

2.3 Examples of Manifolds

We will now discuss some basic examples of manifolds. In each case, the manifold structure is given by a finite atlas; hence the countability property is immediate. We will not spend too much time on verifying the Hausdorff property; while it may be done ‘by hand’, we will later have better ways of doing this.

2.3.1 Spheres

The construction of an atlas for the 2-sphere S^2 , by stereographic projection, also works for the n -sphere

$$S^n = \{(x^0, \dots, x^n) \mid (x^0)^2 + \dots + (x^n)^2 = 1\}.$$

Let U_{\pm} be the subsets obtained by removing $(\mp 1, 0, \dots, 0)$. Stereographic projection defines bijections $\varphi_{\pm} : U_{\pm} \rightarrow \mathbb{R}^n$, where $\varphi_{\pm}(x^0, x^1, \dots, x^n) = (u^1, \dots, u^n)$ with

$$u^i = \frac{x^i}{1 \pm x^0}.$$

For the transition function one finds (writing $u = (u^1, \dots, u^n)$)

$$(\varphi_- \circ \varphi_+^{-1})(u) = \frac{u}{\|u\|^2}.$$

We leave it as an exercise to check the details. An equivalent atlas, with $2n+2$ charts, is given by the subsets $U_0^+, \dots, U_n^+, U_0^-, \dots, U_n^-$ where

$$U_j^+ = \{x \in S^n \mid x^j > 0\}, \quad U_j^- = \{x \in S^n \mid x^j < 0\}$$

for $j = 0, \dots, n$, with $\varphi_j^{\pm} : U_j^{\pm} \rightarrow \mathbb{R}^n$ the projection to the j -th coordinate plane (in other words, omitting the j -th component x^j):

$$\varphi_j^{\pm}(x^0, \dots, x^n) = (x^0, \dots, x^{j-1}, x^{j+1}, \dots, x^n).$$

2.3.2 Real projective spaces

The n -dimensional projective space $\mathbb{R}P^n$, is the set of all lines $\ell \subseteq \mathbb{R}^{n+1}$. It may also be regarded as a quotient space[‡]

$$\mathbb{R}P^n = (\mathbb{R}^{n+1} \setminus \{0\}) / \sim$$

for the equivalence relation

$$x \sim x' \Leftrightarrow \exists \lambda \in \mathbb{R} \setminus \{0\} : x' = \lambda x.$$

[‡] See the appendix to this chapter for some background on quotient spaces.

Indeed, any $x \in \mathbb{R}^{n+1} \setminus \{0\}$ determines a line, while two points x, x' determine the same line if and only if they agree up to a non-zero scalar multiple. The equivalence class of $x = (x^0, \dots, x^n)$ under this relation is commonly denoted

$$[x] = (x^0 : \dots : x^n).$$

$\mathbb{R}P^n$ has a *standard atlas*

$$\mathcal{A} = \{(U_0, \varphi_0), \dots, (U_n, \varphi_n)\}$$

defined as follows. For $j = 0, \dots, n$, let

$$U_j = \{(x^0 : \dots : x^n) \in \mathbb{R}P^n \mid x^j \neq 0\}$$

be the set for which the j -th coordinate is non-zero, and put

$$\varphi_j : U_j \rightarrow \mathbb{R}^n, \quad (x^0 : \dots : x^n) \mapsto \left(\frac{x^0}{x^j}, \dots, \frac{x^{j-1}}{x^j}, \frac{x^{j+1}}{x^j}, \dots, \frac{x^n}{x^j} \right).$$

This is well-defined, since the quotients do not change when all x^i are multiplied by a fixed scalar. Put differently, given an element $[x] \in \mathbb{R}P^n$ for which the j -th component x^j is non-zero, we first rescale the representative x to make the j -th component equal to 1, and then use the remaining components as our coordinates. As an example (with $n = 2$),

$$\varphi_1(7 : 3 : 2) = \varphi_1\left(\frac{7}{3} : 1 : \frac{2}{3}\right) = \left(\frac{7}{3}, \frac{2}{3}\right).$$

From this description, it is immediate that φ_j is a bijection from U_j onto \mathbb{R}^n , with inverse map

$$\varphi_j^{-1}(u^1, \dots, u^n) = (u^1 : \dots : u^j : 1 : u^{j+1} : \dots : u^n).$$

