \mathbb{R}^d

- 1 $B_t = (B_t^1, \dots, B_t^d)$, B_t^i independent Brownian motions
- 2 B_t Markov with $P(B_t \in A \mid B_s = x) = \int_A \frac{1}{(2\pi(t-s))^{d/2}} e^{-\frac{|y-x|^2}{2(t-s)}} dy$
- 3 B_t has stationary independent mean zero increments with $E[|B_t - B_s|^2] = d(t-s)$
- 4 $e^{\lambda \cdot B_t - \frac{1}{2}|\lambda|^2 t}$ is a martingale for any λ

Note that 1 does not depend on the basis: If B_t^1, \dots, B_t^d independent and \mathcal{O} is orthogonal, then the coordinates of $\mathcal{O}B_t$ are independent Brownian motions in fact

Theorem

Suppose X_1, X_2 independent and $\exists \theta \neq N\pi/2$ such that

$$X_1 \cos \theta + X_2 \sin \theta, \quad -X_1 \sin \theta + X_2 \cos \theta \quad \text{independent}$$

Then X_1, X_2 are Gaussians (Maxwell)

Dirichlet problem

Given a bounded open subset $G \subset \mathbf{R}^d$ and a continuous function $f : \partial G \rightarrow \mathbf{R}$ find a continuous function $u : \bar{G} \rightarrow \mathbf{R}$ such that

$$\begin{cases} \Delta u = 0 & \text{in } G \\ u|_{\partial G} = f \end{cases}$$

$$\Delta u \stackrel{\text{def}}{=} \sum_{i=1}^d \frac{\partial^2 u}{\partial x_i^2} = 2d \lim_{r \rightarrow 0} r^{-2} \left(\frac{1}{|\partial S(r, x)|} \int_{\partial S(r, x)} u dS - u(x) \right)$$

Lemma

u harmonic in $G \Leftrightarrow u$ satisfies the mean value property: for all sufficiently small $r > 0$,

$$\frac{1}{|\partial S(r, x)|} \int_{\partial S(r, x)} u dS = u(x)$$

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Proof.

Green's identity $\int_G v \Delta u dx = \int_G u \Delta v dx + \int_{\partial G} v \frac{\partial u}{\partial n} - u \frac{\partial v}{\partial n} dS$

$$G = \{\delta < |x| < r\}, \quad v = \begin{cases} \frac{\log r - \log |x|}{\log r - \log \delta} & d = 2 \\ \frac{|x|^{2-d} - r^{2-d}}{\delta^{2-d} - r^{2-d}} & d > 2 \end{cases}$$

let $\rho \downarrow 0$



B_t d -dimensional Brownian motion starting at $x \in G$

$$\tau_G = \inf\{t \geq 0 : B(t) \notin G\}$$

$$u(x) = E_x[f(B(\tau_G))]$$

"Theorem" If ∂G "nice" then u solves the Dirichlet problem

$$E_x[f(B(\tau_G))] = \int_{\partial G} f(y) \pi_G(x, dy), \quad \pi_G(x, \Gamma) = P_x(B(\tau_G) \in \Gamma), \quad \Gamma \subset \partial G$$

Example. $G = B(x, r)$, $\pi_G(x, \Gamma) = \frac{|\Gamma|}{|\partial S(x, r)|}$, $\Gamma \subset S(x, r)$

Brownian motion is invariant under rotations

$\therefore \pi_G(x, \cdot)$ is invariant under rotations

Proposition

G bounded open $\subset \mathbb{R}^d$, f bounded measurable on ∂G . Then $u(x) = E_x[f(B(\tau_G))]$ is harmonic in G .

Proof.

$$B = B(x, r) \subset G \quad \tau_B \leq \tau_G$$

Strong Markov property: $u(B(\tau_S)) = E_x[f(B(\tau_G)) \mid \mathcal{F}_{\tau_S}]$

$$\begin{aligned} u(x) = E_x[f(B(\tau_G))] &= E_x[E_x[f(B(\tau_G)) \mid \mathcal{F}_{\tau_S}]] \\ &= E_x[u(B(\tau_S))] \\ &= \int_{\partial S} u(y) \pi_S(x, dy) \\ &= \frac{1}{|\partial S|} \int_{\partial S} u(y) dS \end{aligned}$$

So u satisfies the mean value property in G . □

$$a \in \partial G$$

To complete the proof that u solves the Dirichlet problem we need

$$\lim_{x \rightarrow a, x \in G} E_x[f(B(\tau_G))] = f(a) \quad \text{It is not always true!}$$

Proposition

If $\lim_{x \rightarrow a, x \in G} P_x[\tau_G > \epsilon] = 0, \forall \epsilon > 0$ then for any bdd mble function $f : \partial G \rightarrow \mathbb{R}$ which is continuous at a , $\lim_{x \rightarrow a, x \in G} E_x[f(B(\tau_G))] = f(a)$

Proof.

