RESONANT DECOMPOSITIONS AND THE I-METHOD FOR THE CUBIC NLS ON R^2

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1. Cubic NLS Initial Value Problem on \mathbb{R}^2

We consider the initial value problems:

$$\begin{cases} (i\partial_t + \Delta)u = \pm |u|^2 u \\ u(0, x) = u_0(x). \end{cases}$$
 (NLS₃[±](ℝ²))

The + case is called defocusing; – is focusing. NLS_3^{\pm} is ubiquitous in physics. The solution has a dilation symmetry

$$u^{\lambda}(\tau, y) = \lambda^{-1} u(\lambda^{-2}\tau, \lambda^{-1}y).$$
 Scaling

which is invariant in $L^2(\mathbb{R}^2)$. This problem is L^2 -critical.

TIME INVARIANT QUANTITIES

$$\begin{aligned} \mathsf{Mass} &= \int_{\mathbb{R}^d} |u(t,x)|^2 dx. \\ \mathsf{Momentum} &= 2\Im \int_{\mathbb{R}^2} \overline{u}(t) \nabla u(t) dx. \\ \mathsf{Energy} &= H[u(t)] = \frac{1}{2} \int_{\mathbb{R}^2} |\nabla u(t)|^2 dx \pm \frac{1}{2} |u(t)|^4 dx. \end{aligned}$$

- Mass is L^2 ; Momentum is close to $H^{1/2}$; Energy involves H^1 .
- Dynamics on a sphere in L²; focusing/defocusing energy.
- Local conservation laws express **how** quantity is conserved: e.g., $\partial_t |u|^2 = \nabla \cdot 2\Im(\overline{u}\nabla u)$. Frequency Localizations?

Local-in-time theory for $NLS_3^{\pm}(\mathbb{R}^2)$

•
$$\forall \ u_0 \in L^2(\mathbb{R}^2) \ \exists \ \mathcal{T}_{lwp}(u_0)$$
 determined by

Strichartz
$$\|e^{it\Delta}u_0\|_{L^4_{tx}([0,T_{lwp}]\times\mathbb{R}^2)} < \frac{1}{100}$$
 such that

∃ unique $u \in C([0, T_{lwp}]; L^2) \cap L^4_{tx}([0, T_{lwp}] \times \mathbb{R}^2)$ solving $NLS_3^+(\mathbb{R}^2)$.

- $\forall u_0 \in H^s(\mathbb{R}^2), s > 0, T_{lwp} \sim ||u_0||_{H^s}^{-\frac{2}{s}}$ and regularity persists: $u \in C([0, T_{lwp}]; H^s(\mathbb{R}^2)).$
- Define the maximal forward existence time $T^*(u_0)$ by

$$\|u\|_{L^4_{tx}([0,T^*-\delta]\times\mathbb{R}^2)}<\infty$$

for all $\delta > 0$ but diverges to ∞ as $\delta \searrow 0$.

• \exists small data scattering threshold $\mu_0 > 0$

$$||u_0||_{L^2} < \mu_0 \implies ||u||_{L^4_{tx}(\mathbb{R}\times\mathbb{R}^2)} < 2\mu_0.$$

What is the ultimate fate of the local-in-time solutions?

 $\begin{array}{l} \underbrace{L^2\text{-critical Scattering Conjecture:}}_{L^2 \ni u_0 \longmapsto u \text{ solving } NLS_3^+(\mathbb{R}^2) \text{ is global-in-time and} \\ \|u\|_{L^4_{t,x}} < A(u_0) < \infty. \end{array}$ Moreover, $\exists \ u_{\pm} \in L^2(\mathbb{R}^2)$ such that $\begin{array}{c} \text{Asymptotic} \\ \text{Representation} \\ \\ \lim_{t \to \pm \infty} \|e^{\pm it\Delta}u_{\pm} - u(t)\|_{L^2(\mathbb{R}^2)} = 0. \end{array}$

Same statement for focusing $NLS_3^-(\mathbb{R}^2)$ if $||u_0||_{L^2} < ||Q||_{L^2}$. Remarks:

- Known for small data $||u_0||_{L^2(\mathbb{R}^2)} < \mu_0$.
- Known for large radial data [Killip-Tao-Visan 07].

