

1. FINITE ELEMENT METHOD

Projections in Hilbert Space

Definition 1.1. We say that a bilinear functional $a(u, v)$ defines **an inner product** in linear space B if it has the following properties (λ is an arbitrary complex number):

- (1) $a(u, v) = \overline{a(v, u)}$
- (2) $a(u_1 + u_2, v) = a(u_1, v) + a(u_2, v)$
- (3) $a(\lambda u, v) = \lambda a(u, v)$
- (4) $a(u, u) \geq 0$
- (5) $a(u, u) = 0 \Leftrightarrow u = 0$

(it follows from 3 (take $\lambda = 0$) that $a(0, v) = 0$.)

A Hilbert Space is a linear space that is complete with respect to the norm $\|\cdot\| = \sqrt{(\cdot, \cdot)}$ induced by an inner product (\cdot, \cdot) .

(Not every norm can be induced by an inner product.)

Proposition 1.2. A norm $\|\cdot\|$ is induced by an inner product (\cdot, \cdot) if and only if the parallelogram equation

$$\|f_1 + f_2\|^2 + \|f_1 - f_2\|^2 = 2(\|f_1\|^2 + \|f_2\|^2)$$

holds for any f_1, f_2 .

Proof. This is a straight forward to show because

$$\|f_1 + f_2\|^2 + \|f_1 - f_2\|^2 = (f_1 + f_2, f_1 + f_2) + (f_1 - f_2, f_1 - f_2) = 2(\|f_1\|^2 + \|f_2\|^2)$$

□

Proposition 1.3. If B_1 is a closed linear subspace of a Hilbert space B then B_1 is also a Hilbert space with respect to the same norm.

Proof. It follows from the completeness of B that a Cauchy sequence in B_1 will converge to some element in B . This element will also belong to B_1 because B_1 is closed. Hence B_1 is complete. □

Example 1

Hilbert space:

$$L^2(0, 1) := \{f \in L^2(0, 1), \int_0^1 |f(x)|^2 dx < \infty\}.$$

Inner product is given by:

$$(f, g) = \int_0^1 f(x)\overline{g(x)}dx$$

(For the proof of completeness see any functional analysis textbook) Check that the inner product satisfies properties 1 – 4.

Property 5.

If $u(x) = 0$ then $(u, u) = \int_0^1 (0)^2 dx = 0$.

If $(u, u) = 0$? Compare two functions: $f_1(x) = 0, x \in [0, 1]$ and $f_2(x) : \{f_2(x) = 0, x \in [0, 1/2) \cup (1/2, 1], f_2(1/2) = 100\}$. We can see that $(f_1, f_1) = 0$ and $(f_2, f_2) = \int_0^1 |f_2|^2 dx = \int_0^{1/2} |f_2|^2 dx + \int_{1/2}^1 |f_2|^2 dx = 0$. But a linear space can have only one zero element. What is the zero element in $L^2(0, 1)$? This is not a function ! This is a class of functions which can differ from $f(x) = 0$ on the set of zero measure only (each class can have not more than one continuous function). This is the reason that "value at a point" notion is not applicable to elements from $L^2(0, 1)$ space.

Example 2

Sobolev space:

$$H^1(0, 1) : \{f \in H^1(0, 1), \int_0^1 |f(x)|^2 dx < \infty, \int_0^1 |f'(x)|^2 dx < \infty\}.$$

This is a Hilbert Space with respect to the inner product: $(f, g) = \int_0^1 f(x) \overline{g(x)} dx + \int_0^1 f'(x) \overline{g'(x)} dx$ where derivatives are understood in a weak sense to make the space complete (for example $f(x) = |x - 1/2|$ belongs to the space $H^1(0, 1)$).

Definition 1.4. Let B_N be a subspace of B . We say that u_N is the projection of $u \in B$ to B_N if

$$\|u - u_N\| = \inf_{u_N^* \in B_N} \|u - u_N^*\|.$$

(projection is the closest element from B_N to u)

Theorem 1.5. If u_N is the projection of u to B_N then $u - u_N$ is orthogonal to $\forall h \in B_N$. [$(u - u_N, h) = 0, \forall h \in B_N$]

