

# Geometric Fluid Dynamics

Henan University, Sept - Oct 2021

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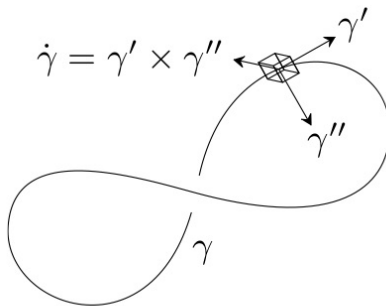
Lecture 7

# The binormal equation

Let  $\gamma \subset \mathbb{R}^3$  be a closed arc-length parametrized curve,  $\gamma = \gamma(s, t)$ .  
The *vortex filament* equation is

$$\partial_t \gamma = \gamma' \times \gamma'',$$

where  $\gamma' := \partial \gamma / \partial s$ .



Other names: Localized Induction Approximation (LIA) equation,  
Da Rios equations (1906)

# Vortex rings in nature

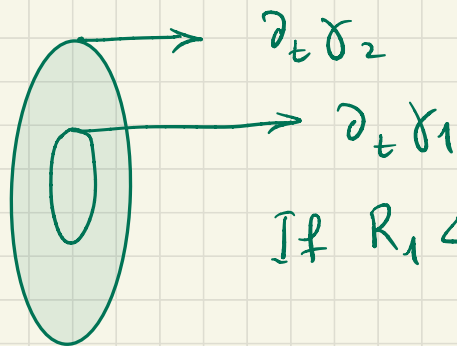


In any parametrization it is the *binormal equation*

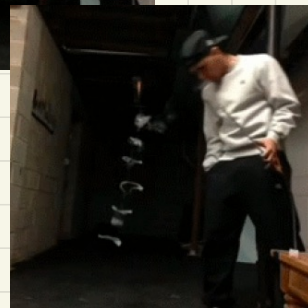
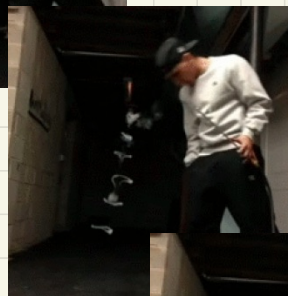
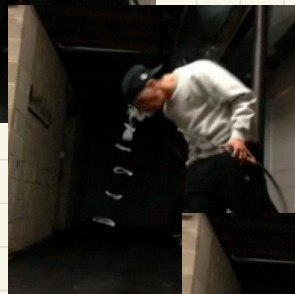
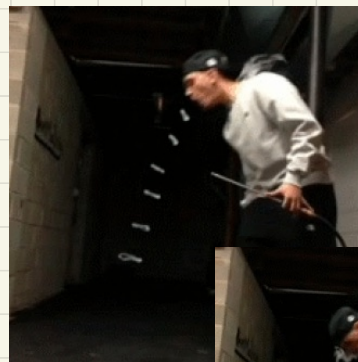
$$\partial_t \gamma = \kappa \mathbf{b},$$

where  $\kappa$  is the curvature of  $\gamma$  and  $\mathbf{b} = \mathbf{t} \times \mathbf{n}$  is the binormal unit vector at any point of  $\gamma$ .

**Rings of smaller radius move faster!**



$$\text{If } R_1 < R_2 \Rightarrow \underset{\substack{\text{"} \\ 1/R_1}}{\kappa_1} > \underset{\substack{\text{"} \\ 1/R_2}}{\kappa_2} \Rightarrow \partial_t \delta_1 > \partial_t \delta_2$$



# Properties of the binormal equation

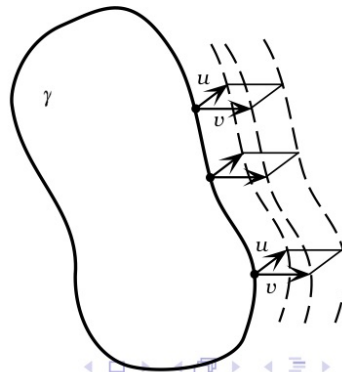
– it is **Hamiltonian**:

The Hamiltonian function is the *length*  $H(\gamma) = \int_{\gamma} |\gamma'(s)| ds$  of  $\gamma$ .