Geometrically, viewing $\mathbb{R}P^n$ as the set of lines in \mathbb{R}^{n+1} , the subset $U_j \subseteq \mathbb{R}P^n$ consists of those lines ℓ which intersect the affine hyperplane

$$H_j = \{x \in \mathbb{R}^{n+1} \mid x^j = 1\},$$

and the map φ_j takes such a line ℓ to its unique point of intersection $\ell \cap H_j$, followed by the identification $H_j \cong \mathbb{R}^n$ (dropping the coordinate $x^j = 1$).

Let us verify that \mathcal{A} is indeed an atlas. Clearly, the domains U_j cover $\mathbb{R}P^n$, since any element $[x] \in \mathbb{R}P^n$ has at least one of its components non-zero. For $i \neq j$, the intersection $U_i \cap U_j$ consists of elements x with the property that both components x^i, x^j are non-zero.

Exercise 8. Compute the transition maps $\varphi_i \circ \varphi_j^{-1}$, and verify they are smooth. (Hint: You will need to distinguish between the cases $i < j$ and $i > j$.)

To complete the proof that this atlas (or the unique maximal atlas containing it) defines a manifold structure, it remains to check the Hausdorff property.

This can be done with the help of Lemma 2.2, but we postpone the proof since we will soon have a simple argument in terms of smooth functions. See Proposition 3.1 below.

Remark 2.4. In low dimensions, we have that $\mathbb{R}P^0$ is just a point, while $\mathbb{R}P^1$ is a circle.

Remark 2.5. Geometrically, U_i consists of all lines in \mathbb{R}^{n+1} meeting the affine hyperplane H_i , hence its complement consists of all lines that are parallel to H_i , i.e., the lines in the coordinate subspace defined by $x^i = 0$. The set of such lines is $\mathbb{R}P^{n-1}$. In other words, the complement of U_i in $\mathbb{R}P^n$ is identified with $\mathbb{R}P^{n-1}$.

Thus, as sets, $\mathbb{R}P^n$ is a disjoint union

$$\mathbb{R}P^n = \mathbb{R}^n \sqcup \mathbb{R}P^{n-1},$$

where \mathbb{R}^n is identified (by the coordinate map φ_i) with the open subset U_n , and $\mathbb{R}P^{n-1}$ with its complement. Inductively, we obtain a decomposition

$$\mathbb{R}P^n = \mathbb{R}^n \sqcup \mathbb{R}^{n-1} \sqcup \dots \sqcup \mathbb{R} \sqcup \mathbb{R}^0,$$

where $\mathbb{R}^0 = \{0\}$. At this stage, it is simply a decomposition into subsets; later it will be recognized as a decomposition into submanifolds.

Exercise 9. Find an identification of the space of rotations in \mathbb{R}^3 with the 3-dimensional projective space $\mathbb{R}P^3$.

(Note that the space of rotations is a manifold.)

Hint: Associate to any $\lambda \in \mathbb{K}_3$ a rotation as follows: If $\lambda = 0$, take the identity rotation. If $\lambda \neq 0$, take the rotation by an angle θ about the oriented axis determined by λ . Note that $\|\lambda\| = \alpha$ and $-\lambda$ determine the same rotation.

2.3.3 Complex projective spaces

In a similar fashion to the real projective space, one can define a *complex projective space* $\mathbb{C}P^n$ as the set of complex 1-dimensional subspaces of \mathbb{C}^{n+1} . If we identify \mathbb{C} with \mathbb{R}^2 , thus \mathbb{C}^{n+1} with \mathbb{R}^{2n+2} , we have

$$\mathbb{C}P^n = (\mathbb{C}^{n+1} \setminus \{0\}) / \sim$$

where the equivalence relation is $z \sim z'$ if and only if there exists a complex λ with $z' = \lambda z$. (Note that the scalar λ is then unique, and is non-zero.) Alternatively, letting $S^{2n+1} \subseteq \mathbb{C}^{n+1} = \mathbb{R}^{2n+2}$ be the ‘unit sphere’ consisting of complex vectors of length $\|z\| = 1$, we have