Proof. We will prove the statement by contradiction. Assume that exists such $h \neq 0 \in B_N$ that $(u - u_N, h) = \sigma \neq 0$. Construct a new element

$$h^* = u_N + \frac{\sigma}{(h, h)} h \in B_N$$

$$\|u - h^*\|^2 = (u - u_N - \frac{\sigma}{(h, h)} h, u - u_N - \frac{\sigma}{(h, h)} h) = \|u - u_N\|^2 - \frac{\sigma^2}{(h, h)}$$

that means that h^* is closer to u than u_N and u_N is not the projection of u . \square

Let B_N be a finite dimensional subspace of B . Let $\{\phi_1, \phi_2 \dots \phi_N\}$ be a set of linearly independent functions in B_N , i.e $\{\phi_1, \phi_2 \dots \phi_N\}$ forms a basis in B_N . That implies that for any element $f \in B_N$ exists the unique set of coefficients $(c_1, c_2 \dots c_N)$ such that

$$f = c_1 \phi_1 + c_2 \phi_2 \dots + c_N \phi_N.$$

Matrix

$$\Gamma = \begin{pmatrix} (\phi_1, \phi_1) & \cdots & (\phi_1, \phi_N) \\ \vdots & & \vdots \\ (\phi_N, \phi_1) & \cdots & (\phi_N, \phi_N) \end{pmatrix}$$

is called Gram Matrix.

Proposition 1.6. $\det(\Gamma) \neq 0$ (Γ is invertible)

Proof. Multiply $f = c_1 \phi_1 + c_2 \phi_2 \dots + c_N \phi_N$ by $\phi_1, \phi_2 \dots \phi_N$ (by inner product). We obtain the linear system of equations:

$$\begin{cases} (\phi_1, f), = c_1(\phi_1, \phi_1) + \dots + c_N(\phi_1, \phi_N) \\ \vdots \\ (\phi_N, f), = c_1(\phi_N, \phi_1) + \dots + c_N(\phi_N, \phi_N) \end{cases}$$

Because $\{\phi_1, \phi_2 \dots \phi_N\}$ forms a basis the system above has the unique solution. Hence the $\det(\Gamma) \neq 0$. \square

Projection of PDE

Let L be some closed linear operator acting in B . (For any closed linear operator the adjoint operator L^* is well defined.)

$$(1.1) \quad u_t = Lu + f, \quad u, f \in B, \quad L : B \rightarrow B$$

Let $u(x, t) \in C^2(0, 1)$ be a classic solution of 1.1.

Let $B_N = \text{span}(\phi_1, \phi_2 \dots \phi_N)$ (we have basis in B_N).

Let $\{\phi_1, \phi_2 \dots \phi_N, \phi_{N+1} \dots\}$ be some basis in B (the unique infinite series representation of any element in B converges strongly in the sense of the norm in B .)

Let u_N and f_N (see our definition) be the projections of u and f to B_N .

Under what conditions on $\phi_1, \phi_2 \dots \phi_N$ does the equality

$$(u_{Nt}, \phi_n) = (Lu_n, \phi_n) + (f_N, \phi_n), \quad n = 1..N$$

hold ?

By the Theorem 1.5:

$$(u - u_N, \phi_n) = 0, \quad (f - f_N, \phi_n), \quad n = 1..N.$$

$$(1.2) \quad (L(u - u_N), \phi_n) = (u - u_N, L^* \phi_n) = 0$$

if $L^* \phi_n \in B_N$, $n = 1..N$ (i.e if B_N is invariant under the adjoint operator L^*)

$$(1.3) \quad (u_t - u_{Nt}, \phi_n) = \frac{d}{dt}(u - u_N, \phi_n) = 0, \quad n = 1..N.$$

because ϕ_n does not depend on t .

It follows from the equation 1.1 that

$$(1.4) \quad (u_t, \phi_n) = (Lu, \phi_n) + (f, \phi_n), \quad n = 1..N.$$

From 1.2, 1.3, 1.4 it follows that

$$(u_{Nt}, \phi_n) = (Lu_n, \phi_n) + (f_N, \phi_n), \quad n = 1..N.$$

u_N converges to u as $N \rightarrow \infty$ strongly by the norm in B because

$$\{\phi_1, \phi_2 \dots \phi_N, \phi_{N+1} \dots\}$$

forms a basis in B .

The solution u_N does make sense because this is the closest element from B_N to the exact solution u . (The solution of 1.4 exists and it is unique because Γ is invertible.)

Finite Element Method.