The symplectic structure is the *Marsden-Weinstein symplectic structure*  $\omega^{MW}$  on the space of knots:

$$\omega^{MW}(\gamma)(u, v) = \int_{\gamma} i_u i_v \mu = \int_{\gamma} \mu(u, v, \gamma') ds,$$

where  $u$  and  $v$  are two vector fields attached to  $\gamma$ , and  $\mu$  is the volume form in  $\mathbb{R}^3$ .



# Properties of the binormal equation

– **it is integrable:**

To a curve  $\gamma : \mathbb{R} \rightarrow \mathbb{R}^3$  with curvature  $\kappa$  and torsion  $\tau$ , the *Hasimoto transformation* assigns the following wave function  $\psi : \mathbb{R} \rightarrow \mathbb{C}$

$$(k(s), \tau(s)) \mapsto \psi(s) = \kappa(s) e^{i \int_{s_0}^s \tau(x) dx},$$

where  $s_0$  is some fixed point on the curve.

(The ambiguity in the choice of  $s_0$  defines the wave function  $\psi$  up to a phase.)

This Hasimoto map takes the binormal equation to the 1D nonlinear Schrödinger (NLS) equation on for  $\psi(\cdot, t) : \mathbb{R} \rightarrow \mathbb{C}$ :

$$i \partial_t \psi + \psi'' + \frac{1}{2} |\psi|^2 \psi = 0.$$

## Properties of the binormal equation

– **it is equivalent to a barotropic-type fluid**

Introduce the density  $\rho = \kappa^2$  and the velocity  $v = 2\tau$  for a curve  $\gamma$  governed by the binormal flow. Then  $\rho$  and  $v$  satisfy the system of compressible 1D fluid equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho v) = 0, \\ \partial_t v + v v' + \left( -\rho - 2 \frac{\sqrt{\rho}''}{\sqrt{\rho}} \right)' = 0. \end{cases}$$

Thus there is an equivalence of three evolution equations:

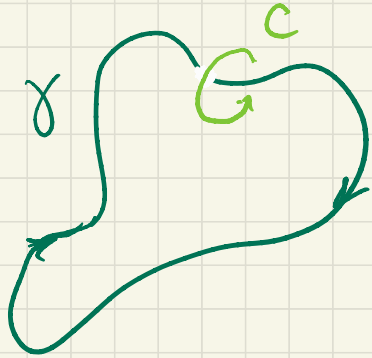
- the binormal equation
- the 1D nonlinear Schrödinger equation
- the 1D barotropic-type fluid equation.

What of this remains in higher dimensions?

## What is Localized Induction Approximation (LIA)?

Recall that in  $\mathbb{R}^3$  the Euler eq'n has the vorticity form:  $\partial_t \xi = -L_V \xi$  for the field  $\xi = \text{curl } v$ .

Let  $\xi$  be a singular vorticity, supported on a closed curve  $\gamma \subset \mathbb{R}^3$ .



Note: the Euler dynamics of  $\gamma$  is nonlocal: one needs to find  $v = \text{curl}^{-1} \xi$ , which is an integral operator.



Set  $\vec{\zeta} = c \delta_{\gamma}$  for the 2-form  $\delta_{\gamma}$  supported on  $\gamma \subset \mathbb{R}^3$ ,  
 $c$  is the flux of  $\vec{\zeta}$  across a small contour around  $\gamma$ .

Symbolically, 
$$\vec{\zeta}(x, t) = c \int_0^L \delta(x - \gamma(\theta, t)) \frac{\partial \gamma}{\partial \theta} d\theta$$

where  $\delta$  is the  $\delta$ -function in  $\mathbb{R}^3$ ,  $\theta$  is the arc-length parameter on  $\gamma$  (of length  $L$ ).