$NLS_3^{\pm}(\mathbb{R}^2)$: Present Status for General Data

regularity	idea	reference
$s > \frac{2}{3}$	high/low frequency decomposition	[Bourgain98]
$s > \frac{4}{7}$	H(lu)	[CKSTT02]
$s > \frac{1}{2}$	resonant cut of 2nd energy	[CKSTT07]
$s \geq \frac{1}{2}$	H(Iu) & Interaction Morawetz	[Fang-Grillakis05]
$s > \frac{2}{5}$	H(Iu) & Interaction I-Morawetz	[CGTz07]
$s > \frac{1}{3}$	resonant cut & <i>I</i> -Morawetz	[C-Roy08]
<i>s</i> > 0?		

- Morawetz-based arguments are only for defocusing case.
- Focusing results assume $||u_0||_{L^2} < ||Q||_{L^2}$.
- Unify theory of focusing-under-ground-state and defocusing?

H^1 Global Well-Posedness Scheme

Consider $NLS_3^{\pm}(\mathbb{R}^2)$ with finite energy data $u_0 \in H^1$. Classical H^1 -GWP Scheme relies on three inputs:

- **1** LWP lifetime dependence on data norm: $T_{lwp} \sim ||u_0||_{H^s}^{-2/s}$.
- **2** Energy controls data norm: $||u(t)||_{H^1}^2 \lesssim H[u(t)] + ||u(t)||_{L^2}^2$.
- **B** Conservation: $H[u(t)] + ||u(t)||_{L^2}^2 \leq C(Energy, Mass).$

Fix arbitrary time interval [0, T]. Break [0, T] into subintervals of uniform size c(Energy, Mass) + LWP iteration \implies GWP.

For $u_0 \in H^s$ with 0 < s < 1, we may have infinite energy. Classical persistence of regularity from LWP/Duhamel only gives

$$\sup_{t\in[0,T_{lwp}]}\|u(t)\|_{H^s}\lesssim 2\|u_0\|_{H^s}$$

and LWP iteration fails due to (possible) doubling. [Bourgain98]

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Refinements of Strichartz' Inequality and Applications to 2D-NLS with Critical Nonlinearity

J. Bourgain

Summary

Consider the 2D IVP

$$\begin{split} & \mathrm{i} \mathrm{u}_{\mathrm{t}} + \Delta \mathrm{u} + \lambda |\mathrm{u}|^2 \mathrm{u} = 0 \\ & \mathrm{u}(0) = \varphi \in \mathrm{L}^2(\mathbb{R}^2). \end{split} \tag{t}$$

The theory on the Cauchy problem asserts a unique maximal solution

 $u \in \mathcal{C}(] - T_*, T^*[, L^2(\mathbb{R}^2)) \cap L^4(] - T_*, T^*[; L^4(\mathbb{R}^2)),$

where T T* > 0 Assume for instance T* $< \infty$ It is shown then that

2. Abstract *I*-method Scheme for H^{s} -GWP

Let $H^s \ni u_0 \longmapsto u$ solve *NLS* for $t \in [0, T_{lwp}], T_{lwp} \sim ||u_0||_{H^s}^{-2/s}$. Consider two ingredients (to be defined):

- A smoothing operator $I = I_N : H^s \mapsto H^1$. The *NLS* evolution $u_0 \mapsto u$ induces a smooth reference evolution $H^1 \ni Iu_0 \mapsto Iu$ solving I(NLS) equation on $[0, T_{Iwp}]$.
- A modified energy $\tilde{E}[lu]$ built using the reference evolution.

We postpone how we actually choose these objects.

For $s < 1, N \gg 1$ define smooth monotone $m : \mathbb{R}^2_{\mathcal{E}} \to \mathbb{R}^+$ s.t.

$$m(\xi) = \begin{cases} 1 & \text{for } |\xi| < N\\ \left(\frac{|\xi|}{N}\right)^{s-1} & \text{for } |\xi| > 2N. \end{cases}$$

The associated Fourier multiplier operator, $(Iu)(\xi) = m(\xi)\hat{u}(\xi)$, satisfies $I : H^s \to H^1$. Note that, pointwise in time, we have

$$\|u\|_{H^{s}} \lesssim \|Iu\|_{H^{1}} \lesssim N^{1-s} \|u\|_{H^{s}}.$$

Set $\widetilde{E}[Iu(t)] = H[Iu(t)]$. Other choices of \widetilde{E} are considered later.