Consider the boundary value problem (BVP):

$$\begin{cases} -u'' = f, \forall x \in (0, 1) \\ u(0) = 0 \\ u'(1) = 0 \end{cases}$$

Construct a suitable Hilbert Space (real valued functions):

$$V = \{v(x) \in V, \int_0^1 v^2 dx < \infty, \int_0^1 v'^2 dx < \infty, v(0) = 0\}$$

that is a subspace of the Sobolev Space $H^1(0, 1)$ and as it follows from the proposition 1.3 V is a Hilbert space.

Definition 1.7. We say that $u(x) \in C^1(0, 1)$, $u(0) = 0$ is a **weak solution** of the BVP if

$$\int_0^1 f v dx = \int_0^1 u' v' dx$$

for any $v(x) \in V$.

The definition of a weak solution comes from the integration by parts (assume that $u(x, t)$ is a classic solution of BVP: $u(0) = 0$ and $u'(1) = 0$ and $v(x) \in V$, $v(0) = 0$):

$$\int_0^1 f v dx = - \int_0^1 u'' v dx = \int_0^1 u' v' dx - u'(1)v(1) + u'(0)v(0) = \int_0^1 u' v' dx$$

Theorem 1.8. Assume that f and u'' are continuous functions on $[0, 1]$. If $u \in V$ and u is a weak solution of the BVP then u is a classical solution of the BVP.

Proof. Given $u(0) = 0$ and $\int_0^1 f v dx = \int_0^1 u' v' dx$ for any $v(x) \in V$ we want to show that $u'(1) = 0$ and $-u'' = f$.

Integrating by parts:

$$\int_0^1 f v dx = \int_0^1 u' v' dx = - \int_0^1 u'' v dx + u'(1)v(1)$$

We obtain:

$$(1.5) \quad u'(1)v(1) = \int_0^1 (f + u'') v dx$$

Define the new continuous function as $h(x) = f(x) + u''(x)$. Assume that $h(x)$ is not identically 0 on $[0, 1]$. Then there exists a subinterval (δ_1, δ_2) of $(0, 1)$ such that $h(x)$ is strictly positive (or strictly negative). In this case we just choose a test function $v(x)$ such that $v(x) \equiv 0$ on $(0, 1)/(\delta_1, \delta_2)$ and

$v(x) > 0$ on (δ_1, δ_2) . The equality 1.5 does not hold for this $v(x)$ hence $f(x) + u''(x) = 0$ and $u'(1) = 0$. \square

Define a bilinear functional $a(u, v) = \int_0^1 u' v' dx$ and $(f, v) = \int_0^1 f(x)v(x) dx$. Show that $a(u, v) = \int_0^1 u' v' dx$ is an inner product on V . Check properties (1-4) by your own. Property 5.

$$a(u, u) = 0 \quad \Leftrightarrow \quad u = 0$$

If $u = 0$ then $\int_0^1 (0)^2 dx = 0$

If $a(u, u) = 0$? ($u(x) \in V$, $u(0) = 0$)

$$u(x) = \int_0^x u'(t) dt$$

$$|u(x)| = \left| \int_0^x u'(t) dt \right| \leq \sqrt{x} \sqrt{\int_0^x (u'(t))^2 dt} \leq \sqrt{a(u, u)}$$

Hence $a(u, u) = 0$ implies that $u(x) = 0$ pointwise.

Theorem 1.9. Let $V_N = \text{span}(\phi_1, \phi_2, \dots, \phi_N) \subset V$. Let u be a weak solution of the BVP problem, i.e

$$(f, v) = a(u, v)$$

for any $v \in V$. If f_N is the projection of f to V_N and the $u_N \in V_N$ satisfies the equality

$$(f_N, v_N) = a(u_N, v_N)$$

for any $v_N \in V_N$ then u_N is the projection of the weak solution u to V_N . (u_N is the closest element from V_N to the weak solution u)

Proof. Given that

$$(f, v) = a(u, v)$$

holds for any $v \in V$ we obtain that

$$(f, v_N) = a(u, v_N)$$

for any $v_N \in V_N$. We also given that

$$(f_N, v_N) = a(u_N, v_N).$$

Hence

$$0 = (f - f_N, v_N) = a(u - u_N, v_N)$$

and u_N is the projection of the weak solution u to the subspace V_N (We used the bilinear form $a(u, v)$ as a new inner product in V instead of the inner product $(u, v) = \int_0^1 uv dx + \int_0^1 u'v' dx$ inherited from the Sobolev space but one can show that V is complete with respect to this new inner product.) \square