$$\mathbb{C}P^n = S^{2n+1} / \sim,$$

where $z' \sim z$ if and only if there exists a complex number λ with $z' = \lambda z$. (Note that the scalar λ is then unique, and has absolute value 1.) One defines charts (U_j, φ_j) similarly to those for the real projective space:

$$U_j = \{(z^0 : \dots : z^n) \mid z^j \neq 0\}, \quad \varphi_j : U_j \rightarrow \mathbb{C}^n = \mathbb{R}^{2n},$$

$$\varphi_j(z^0 : \dots : z^n) = \left(\frac{z^0}{z^j}, \dots, \frac{z^{j-1}}{z^j}, \frac{z^{j+1}}{z^j}, \dots, \frac{z^n}{z^j} \right).$$

The transition maps between charts are given by similar formulas as for $\mathbb{R}P^n$ (just replace x with z); they are smooth maps between open subsets of $\mathbb{C}^n = \mathbb{R}^{2n}$. Thus $\mathbb{C}P^n$ is a smooth manifold of dimension $2n$ [§]. As with $\mathbb{R}P^n$ there is a decomposition

$$\mathbb{C}P^n = \mathbb{C}^n \sqcup \mathbb{C}^{n-1} \sqcup \dots \sqcup \mathbb{C} \sqcup \mathbb{C}^0.$$

2.3.4 Grassmannians

The set $\text{Gr}(k, n)$ of all k -dimensional subspaces of \mathbb{R}^n is called the *Grassmannian of k -planes in \mathbb{R}^n* . (Named after *Hermann Grassmann* (1809-1877).)



As a special case, $\text{Gr}(1, n) = \mathbb{R}P^{n-1}$.

We will show that for general k , the Grassmannian is a manifold of dimension

$$\dim(\text{Gr}(k, n)) = k(n - k).$$

An atlas for $\text{Gr}(k, n)$ may be constructed as follows. The idea is to present linear subspaces of dimension k as graphs of linear maps from \mathbb{R}^k to \mathbb{R}^{n-k} . Here \mathbb{R}^k is viewed as the coordinate subspace corresponding to a choice of k components from $x = (x^1, \dots, x^n) \in \mathbb{R}^n$, and \mathbb{R}^{n-k} the coordinate subspace for the remaining coordinates. To make it precise, we introduce some notation.

For any subset $I \subseteq \{1, \dots, n\}$ of the set of indices, let

$$I' = \{1, \dots, n\} \setminus I$$

be its complement. Let $\mathbb{R}^I \subseteq \mathbb{R}^n$ be the coordinate subspace

$$\mathbb{R}^I = \{x \in \mathbb{R}^n \mid x^i = 0 \text{ for all } i \in I'\}.$$

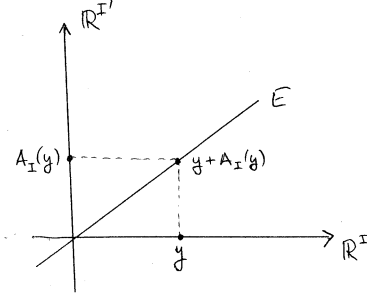
If I has cardinality $|I| = k$, then $\mathbb{R}^I \in \text{Gr}(k, n)$. Note that $\mathbb{R}^{I'} = (\mathbb{R}^I)^\perp$. Let

$$U_I = \{E \in \text{Gr}(k, n) \mid E \cap \mathbb{R}^{I'} = \{0\}\}.$$

[§] The transition maps are not only smooth but even holomorphic, making $\mathbb{C}P^n$ into an example of a *complex manifold* (of complex dimension n).

Each $E \in U_I$ is described as the graph of a unique linear map $A_I : \mathbb{R}^I \rightarrow \mathbb{R}^{I'}$, that is,

$$E = \{y + A_I(y) \mid y \in \mathbb{R}^I\}.$$



Exercise 10. Let E be as above. Show that there is a unique linear map $A_I : \mathbb{R}^I \rightarrow \mathbb{R}^{I'}$ such that $E = \{y + A_I(y) \mid y \in \mathbb{R}^I\}$.