AC LAW DECAY AND SOBOLEV GWP INDEX

- **1** Modified LWP. Initial v_0 s.t. $\|\nabla I v_0\|_{L^2} \sim 1$ has $T_{Iwp} \sim 1$.
- **2** Goal. $\forall u_0 \in H^s, \forall T > 0$, construct $u : [0, T] \times \mathbb{R}^2 \to \mathbb{C}$.
- **B** \iff **Dilated Goal.** Construct $u^{\lambda} : [0, \lambda^2 T] \times \mathbb{R}^2 \to \mathbb{C}$.
- **4** Rescale Data. $\| I \nabla u_0^{\lambda} \|_{L^2} \lesssim N^{1-s} \lambda^{-s} \| u_0 \|_{H^s} \sim 1$ provided we choose $\lambda = \lambda(N) \sim N^{\frac{1-s}{s}} \iff N^{1-s} \lambda^{-s} \sim 1$.
- **5** Almost Conservation Law. $||I \nabla u(t)||_{L^2} \leq H[Iu(t)]$ and

$$\sup_{t\in[0,T_{lwp}]}H[lu(t)]\leq H[lu(0)]+N^{-\alpha}$$

6 Delay of Data Doubling. Iterate modified LWP N^{α} steps with $T_{lwp} \sim 1$. We obtain rescaled solution for $t \in [0, N^{\alpha}]$.

$$\lambda^2(N)T < N^{lpha} \iff T < N^{lpha + rac{2(s-1)}{s}} ext{ so } s > rac{2}{2+lpha} ext{ suffices}.$$

A Fourier analysis established the almost conservation property of $\tilde{E} = H[Iu]$ with $\alpha = \frac{3}{2}$ which led to...

THEOREM (CKSTT 02)

 $NLS_{3}^{+}(\mathbb{R}^{2})$ is globally well-posed for data in $H^{s}(\mathbb{R}^{2})$ for $\frac{4}{7} < s < 1$. Moreover, $\|u(t)\|_{H^{s}} \lesssim \langle t \rangle^{\beta(s)}$ for appropriate $\beta(s)$.

- Same result for NLS₃[−](ℝ²) if ||u₀||_{L²} < ||Q||_{L²}. Here Q is the ground state (unique positive solution of −Q + ΔQ = −Q³).
- Fourier analysis leading to $\alpha = \frac{3}{2}$ in fact gives $\alpha = 2$ for most frequency interactions.

Almost Conservation Law for H[lu]

PROPOSITION

Given $s > \frac{4}{7}$, $N \gg 1$, and initial data $\phi_0 \in C_0^{\infty}(\mathbb{R}^2)$ with $E(I_N u_0) \leq 1$, then there exists a $T_{Iwp} \sim 1$ so that the solution

 $u(t,x) \in C([0, T_{lwp}], H^{s}(\mathbb{R}^{2}))$

of $NLS_3^+(\mathbb{R}^2)$ satisfies

 $E(I_N u)(t) = E(I_N u)(0) + O(N^{-\frac{3}{2}+}),$ for all $t \in [0, T_{lwp}].$

IDEAS IN THE PROOF OF ALMOST CONSERVATION

Standard Energy Conservation Calculation:

• For the smoothed reference evolution, we imitate.... $\partial_t H(lu) = \Re \int_{\mathbb{R}^2} \overline{lu_t} (|lu|^2 lu - \underline{\Delta lu} - \underline{lu_t}) dx$ $= \Re \int_{\mathbb{R}^2} \overline{lu_t} (|lu|^2 lu - l(|u|^2 u)) dx \neq 0.$

The increment in modified energy involves a commutator,

$$H(Iu)(t) - H(Iu)(0) = \Re \int_0^t \int_{\mathbb{R}^2} \overline{Iu_t}(|Iu|^2 Iu - I(|u|^2 u)) dx dt.$$

■ Littlewood-Paley, Case-by-Case, (Bi)linear Strichartz, X_{s,b}....

