

We now proceed with the first step towards showing that transversality is generic.

**Theorem 1.43.** *Let  $F : X \times S \rightarrow Y$  and  $g : Z \rightarrow Y$  be smooth maps of manifolds where only  $X$  has boundary. Suppose that  $F$  and  $\partial F$  are transverse to  $g$ . Then for almost every  $s \in S$ ,  $f_s = F(\cdot, s)$  and  $\partial f_s$  are transverse to  $g$ .*

*Proof.* The fiber product  $W = (X \times S) \times_Y Z$  is a regular submanifold (with boundary) of  $X \times S \times Z$  and projects to  $S$  via the usual projection map  $\pi$ . We show that any  $s \in S$  which is a regular value for both the projection map  $\pi : W \rightarrow S$  and its boundary map  $\partial\pi$  gives rise to a  $f_s$  which is transverse to  $g$ . Then by Sard's theorem the  $s$  which fail to be regular in this way form a set of measure zero.

Suppose that  $s \in S$  is a regular value for  $\pi$ . Suppose that  $f_s(x) = g(z) = y$  and we now show that  $f_s$  is transverse to  $g$  there. Since  $F(x, s) = g(z)$  and  $F$  is transverse to  $g$ , we know that

$$\text{Im}DF_{(x,s)} + \text{Im}Dg_z = T_y Y.$$

Therefore, for any  $a \in T_y Y$ , there exists  $b = (w, e) \in T(X \times S)$  with  $DF_{(x,s)}b - a$  in the image of  $Dg_z$ . But since  $D\pi$  is surjective, there exists  $(w', e, c') \in T_{(x,y,z)}W$ . Hence we observe that

$$(Df_s)(w - w') - a = DF_{(x,s)}[(w, e) - (w', e)] - a = (DF_{(x,s)}b - a) - DF_{(x,s)}(w', e),$$

where both terms on the right hand side lie in  $\text{Im}Dg_z$ .

Precisely the same argument (with  $X$  replaced with  $\partial X$  and  $F$  replaced with  $\partial F$ ) shows that if  $s$  is regular for  $\partial\pi$  then  $\partial f_s$  is transverse to  $g$ . This gives the result.  $\square$

The previous result immediately shows that transversal maps to  $\mathbb{R}^n$  are generic, since for any smooth map  $f : M \rightarrow \mathbb{R}^n$  we may produce a family of maps

$$F : M \times \mathbb{R}^n \rightarrow \mathbb{R}^n$$

via  $F(x, s) = f(x) + s$ . This new map  $F$  is clearly a submersion and hence is transverse to any smooth map  $g : Z \rightarrow \mathbb{R}^n$ . For arbitrary target manifolds, we will imitate this argument, but we will require a (weak) version of Whitney's embedding theorem for manifolds into  $\mathbb{R}^n$ .

## 1.10 Partitions of unity and Whitney embedding

In this section we develop the tool of partition of unity, which will allow us to *go from local to global*, i.e. to glue together objects which are defined locally, creating objects with global meaning. As a particular case of this, to define a global map to  $\mathbb{R}^N$  which is an embedding, thereby proving Whitney's embedding theorem.

**Definition 13.** A collection of subsets  $\{U_\alpha\}$  of the topological space  $M$  is called *locally finite* when each point  $x \in M$  has a neighbourhood  $V$  intersecting only finitely many of the  $U_\alpha$ .

**Definition 14.** A covering  $\{V_\alpha\}$  is a *refinement* of the covering  $\{U_\beta\}$  when each  $V_\alpha$  is contained in some  $U_\beta$ .

**Lemma 1.44.** *Any open covering  $\{A_\alpha\}$  of a topological manifold has a countable, locally finite refinement  $\{(U_i, \varphi_i)\}$  by coordinate charts such that  $\varphi_i(U_i) = B(0, 3)$  and  $\{V_i = \varphi_i^{-1}(B(0, 1))\}$  is still a covering of  $M$ . We will call such a cover a regular covering. In particular, any topological manifold is paracompact (i.e. every open cover has a locally finite refinement)*

*Proof.* If  $M$  is compact, the proof is easy: choosing coordinates around any point  $x \in M$ , we can translate and rescale to find a covering of  $M$  by a refinement of the type desired, and choose a finite subcover, which is obviously locally finite.

For a general manifold, we note that by second countability of  $M$ , there is a countable basis of coordinate neighbourhoods and each of these charts is a countable union of open sets  $P_i$  with  $\bar{P}_i$  compact. Hence  $M$  has a countable basis  $\{P_i\}$  such that  $\bar{P}_i$  is compact.