The Biot-Savart law gives for  $v(x, t) = \text{curl}^{-1} \vec{\zeta}(x, t)$ :

$$v(x, t) = -\frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{(x - \bar{x}) \times \vec{\zeta}(\bar{x})}{\|x - \bar{x}\|^3} d^3 \bar{x} = -\frac{c}{4\pi} \int_{\gamma} \frac{x - \gamma(\bar{\theta}, t)}{\|x - \gamma(\bar{\theta}, t)\|^3} \times \frac{\partial \gamma}{\partial \theta} d\bar{\theta}$$

Since the Euler equation is the evolution given by the velocity  $v$ ,  $\partial_t \gamma(\theta, t) = v(\gamma(\theta, t), t)$ , we have

$$\partial_t \gamma(\theta, t) = -\frac{c}{4\pi} \int \frac{\gamma(\theta, t) - \gamma(\bar{\theta}, t)}{\|\gamma(\theta, t) - \gamma(\bar{\theta}, t)\|^3} \times \frac{\partial \gamma}{\partial \theta} d\bar{\theta}$$

This integral diverges: it goes to  $\infty$  for small  $\theta - \bar{\theta}$ !

Indeed, consider the Taylor expansion:

$$\gamma(\theta) = \gamma(\bar{\theta}) + \frac{\partial \gamma}{\partial \theta} (\theta - \bar{\theta}) + \frac{1}{2} \frac{\partial^2 \gamma}{\partial \theta^2} (\theta - \bar{\theta})^2 + \dots$$

Then

$$\partial_t \gamma = -\frac{c}{4\pi} \int \frac{\frac{\partial \gamma}{\partial \theta} (\theta - \bar{\theta}) + \frac{1}{2} \frac{\partial^2 \gamma}{\partial \theta^2} (\theta - \bar{\theta})^2 + \dots}{|\theta - \bar{\theta}|^3} \times \frac{\partial \gamma}{\partial \theta} d\bar{\theta}, \text{ i.e.}$$

$$\partial_t \gamma = \frac{c}{8\pi} \left( \frac{\partial \gamma}{\partial \theta} \times \frac{\partial^2 \gamma}{\partial \theta^2} \right) \left[ \int_0^L \frac{d\bar{\theta}}{|\theta - \bar{\theta}|} + O(1) \right] \text{ as } \theta \rightarrow \bar{\theta}$$

This integral is  $\infty$ , but we apply a cut-off beyond

$$|\theta - \bar{\theta}| > \varepsilon, \text{ i.e. } \int_0^L \frac{d\bar{\theta}}{|\theta - \bar{\theta}|} \approx \int_{[-\varepsilon, \varepsilon]} \frac{d\bar{\theta}}{|\theta - \bar{\theta}|} + O(1) \approx \ln \varepsilon + O(1) \text{ as } \varepsilon \rightarrow 0$$

Now rescale time  $t \rightsquigarrow t \cdot \ln \varepsilon$  and obtain the (local)

filament equation  $\partial_t \gamma = \frac{\partial \gamma}{\partial \theta} \times \frac{\partial \gamma}{\partial \theta^2}$ , i.e.  $\partial_t \gamma = \gamma' \times \gamma''$

Rm For arc-length parameter

$$\gamma' = \vec{T} \text{ (unit tangent)}, \quad \gamma'' = k \cdot \vec{n} \text{ (unit normal)}, \quad \vec{b} = \vec{T} \times \vec{n} \text{ (unit binormal)}$$

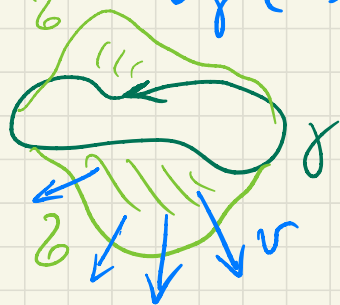
↑  
curvature of  $\gamma$

the filament equation is  $\partial_t \gamma = k \cdot \vec{b}$ , binormal equation, valid  $\forall$  parameter.