Need: $\lim_{x \rightarrow a, x \in G} P_x(|B(\tau_G) - x| < \delta) = 1$

$$\begin{aligned} P_x(|B(\tau_G) - x| < \delta) &\geq P_x(\sup_{0 \leq t \leq \epsilon} |B(t) - x| < \delta, \tau_G \leq \epsilon) \\ &\geq P_x(\sup_{0 \leq t \leq \epsilon} |B(t) - x| < \delta) - P_x(\tau_G \leq \epsilon) \\ &\rightarrow 1 \text{ as } x \rightarrow a, x \in G \text{ then } \epsilon \downarrow 0 \end{aligned}$$

Proposition

$a \in \partial G$ is *regular* if $P_a(\sigma_G = 0) = 1$ $\sigma_G = \inf\{t > 0 : B(t) \notin G\}$
 a regular $\Leftrightarrow \lim_{x \rightarrow a, x \in G} E_x[f(B_{\tau_G})] = f(a) \forall f$ bdd mble, cont at a

Proof of \Rightarrow

Enough to prove $P_x(\sigma_G < \epsilon)$ lower semi-continuous in x

Then $\limsup_{\substack{x \rightarrow a \\ x \in G}} P_x(\sigma_G < \epsilon) \geq P_a(\sigma_G < \epsilon) = 1$ and $\sigma_G \geq \tau_G$

But $\int p(0, x, \delta, y) P_y(\exists s \in (0, \epsilon - \delta), B(s) \notin G)$ continuous
and $\uparrow P_x(\sigma_G < \epsilon)$ as $\delta \downarrow 0$

Examples

- 1 If ∂G is a smooth manifold near a then a is regular by LIL
- 2 If \exists cone C of height $h > 0$ and vertex at a such that $C - \{a\} \subset \bar{G}^c$ then a is a regular (exterior cone condition)
- 3 $d \leq 2$ always, $d \geq 3 \exists$ counterexamples

Application to recurrence/transience of Brownian motion

$$G = \{y \in \mathbf{R}^d : \delta < |y| < R\} \quad f = \begin{cases} 0 & |y| = R \\ 1 & |y| = \delta \end{cases}$$

$$u(x) = E_x[f(B(\tau_G))] = P_x(\tau_\delta < \tau_R) = \begin{cases} \frac{\log R - \log |x|}{\log R - \log \delta} & d = 2 \\ \frac{|x|^{2-d} - R^{2-d}}{\delta^{2-d} - R^{2-d}} & d > 2 \end{cases}$$

Theorem In $d \geq 2$, Brownian motion does not visit a point

Proof.

$$P_x(\tau_0 < \tau_R) = \lim_{\delta \downarrow 0} P_x(\tau_\delta < \tau_R) = \lim_{\delta \downarrow 0} \frac{\log R - \log |x|}{\log R - \log \delta} = 0$$

□

Theorem In $d = 2$, Brownian motion is recurrent, ie. comes arbitrarily close to any point arbitrarily many times

Proof.

$$P_x(\tau_\delta < \infty) = \lim_{R \uparrow \infty} P_x(\tau_\delta < \tau_R) = \lim_{R \uparrow \infty} \frac{\log R - \log |x|}{\log R - \log \delta} = 1$$

□

Theorem In $d \geq 3$, Brownian motion wanders off to infinity

Proof.

$$P_x(\tau_\delta < \infty) = \lim_{R \uparrow \infty} \frac{|x|^{2-d} - R^{2-d}}{\delta^{2-d} - R^{2-d}} = \left(\frac{|x|}{\delta}\right)^{2-d} \text{ if } |x| > \delta, 0 \text{ otherwise}$$

$$P_x(\text{hit } |y| = \delta \text{ after time } t) = \int \frac{e^{-\frac{|x-y|^2}{2t}}}{(2\pi t)^{d/2}} P_y(\tau_\delta < \infty) dy \rightarrow 0 \text{ as } t \rightarrow \infty$$

$$P_x(\liminf_{t \rightarrow \infty} |B(t)| > \delta) = 1$$

$$\delta \uparrow \infty \liminf_{t \rightarrow \infty} |B(t)| = \infty \quad \text{a.s.}$$

□