Using these, we may define an increasing sequence of compact sets which exhausts  $M$ : let  $K_1 = \overline{P}_1$ , and

$$K_{i+1} = \overline{P_1 \cup \dots \cup P_r},$$

where  $r > 1$  is the first integer with  $K_i \subset P_1 \cup \dots \cup P_r$ .

Now note that  $M$  is the union of ring-shaped sets  $K_i \setminus K_{i-1}^\circ$ , each of which is compact. If  $p \in A_\alpha$ , then  $p \in K_{i+2} \setminus K_{i-1}^\circ$  for some  $i$ . Now choose a coordinate neighbourhood  $(U_{p,\alpha}, \varphi_{p,\alpha})$  with  $U_{p,\alpha} \subset K_{i+2} \setminus K_{i-1}^\circ$  and  $\varphi_{p,\alpha}(U_{p,\alpha}) = B(0,3)$  and define  $V_{p,\alpha} = \varphi^{-1}(B(0,1))$ .

Letting  $p, \alpha$  vary, these neighbourhoods cover the compact set  $K_{i+1} \setminus K_i^\circ$  without leaving the band  $K_{i+2} \setminus K_{i-1}^\circ$ . Choose a finite subcover  $V_{i,k}$  for each  $i$ . Then  $(U_{i,k}, \varphi_{i,k})$  is the desired locally finite refinement.  $\square$

**Definition 15.** A smooth partition of unity is a collection of smooth non-negative functions  $\{f_\alpha : M \rightarrow \mathbb{R}\}$  such that

- i)  $\{\text{supp } f_\alpha = \overline{f_\alpha^{-1}(\mathbb{R} \setminus \{0\})}\}$  is locally finite,
- ii)  $\sum_\alpha f_\alpha(x) = 1 \quad \forall x \in M$ , hence the name.

A partition of unity is *subordinate* to an open cover  $\{U_i\}$  when  $\forall \alpha, \text{supp } f_\alpha \subset U_i$  for some  $i$ .

**Theorem 1.45.** *Given a regular covering  $\{(U_i, \varphi_i)\}$  of a manifold, there exists a partition of unity  $\{f_i\}$  subordinate to it with  $f_i > 0$  on  $V_i$  and  $\text{supp } f_i \subset \varphi_i^{-1}(B(0,2))$ .*

*Proof.* A bump function is a smooth non-negative real-valued function  $\tilde{g}$  on  $\mathbb{R}^n$  with  $\tilde{g}(x) = 1$  for  $\|x\| \leq 1$  and  $\tilde{g}(x) = 0$  for  $\|x\| \geq 2$ . For instance, take

$$\tilde{g}(x) = \frac{h(2 - \|x\|)}{h(2 - \|x\|) + h(\|x\| + 1)},$$

for  $h(t)$  given by  $e^{-1/t}$  for  $t > 0$  and 0 for  $t < 0$ .

Having this bump function, we can produce non-negative bump functions on the manifold  $g_i = \tilde{g} \circ \varphi_i$  which have support  $\text{supp } g_i \subset \varphi_i^{-1}(B(0,2))$  and take the value +1 on  $\overline{V}_i$ . Finally we define our partition of unity via

$$f_i = \frac{g_i}{\sum_j g_j}, \quad i = 1, 2, \dots$$

$\square$

We now investigate the embedding of arbitrary smooth manifolds as regular submanifolds of  $\mathbb{R}^k$ . We shall first show by a straightforward argument that any smooth manifold may be embedded in some  $\mathbb{R}^N$  for some sufficiently large  $N$ . We will then explain how to cut down on  $N$  and approach the optimal  $N = 2 \dim M$  which Whitney showed (we shall reach  $2 \dim M + 1$  and possibly at the end of the course, show  $N = 2 \dim M$ .)

**Theorem 1.46** (Compact Whitney embedding in  $\mathbb{R}^N$ ). *Any compact manifold may be embedded in  $\mathbb{R}^N$  for sufficiently large  $N$ .*

*Proof.* Let  $\{(U_i \supset V_i, \varphi_i)\}_{i=1}^k$  be a finite regular covering, which exists by compactness. Choose a partition of unity  $\{f_1, \dots, f_k\}$  as in Theorem 1.45 and define the following “zoom-in” maps  $M \rightarrow \mathbb{R}^{\dim M}$ :

$$\tilde{\varphi}_i(x) = \begin{cases} f_i(x)\varphi_i(x) & x \in U_i, \\ 0 & x \notin U_i. \end{cases}$$

Then define a map  $\Phi : M \rightarrow \mathbb{R}^{k(\dim M + 1)}$  which zooms simultaneously into all neighbourhoods, with extra information to guarantee injectivity:

$$\Phi(x) = (\tilde{\varphi}_1(x), \dots, \tilde{\varphi}_k(x), f_1(x), \dots, f_k(x)).$$

Note that  $\Phi(x) = \Phi(x')$  implies that for some  $i$ ,  $f_i(x) = f_i(x') \neq 0$  and hence  $x, x' \in U_i$ . This then implies that  $\varphi_i(x) = \varphi_i(x')$ , implying  $x = x'$ . Hence  $\Phi$  is injective.