Remarks

The almost conservation property

$$\sup_{t\in[0,\mathcal{T}_{lwp}]}\widetilde{E}[lu(t)]\leq\widetilde{E}[lu_0]+N^{-\alpha}$$

leads to GWP for

$$s > s_{\alpha} = \frac{2}{2+\alpha}.$$

- The *I*-method is a *subcritical method*. To prove the Scattering Conjecture at *s* = 0 via the *I*-method would require α = +∞.
- The *I*-method *localizes the conserved density in frequency*. Similar ideas appear in recent critical scattering results.
- There is a *multilinear corrections algorithm* for defining new choices of \tilde{E} which should have a better AC property.

Focusing Case Below the Ground State Mass

- Modified LWP lifetime is controlled by $||I \nabla u_0||_{L^2}$.
- The GWP scheme progresses if $||I \nabla u(t)||_{L^2}^2 \lesssim H[Iu(t)]$.
- Weinstein's optimal Gagliardo-Nirenberg Inequality:

$$\|w\|_{L^4}^4 \leq \frac{2}{\|Q\|_{L^2}^2} \|w\|_{L^2}^2 \|\nabla w\|_{L^2}^2.$$

• I has symbol m satisfying $|m| \leq 1$ so $||If||_{L^2} \leq ||f||_{L^2}$. Thus,

$$\|u_0\|_{L^2} < \|Q\|_{L^2} \implies \|Iu_0\|_{L^2} < \|Q\|_{L^2}.$$

The required control then follows:

$$||u_0||_{L^2} < ||Q||_{L^2} \implies ||I \nabla u(t)||_{L^2}^2 \lesssim H[Iu(t)].$$

3. Multilinear Correction Terms

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(Inspired by [Coifman-Meyer]; following [CKSTT:KdV]) **1** For $k \in \mathbb{N}$, define the *convolution hypersurface*

$$\Sigma_k := \{ (\xi_1,\ldots,\xi_k) \in (\mathbb{R}^2)^k : \xi_1 + \ldots + \xi_k = 0 \} \subset (\mathbb{R}^2)^k.$$

2 For $M : \Sigma_k \to \mathbb{C}$ and u_1, \ldots, u_k nice, define *k*-linear functional

$$\Lambda_k(M; u_1, \ldots, u_k) := c_k \, \Re \int_{\Sigma_k} M(\xi_1, \ldots, \xi_k) \widehat{u_1}(\xi_1) \ldots \widehat{u_k}(\xi_k).$$

B For $k \in 2\mathbb{N}$ abbreviate $\Lambda_k(M; u) = \Lambda_k(M; u, \overline{u}, \dots, \overline{u})$.

4 $\Lambda_k(M; u)$ invariant under interchange of even/odd arguments,

$$M(\xi_1,\xi_2,\ldots,\xi_{k-1},\xi_k)\mapsto \overline{M}(\xi_2,\xi_1,\ldots,\xi_k,\xi_{k-1}).$$

5 We can define a symmetrization rule via group orbit.

EXAMPLES

$\int u\overline{u}u\overline{u}dx = \int (\int e^{ix\cdot\xi_1}\widehat{u}(\xi_1)d\xi_1)\dots(\int e^{ix\cdot\xi_4}\widehat{\overline{u}}(\xi_4)d\xi_4)dx$ $= \int_{\xi_1,\ldots,\xi_4} \left[\int_{x} e^{ix \cdot (\xi_1 + \xi_2 + \xi_3 + \xi_4)} dx \right] \widehat{u}(\xi_1) \widehat{\overline{u}}(\xi_2) \widehat{u}(\xi_3) \widehat{\overline{u}}(\xi_4) d\xi_{1,\ldots,4}$ $=\int \widehat{u}(\xi_1)\widehat{\overline{u}}(\xi_2)\widehat{u}(\xi_3)\widehat{\overline{u}}(\xi_4)=\Lambda_4(1;u).$ $\Lambda_2(-\xi_1 \cdot \xi_2; u) = \|\nabla u\|_{L^2}^2$

Thus, $H[u] = \Lambda_2(-\xi_1 \cdot \xi_2; u) \pm \Lambda_4(\frac{1}{2}; u).$

Suppose *u* nicely solves $NLS_3^+(\mathbb{R}^2)$; *M* is time independent, symmetric. Calculations produce the *time differentiation formula*

$$\partial_t \Lambda_k(M; u(t)) = \Lambda_k(iM\alpha_k; u(t)) - \Lambda_{k+2}(ikX(M); u(t)) = \Lambda_k(iM\alpha_k; u(t)) - \Lambda_{k+2}([ikX(M)]_{sym}; u(t)).$$