# The Marsden-Weinstein symplectic structure on knots

Def. An oriented curve  $\gamma \subset \mathbb{R}^3$  is a linear functional  $l_\gamma$  on div-free vector fields in  $\mathbb{R}^3$ :

$$l_\gamma(v) = \text{Flux } v \Big|_{\partial \mathcal{B}} = \int_{\mathcal{B}} i_v \mu, \text{ where } \mu \text{ - volume form in } \mathbb{R}^3,$$



$\mathcal{B}$  - oriented surface bounded by  $\gamma$ ,  $\partial \mathcal{B} = \gamma$ .

Prop  $l_\gamma(v)$  does not depend on the choice of  $\mathcal{B}$ , provided that  $\partial \mathcal{B} = \gamma$ .

Pf  $\int_{\mathcal{B}} i_v \mu - \int_{\tilde{\mathcal{B}}} i_v \mu = \int_{\mathcal{B} \cup \tilde{\mathcal{B}}} i_v \mu = 0$ , as a closed 2-form  $i_v \mu$  over a closed surface  $\mathcal{B} \cup \tilde{\mathcal{B}}$ .

(Recall:  $\text{div } \mu = L_v \mu = 0$ )

QED.

Rm Recall that for the Lie algebra  $\mathfrak{g} = \text{Vect}_\mu(\mathbb{R}^3)$  the dual space is  $\mathfrak{g}^* = \Omega^1 / d\Omega^0(\mathbb{R}^3) \simeq d\Omega^1(\mathbb{R}^3) \simeq \mathbb{Z}^2(\mathbb{R}^3)$ ,

the space of closed 2-forms in  $\mathbb{R}^3$ .

Let  $\omega_\gamma$  be the  $\delta$ -type 2-form supported on  $\gamma$ .

Then  $d^{-1}\omega_\gamma = \mu_\partial$ , i.e.  $\delta$ -type 1-form supported on  $\partial$ , where  $\partial\partial = \gamma$



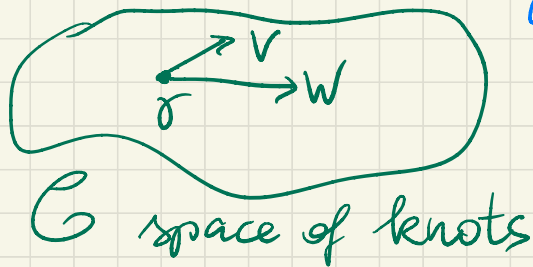
Note:

different choices of  $\partial$ , s.t.  $\partial\partial = \gamma \iff$  different choices of  $\mu_\partial = d^{-1}\omega_\gamma$

Prop The pairing of  $[U_2] \in \mathcal{O}_\gamma^x$  with  $v \in \mathcal{O}_\gamma = \text{Vect}_\mu(\mathbb{R}^3)$  coincides with the pairing of  $l_\gamma$  and  $v$ .

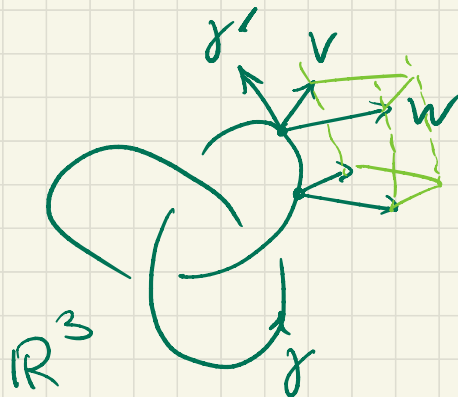
Pf  $\langle [U_2], v \rangle = \int_{\mathbb{R}^3} i_v U_2 \wedge \mu = \int_{\mathbb{R}^3} U_2 \wedge i_v \mu = \int_{\mathcal{O}} i_v \mu = \text{Flux } v \Big|_{\mathcal{O}}.$   
 QED