We now check that  $D\Phi$  is injective, which will show that it is an injective immersion. At any point  $x$  the differential sends  $v \in T_x M$  to the following vector in  $\mathbb{R}^{\dim M} \times \cdots \times \mathbb{R}^{\dim M} \times \mathbb{R} \times \cdots \times \mathbb{R}$ .

$$(Df_1(v)\varphi_1(x) + f_1(x)D\varphi_1(v), \dots, Df_k(v)\varphi_k(x) + f_k(x)D\varphi_k(v), Df_1(v), \dots, Df_k(v))$$

But this vector cannot be zero. Hence we see that  $\Phi$  is an immersion.

But an injective immersion from a compact space must be an embedding: view  $\Phi$  as a bijection onto its image. We must show that  $\Phi^{-1}$  is continuous, i.e. that  $\Phi$  takes closed sets to closed sets. If  $K \subset M$  is closed, it is also compact and hence  $\Phi(K)$  must be compact, hence closed (since the target is Hausdorff).  $\square$

**Theorem 1.47** (Compact Whitney embedding in  $\mathbb{R}^{2n+1}$ ). *Any compact  $n$ -manifold may be embedded in  $\mathbb{R}^{2n+1}$ .*

*Proof.* Begin with an embedding  $\Phi : M \rightarrow \mathbb{R}^N$  and assume  $N > 2n + 1$ . We then show that by projecting onto a hyperplane it is possible to obtain an embedding to  $\mathbb{R}^{N-1}$ .

A vector  $v \in S^{N-1} \subset \mathbb{R}^N$  defines a hyperplane (the orthogonal complement) and let  $P_v : \mathbb{R}^N \rightarrow \mathbb{R}^{N-1}$  be the orthogonal projection to this hyperplane. We show that the set of  $v$  for which  $\Phi_v = P_v \circ \Phi$  fails to be an embedding is a set of measure zero, hence that it is possible to choose  $v$  for which  $\Phi_v$  is an embedding.

$\Phi_v$  fails to be an embedding exactly when  $\Phi_v$  is not injective or  $D\Phi_v$  is not injective at some point. Let us consider the two failures separately:

If  $v$  is in the image of the map  $\beta_1 : (M \times M) \setminus \Delta_M \rightarrow S^{N-1}$  given by

$$\beta_1(p_1, p_2) = \frac{\Phi(p_2) - \Phi(p_1)}{\|\Phi(p_2) - \Phi(p_1)\|},$$

then  $\Phi_v$  will fail to be injective. Note however that  $\beta_1$  maps a  $2n$ -dimensional manifold to a  $N - 1$ -manifold, and if  $N > 2n + 1$  then baby Sard's theorem implies the image has measure zero.

The immersion condition is a local one, which we may analyze in a chart  $(U, \varphi)$ .  $\Phi_v$  will fail to be an immersion in  $U$  precisely when  $v$  coincides with a vector in the normalized image of  $D(\Phi \circ \varphi^{-1})$  where

$$\Phi \circ \varphi^{-1} : \varphi(U) \subset \mathbb{R}^n \rightarrow \mathbb{R}^N.$$

Hence we have a map (letting  $N(w) = \|w\|$ )

$$\frac{D(\Phi \circ \varphi^{-1})}{N \circ D(\Phi \circ \varphi^{-1})} : U \times S^{n-1} \rightarrow S^{N-1}.$$

The image has measure zero as long as  $2n - 1 < N - 1$ , which is certainly true since  $2n < N - 1$ . Taking union over countably many charts, we see that immersion fails on a set of measure zero in  $S^{N-1}$ .

Hence we see that  $\Phi_v$  fails to be an embedding for a set of  $v \in S^{N-1}$  of measure zero. Hence we may reduce  $N$  all the way to  $N = 2n + 1$ .  $\square$

**Corollary 1.48.** *We see from the proof that if we do not require injectivity but only that the manifold be immersed in  $\mathbb{R}^N$ , then we can take  $N = 2n$  instead of  $2n + 1$ .*