Here

$$\alpha_k(\xi_1,\ldots,\xi_k) := -|\xi_1|^2 + |\xi_2|^2 - \ldots - |\xi_{k-1}|^2 + |\xi_k|^2$$

(so $\alpha_2 = 0$ on Σ_2) and

$$X(M)(\xi_1,\ldots,\xi_{k+2}) := M(\xi_{123},\xi_4,\ldots,\xi_{k+2}).$$

We use the notation $\xi_{ab} := \xi_a + \xi_b$, $\xi_{abc} := \xi_a + \xi_b + \xi_c$, etc.

Exercise: Conservation of Energy

Verify, using the time differentiation formula,

$$\partial_t \Lambda_k(M; u(t)) = \Lambda_k(iM\alpha_k; u(t)) - \Lambda_{k+2}(ikX(M); u(t)) = \Lambda_k(iM\alpha_k; u(t)) - \Lambda_{k+2}([ikX(M)]_{sym}; u(t)).$$

that the Hamiltonian

$$H[u] = \Lambda_2(-\xi_1 \cdot \xi_2; u) \pm \Lambda_4(\frac{1}{2}; u)$$

is conserved.

• Abbreviate $m(\xi_j)$ as m_j . Define σ_2 s.t. $\|I \nabla u\|_{L^2}^2 = \Lambda_2(\sigma_2; u)$:

$$\sigma_2(\xi_1,\xi_2) := -\frac{1}{2}\xi_1 m_1 \cdot \xi_2 m_2 = \frac{1}{2}|\xi_1|^2 m_1^2$$

• With $\tilde{\sigma}_4$ (symmetric, time independent) to be determined, set

$$\widetilde{E} := \Lambda_2(\sigma_2; u) + \Lambda_4(\widetilde{\sigma}_4; u).$$

Using the time differentiation formula, we calculate

$$\partial_t \widetilde{E} = \Lambda_4(\{i\widetilde{\sigma}_4\alpha_4 - i2[X(\sigma_2)]_{sym}\}; u) - \Lambda_6([i4X(\widetilde{\sigma}_4)]_{sym}; u).$$

We'd like to define $\tilde{\sigma}_4$ to cancel away the Λ_4 contribution.

SMALL DIVISOR PROBLEM

Resonant interactions obstruct the natural choice:

$$\tilde{\sigma}_4 = \frac{[2iX(\sigma_2)]_{sym}}{i\alpha_4}.$$
 impossible!

On $\Sigma_4,$ we can reexpress $\alpha_4=-|\xi_1|^2+|\xi_2|^2-|\xi_3|^2+|\xi_4|^2$ as

$$\alpha_4 = -2\xi_{12} \cdot \xi_{14} = -2|\xi_{12}||\xi_{14}| \cos \angle (\xi_{12}, \xi_{14}),$$

and

$$[2iX(\sigma_2)]_{sym} = rac{1}{4}(-m_1^2|\xi_1|^2+m_2^2|\xi_2|^2-m_3^2|\xi_3|^2+m_4^2|\xi_4|^2).$$

When all the $m_j = 1$ (so max_j $|\xi_j| < N$), $\tilde{\sigma}_4$ is well-defined. However, α_4 can also vanish when ξ_{12} and ξ_{14} are orthogonal. For $NLS_3^+(\mathbb{R})$, the resonant obstruction disappears. Thus,

$$\widetilde{E}^1 = \Lambda_2(\sigma_2) + \Lambda_4(\widetilde{\sigma}_4);$$

 $\partial_t \widetilde{E}^1 = -\Lambda_6([i4X(\widetilde{\sigma}_4)]_{sym}).$

We can then define, with $\tilde{\sigma}_6$ to be determined,

$$\widetilde{E}^2 = \widetilde{E}^1 + \Lambda_6(\widetilde{\sigma}_6);$$

 $\partial_t \tilde{E}^2 = \Lambda_6(\{i\tilde{\sigma}_6\alpha_6 - [i4X(\tilde{\sigma}_4)]_{sym}\}) + \Lambda_8([i6X(\tilde{\sigma}_6)]_{sym}).$ Let's define

$$\tilde{\sigma}_6 = \frac{[i4X(\tilde{\sigma}_4)]_{sym}}{i\alpha_6}.$$

REMARK: INTEGRABLE SYSTEMS CONNECTION?