Exer The Kirillov-Kostant sympl. structure (or Lie-Poiss. str) on the orbit  $\mathcal{O}_\gamma$  coincides with the Marsden-Weinstein symplectic structure on the space of knots  $\mathcal{C}$ .



$$\omega_\gamma^{\text{MW}}(v, w) = \int_\gamma i_v i_w \mu$$

= volume of collar  $(v, w, \gamma')$



Pf sketch :  $\omega_{KK}(\xi_\gamma)(V, W) := \langle d^{-1}\xi, [V, W] \rangle$   
 $= \langle [u_2], [V, W] \rangle = \langle u_2, i_{[V, W]}\mu \rangle$

Note: for div-free vect. fields  $V, W$  one has  
 the identity :  $i_{[V, W]}\mu = d i_V i_W \mu$

Then  $\omega_{KK}(\xi_\gamma)(V, W) = \int_{\mathbb{R}^3} u_2 \wedge d i_V i_W \mu$

$= \int_{\mathbb{R}^3} d u_2 \wedge i_V i_W \mu = \int_{\mathbb{R}^3} \delta_\gamma \wedge i_V i_W \mu = \int_\gamma i_V i_W \mu$ . QED

$\overset{\text{"}}{\omega_\gamma} = \delta_\gamma$

To define dynamics on knots we fix the Euclidean metric in  $\mathbb{R}^3$ . Let  $H(\gamma) = \text{length}(\gamma) = \int \sqrt{(\gamma'(\theta), \gamma'(\theta))} d\theta$  be the Hamilton. f'n ( $\theta$ -arc-length)  $s'$

Prop The binormal eq'n  $\partial_t \gamma = \gamma' \times \gamma''$  is Hamiltonian on  $\mathcal{C}$  with Hamilton. f'n  $H(\gamma)$  and the Marsden-Weinstein symplectic str'vc  $\omega^{mw}$ .

Pf sketch.  $H(\gamma + \varepsilon v) = H(\gamma) + \varepsilon \left\langle \frac{\delta H}{\delta \gamma}, v \right\rangle + O(\varepsilon^2)$ ,  $\varepsilon \rightarrow 0$

Then the variational derivative  $\frac{\delta H}{\delta \gamma} = -\gamma''$  for arc-length  $\theta$ .

Hence  $\partial_t \gamma = s \text{grad } H = -J_\gamma \left( \frac{\delta H}{\delta \gamma} \right) = \gamma' \times \gamma''$ , where  $J$  is  $\frac{\pi}{2}$ -rotation in the normal plane to  $\gamma'$ , the almost complex str'vc. QED



$$J * := \gamma' \times *$$



Rm To see that  $\frac{\delta H}{\delta \gamma} = -\gamma''$  expand

$$H(\gamma + \varepsilon v) = \int_{S'} \sqrt{(\gamma' + \varepsilon v', \gamma' + \varepsilon v')} d\theta =$$

$$= \int_{S'} \sqrt{(\gamma', \gamma') + 2\varepsilon(\gamma', v') + O(\varepsilon^2)} d\theta$$

$1''$  for arc-length  $\theta$

$$= \int_{S'} \left(1 + \frac{1}{2} \cdot 2\varepsilon(\gamma', v') + O(\varepsilon^2)\right) d\theta = H(\gamma) - \varepsilon \int_{S'} (\gamma'', v) d\theta + O(\varepsilon^2)$$

Hence  $\frac{\delta H}{\delta \gamma} = -\gamma''$

# Vortex membranes

## Definition

Let  $\Sigma^n \subset \mathbb{R}^{n+2}$  be a codimension 2 membrane (i.e., a compact oriented submanifold of codimension 2 in  $\mathbb{R}^{n+2}$ ).