This gives a bijection

$$\varphi_I : U_I \rightarrow \text{Hom}(\mathbb{R}^I, \mathbb{R}^{I'}), E \mapsto \varphi_I(E) = A_I,$$

where $\text{Hom}(F, F')$ denotes the space of linear maps from a vector space F to a vector space F' . Note $\text{Hom}(\mathbb{R}^I, \mathbb{R}^{I'}) \cong \mathbb{R}^{k(n-k)}$, because the bases of \mathbb{R}^I and $\mathbb{R}^{I'}$ identify the space of linear maps with $(n-k) \times k$ -matrices, which in turn is just $\mathbb{R}^{k(n-k)}$ by listing the matrix entries. In terms of A_I , the subspace $E \in U_I$ is the range of the injective linear map

$$\begin{pmatrix} 1 \\ A_I \end{pmatrix} : \mathbb{R}^I \rightarrow \mathbb{R}^I \oplus \mathbb{R}^{I'} \cong \mathbb{R}^n \tag{2.1}$$

where we write elements of \mathbb{R}^n as column vectors.

To check that the charts are compatible, suppose $E \in U_I \cap U_J$, and let A_I and A_J be the linear maps describing E in the two charts. We have to show that the map

$$\varphi_J \circ \varphi_I^{-1} : \text{Hom}(\mathbb{R}^I, \mathbb{R}^{I'}) \rightarrow \text{Hom}(\mathbb{R}^J, \mathbb{R}^{J'}), A_I = \varphi_I(E) \mapsto A_J = \varphi_J(E)$$

is smooth. By assumption, E is described as the range of (2.1) and also as the range of a similar map for J . Here we are using the identifications $\mathbb{R}^I \oplus \mathbb{R}^{I'} \cong \mathbb{R}^n$ and $\mathbb{R}^J \oplus \mathbb{R}^{J'} \cong \mathbb{R}^n$. It is convenient to describe everything in terms of $\mathbb{R}^J \oplus \mathbb{R}^{J'}$. Let

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} : \mathbb{R}^I \oplus \mathbb{R}^{I'} \rightarrow \mathbb{R}^J \oplus \mathbb{R}^{J'}$$

be the matrix corresponding to the identification $\mathbb{R}^I \oplus \mathbb{R}^{I'} \rightarrow \mathbb{R}^n$ followed by the inverse of $\mathbb{R}^J \oplus \mathbb{R}^{J'} \rightarrow \mathbb{R}^n$. For example, c is the inclusion $\mathbb{R}^I \rightarrow \mathbb{R}^n$ as the corresponding coordinate subspace, followed by projection to the coordinate subspace $\mathbb{R}^{J'}$. ¶ We then get the condition that the injective linear maps

¶ Put differently, the matrix is the permutation matrix ‘renumbering’ the coordinates of \mathbb{R}^n .

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 \\ A_I \end{pmatrix} : \mathbb{R}^I \rightarrow \mathbb{R}^J \oplus \mathbb{R}^{J'}, \quad \begin{pmatrix} 1 \\ A_J \end{pmatrix} : \mathbb{R}^J \rightarrow \mathbb{R}^J \oplus \mathbb{R}^{J'}$$

have the same range. In other words, there is an isomorphism $S : \mathbb{R}^I \rightarrow \mathbb{R}^J$ such that

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 \\ A_I \end{pmatrix} = \begin{pmatrix} 1 \\ A_J \end{pmatrix} S$$

as maps $\mathbb{R}^I \rightarrow \mathbb{R}^J \oplus \mathbb{R}^{J'}$. We obtain

$$\begin{pmatrix} a + bA_I \\ c + dA_I \end{pmatrix} = \begin{pmatrix} S \\ A_J S \end{pmatrix}$$

Using the first row of this equation to eliminate the second row of this equation, we obtain the formula

$$A_J = (c + dA_I)(a + bA_I)^{-1}.$$

The dependence of the right hand side on the matrix entries of A_I is smooth, by Cramer's formula for the inverse matrix. It follows that the collection of all $\varphi_I : U_I \rightarrow \mathbb{R}^{k(n-k)}$ defines on $\text{Gr}(k, n)$ the structure of a manifold of dimension $k(n-k)$. The number of charts of this atlas equals the number of subsets $I \subseteq \{1, \dots, n\}$ of cardinality k , that is, it is equal to $\binom{n}{k}$. (The Hausdorff property may be checked in a similar fashion to $\mathbb{R}P^n$. Alternatively, given distinct $E_1, E_2 \in \text{Gr}(k, n)$, choose a subspace $F \in \text{Gr}(k, n)$ such that F^\perp has zero intersection with both E_1, E_2 . (Such a subspace always exists.) One can then define a chart (U, φ) , where U is the set of subspaces E transverse to F^\perp , and φ realizes any such map as the graph of a linear map $F \rightarrow F^\perp$. Thus $\varphi : U \rightarrow \text{Hom}(F, F^\perp)$. As above, we can check that this is compatible with all the charts (U_I, φ_I) . Since both E_1, E_2 are in this chart U , we are done by Lemma 2.2.)

Exercise 11. Prove the parenthetical remark above: If $E_1, E_2 \in \text{Gr}(k, n)$ are distinct, show that there exists $F \in \text{Gr}(k, n)$ such that $F^\perp \cap E_1 = F^\perp \cap E_2 = \{0\}$.

Remark 2.6. As already mentioned, $\text{Gr}(1, n) = \mathbb{R}P^{n-1}$. One can check that our system of charts in this case is the standard atlas for $\mathbb{R}P^{n-1}$.

Exercise 12. This is a preparation for the following remark. Recall that a linear map $\Pi : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is an orthogonal projection onto some subspace $E \subseteq \mathbb{R}^n$ if $\Pi(x) = x$ for $x \in E$ and $\Pi(x) = 0$ for $x \in E^\perp$. Show that a square matrix $P \in \text{Mat}_{\mathbb{R}}(n)$ is the matrix of an orthogonal projection if and only if it has the properties

$$P^\top = P \text{ and } PP = P.$$

What is the matrix of the orthogonal projection onto E^\perp ?

Remark 2.7. For any k -dimensional subspace $E \subseteq \mathbb{R}^n$, let $\Pi^E : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be the linear map given by orthogonal projection onto E , and let $P_E \in \text{Mat}_{\mathbb{R}}(n)$ be its matrix. By the exercise,

$$P_E^\top = P_E, \quad P_E P_E = P_E,$$

Conversely, any square matrix P with the properties $P^\top = P$, $PP = P$ with $\text{rank}(P) = k$ is the orthogonal projection onto a subspace $\{Px \mid x \in \mathbb{R}^n\} \subseteq \mathbb{R}^n$. This identifies the Grassmannian $\text{Gr}(k, n)$ with the set of orthogonal projections of rank k . In summary, we have an inclusion

$$\text{Gr}(k, n) \hookrightarrow \text{Mat}_{\mathbb{R}}(n) \cong \mathbb{R}^{n^2}, \quad E \mapsto P_E.$$

By construction, this inclusion takes values in the subspace $\text{Sym}_{\mathbb{R}}(n) \cong \mathbb{R}^{n(n+1)/2}$ of symmetric $n \times n$ -matrices.

Remark 2.8. For all k , there is an identification $\text{Gr}(k, n) \cong \text{Gr}(n-k, n)$ (taking a k -dimensional subspace to the orthogonal subspace).

Remark 2.9. Similar to $\mathbb{R}P^2 = S^2 / \sim$, the quotient modulo antipodal identification, one can also consider

$$M = (S^2 \times S^2) / \sim$$

the quotient space by the equivalence relation

$$(x, x') \sim (-x, -x').$$

It turns out that this manifold M is the same as $\text{Gr}(2, 4)$, where ‘the same’ is meant in the sense that there is a bijection of sets identifying the atlases. Note that this is the first genuinely new manifold, since $\text{Gr}(1, 4) = \mathbb{R}P^3$, and $\text{Gr}(3, 4) \cong \text{Gr}(1, 4)$ by the previous remark.

Question: What about the other $\text{Gr}(k, n)$ with $n \leq 4$?

2.3.5 Complex Grassmannians

Similar to the case of projective spaces, one can also consider the *complex Grassmannian* $\text{Gr}_{\mathbb{C}}(k, n)$ of complex k -dimensional subspaces of \mathbb{C}^n . It is a manifold of dimension $2k(n-k)$, which can also be regarded as a complex manifold of complex dimension $k(n-k)$.