The *skew-mean-curvature (or, binormal) flow* of  $\Sigma$  is

$$\partial_t p = -J(\mathbf{MC}(p)),$$

where  $p \in \Sigma$ ,  $\mathbf{MC}(p)$  is the mean curvature vector to  $\Sigma$  at  $p$ , the operator  $J$  is the positive  $\pi/2$  rotation in the 2-dim normal plane  $N_p \Sigma$  at  $p$ .

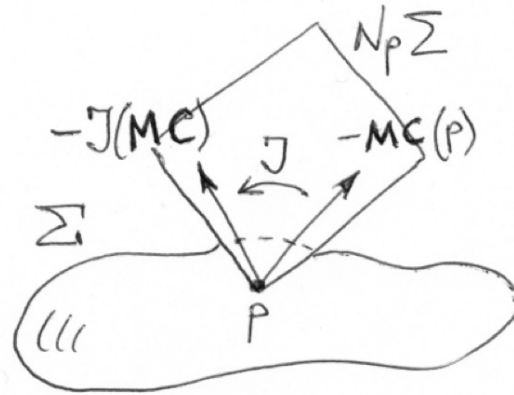
Note: It is a generalization of the binormal equation: in 1D  $\Sigma = \gamma$  is a curve,  $\mathbf{MC} = \kappa \mathbf{n}$ , where  $\kappa$  is the curvature of  $\gamma$ ,  
 $-J(\mathbf{MC}) = -J(\kappa \mathbf{n}) = \kappa \mathbf{b}$ .

## Theorem (Haller-Vizman, Shashikanth, K.)

The skew-mean-curvature flow  $\partial_t p = -J(\mathbf{MC}(p))$  is the Hamiltonian flow on the membrane space equipped with the Marsden-Weinstein structure and with the Hamiltonian given by the volume functional  $\text{vol}$ .

The mean curvature vector  $\mathbf{MC}(p)$  at  $p \in \Sigma \subset \mathbb{R}^{n+2}$  is the average geodesic curvature of  $\Sigma$  over all directions in  $T_p \Sigma$ .

**Corollary:** The skew-mean-curvature flow preserves  $\text{vol}(\Sigma)$ .



## Properties of the flow

– **it is Hamiltonian:**

The Hamiltonian function is the  $n$ -dim *volume*  $\text{vol}(\Sigma)$  of  $\Sigma \subset \mathbb{R}^{n+2}$ .

The *Marsden-Weinstein symplectic structure*  $\omega^{MW}$  on the space of codimension 2 membranes is

$$\omega^{MW}(\Sigma)(u, v) = \int_{\Sigma} i_u i_v \mu,$$

where  $u$  and  $v$  are two vector fields attached to the membrane  $\Sigma$ , and  $\mu$  is the volume form in  $\mathbb{R}^{n+2}$ .

## Idea of proof:

The Marsden-Weinstein symplectic structure is the averaging of the symplectic structures in all 2-dim normal planes  $N_p\Sigma$  to  $\Sigma$ . Hence the skew-gradient is obtained from the gradient field attached at  $\Sigma \subset \mathbb{R}^{n+2}$  by applying the fiberwise  $\pi/2$ -rotation operator  $J$  in  $N_p\Sigma$ .

On the other hand, the gradient for the volume functional  $\text{vol}(\Sigma)$  is  $-\mathbf{MC}(p)$  at  $p \in \Sigma$ . Hence the Hamiltonian field on membranes is given by  $-J(\mathbf{MC}(p))$  at any point  $p \in \Sigma$ . QED

**Question:** Is there an analogue of Hasimoto?

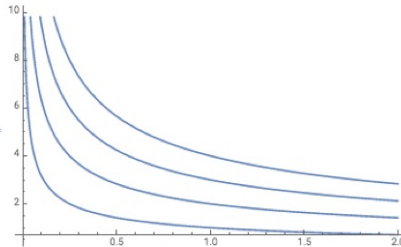
# The binormal flow for products of spheres

Let  $F : \Sigma = \mathbb{S}^m(a) \times \mathbb{S}^\ell(b) \hookrightarrow \mathbb{R}^{m+1} \times \mathbb{R}^{\ell+1} = \mathbb{R}^{m+\ell+2}$  be the product of two spheres of radiuses  $a$  and  $b$ .

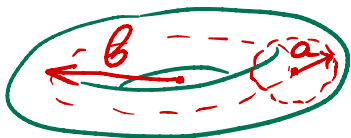
## Theorem (Yang-K.)

*The evolution  $F_t$  of this surface  $\Sigma$  in the binormal flow is the product of spheres  $F_t(\Sigma) = \mathbb{S}^m(a(t)) \times \mathbb{S}^\ell(b(t))$  at any  $t$  with radiuses changing monotonically according to the ODE system:*

$$\begin{cases} \dot{a} &= -\ell/b, \\ \dot{b} &= +m/a. \end{cases}$$

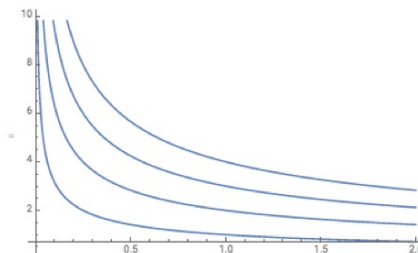


# Clifford tori as vortex membranes



$$\begin{aligned} a &\rightarrow 0 \\ b &\rightarrow \infty \end{aligned}$$

$$\begin{cases} \dot{a} = -\ell/b, \\ \dot{b} = +m/a. \end{cases}$$



## Corollary

For  $m = \ell$  one has  $a(t) = ae^{-t/(ab)}$  and  $b(t) = be^{mt/(ab)}$ , the solutions exist for all  $t \in \mathbb{R}$ .

**Example:** Clifford torus  $T^2 = S^1 \times S^1 \subset \mathbb{R}^4$ .

## Example of collapse for products of spheres

### Corollary

For  $0 < m < \ell$  the corresponding solution  $F_t$  is

$$a(t) = a^{m/(m-\ell)} (a - (\ell - m)b^{-1}t)^{\ell/(\ell-m)} \quad \text{and}$$

$$b(t) = b^{\ell/(\ell-m)} (b + (m - \ell)a^{-1}t)^{m/(m-\ell)}.$$

It exists only for finite time and collapses at  $t = a(0)b(0)/(\ell - m)$ .

**Example:** The simplest case of  $0 < m < \ell$  is  $m = 1, \ell = 2$  for  $\mathbb{S}^1(a) \times \mathbb{S}^2(b) \subset \mathbb{R}^5$ .

**Remark:** Since the skew-mean-curvature flow is the LIA of the Euler equation, this collapse in 5D might be indicative for the Euler singularity problem in higher dimensions.



# The Euler equation of an ideal fluid

For an inviscid incompressible fluid filling a Riemannian manifold  $M$  the fluid motion is described by the classical *Euler equation* on its velocity  $v$ :

$$\partial_t v + \nabla_v v = -\nabla p.$$

Here  $\operatorname{div} v = 0$  and  $v$  is tangent to  $\partial M$ .  $\nabla_v v$  is the Riemannian covariant derivative.

In any dimension, the *vorticity is the 2-form*  $\xi := dv^b$ , where  $v^b$  is the 1-form metric-related to the vector field  $v$ . In 3D  $\xi = \operatorname{curl} v$ .

The *vorticity form of the Euler equation* is

$$\partial_t \xi + L_v \xi = 0,$$

where  $L_v$  is the Lie derivative. It means that the vorticity is transported by (or “frozen into”) the fluid flow.

# Generalized Biot-Savart formula

Consider the vorticity 2-form  $\xi_\Sigma = \delta_\Sigma$  supported on a membrane  $\Sigma^n \subset \mathbb{R}^{n+2}$ .

We need to find the divergence-free field  $v$  with prescribed vorticity 2-form  $\xi$ , i.e.  $\xi_\Sigma = dv^\flat \in \Omega^2(\mathbb{R}^{n+2})$ . In 3D  $v = \text{curl}^{-1}\xi$  is the field-potential given by the Biot-Savart formula.

**Theorem (Shashikanth for 4D, K. for any D)**

*In any dim, vector field  $v$  in  $\mathbb{R}^{n+2}$  satisfying  $\text{curl } v = \xi_\Sigma$  and  $\text{div } v = 0$  is given by the generalized Biot-Savart formula:  $\forall q \notin \Sigma$*

$$v(q) := C_n \cdot \int_{\Sigma} J(\text{Proj}_N \nabla_p G(q, p)) \mu_{\Sigma}(p),$$

*where  $\text{Proj}_N \nabla_p G(\cdot, p)$  is the projection of  $\nabla_p G(\cdot, p)$  of the Green function  $G(\cdot, p)$  to the normal plane  $N_p \Sigma$  at  $p \in \Sigma$ , and  $\mu_{\Sigma}$  is the induced Riemannian volume on  $\Sigma \subset \mathbb{R}^{n+2}$ .*

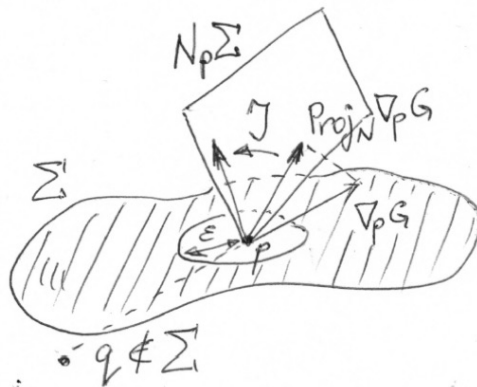
# Regularization of velocity

As  $q \rightarrow \Sigma$  the vector field  $v(q) \rightarrow \infty$ . Given  $\epsilon > 0$ , consider the truncation: for  $q \in \Sigma$  take the integral not over  $\Sigma$  but over all points  $p \in \Sigma$  at the distance at least  $\epsilon$  from  $q$ :

$$v_\epsilon(q) := C_n \cdot \int_{\{p \in \Sigma, \|q-p\| \geq \epsilon\}} J(\text{Proj}_N \nabla_p G(q, p)) \mu_\Sigma(p).$$

It is a *localized induction approximation* of  $v$ .  
Similarly *regularize the energy*:

$$E_\epsilon(v) := \frac{1}{2} \int_{\mathbb{R}^{n+2}} (v, v_\epsilon) \mu,$$



# Localized Induction Approximation theorem

Theorem (Shashikanth for 4D, K. for any D)

For any dim and a membrane  $\Sigma \subset \mathbb{R}^{n+2}$

i) the velocity  $v$  satisfying  $\xi_\Sigma = dv^b$  has the LIA truncation  $v_\epsilon$ : for  $q \in \Sigma \subset \mathbb{R}^{n+2}$  one has

$$\lim_{\epsilon \rightarrow 0} \frac{v_\epsilon(q)}{\ln \epsilon} = C_n \cdot J(\mathbf{MC}(q)) ;$$

ii) the regularized energy  $E_\epsilon(v)$  for the velocity of  $\Sigma$  has the asymptotics:

$$\lim_{\epsilon \rightarrow 0} \frac{E_\epsilon(v)}{\ln \epsilon} = C_n \cdot \int_\Sigma \mu_P = C_n \cdot \text{volume}(\Sigma).$$

**Question:** Relation to 5D Euler?