Thus, we formally obtain a continued-fraction-like algorithm.

$$\tilde{\sigma}_{6} = \frac{\left[i4X\left(\frac{[2iX(\sigma_{2})]_{sym}}{i\alpha_{4}}\right)\right]_{sym}}{i\alpha_{6}},$$

$$\tilde{\sigma}_{8} = \frac{\left[i6X\left(\frac{\left[i4X\left(\frac{[2iX(\sigma_{2})]_{sym}}{i\alpha_{4}}\right)\right]_{sym}}{i\alpha_{6}}\right)\right]_{sym}}{i\alpha_{8}}, \dots$$

Each step gains two derivatives but costs two more factors. This is a big gain!

Conjecture: The multipliers $\tilde{\sigma}_6, \tilde{\sigma}_8, \ldots$ are well defined and lead to better AC properties. Same for other integrable systems?

4. RESONANT DECOMPOSITION

4. RESONANT DECOMPOSITION

We return to $NLS_3^+(\mathbb{R}^2)$. Since the natural choice is not well-defined, we choose

$$ilde{\sigma}_4 := rac{[2iX(\sigma_2)]_{sym}}{ilpha_4} \ \chi_{\Omega_{nr}}$$

where the non-resonant set $\Omega_{nr} \subset \Sigma_4$ such that

$$\Omega_{nr} := \{ \max_{1 \le j \le 4} |\xi_j| \le N \} \cup \{ |\cos \angle (\xi_{12}, \xi_{14})| \ge \theta_0 \}.$$

Eventually, we choose θ_0 to balance the 4-linear and 6-linear contributions to the modified energy increment. We have

$$\partial_t \widetilde{E} = \Lambda_4(\{i\widetilde{\sigma}_4\alpha_4 - i2[X(\sigma_2)]_{sym}\}; u) - \Lambda_6([i4X(\widetilde{\sigma}_4)]_{sym}; u).$$

The 4-linear contribution is constrained to the resonant set Ω_{nr}^{C} .

Lemma

If $||u_0||_{L^2_x(\mathbb{R}^2)} \leq A$; $E(lu_0) \leq 1$; u is a nice solution of $NLS^+_3(\mathbb{R}^2)$ on a time interval $[0, t_0]$, then if $t_0 = t_0(A)$ is small enough,

$$\begin{vmatrix} \int_{0}^{t_{0}} \Lambda_{4}([-2iX(\sigma_{2})]_{sym} + i\tilde{\sigma}_{4}\alpha_{4}; u(t)) dt \end{vmatrix}$$

+
$$\begin{vmatrix} \int_{0}^{t_{0}} \Lambda_{6}([4iX(\tilde{\sigma}_{4})]_{sym}; u(t)) dt \end{vmatrix}$$

$$\lesssim C(A)[N^{-2+} + \theta_{0}^{1/2}N^{-3/2+} + \theta_{0}^{-1}N^{-3+}]$$

The choice $\theta_0 = N^{-1}$ produces the AC property with $\alpha = 2$.

N^{-2} AC law!

OVERVIEW AND DELICATE CASE OF PROOF

The 4-linear contribution has multiplier

$$([-2iX(\sigma_2)]_{sym} + i\tilde{\sigma}_4\alpha_4)(\xi) = [-2iX(\sigma_2)]_{sym}\chi_{\Omega_r}$$

where the *resonant set* $\Omega_r = \Omega_{nr}^C \subset \Sigma_4$,

 $\Omega_r := \{\max(|\xi_1|, |\xi_2|, |\xi_3|, |\xi_4|) > N; |\cos \angle (\xi_{12}, \xi_{14})| < \theta_0\}.$

We wish to bound the associated energy incremement

$$\int_0^{T_{lwp}} \Lambda_4([-2iX(\sigma_2)]_{sym}\chi_{\Omega_r};u)dt.$$

- The 4 factors u are dyadically decomposed. The integral is studied case-by-case based on dyadic frequency sizes.
- On Σ_4 , the two largest frequencies are comparable.

OVERVIEW AND DELICATE CASE OF PROOF

Let |ξ_j| ~ N_j ∈ 2^ℤ. Symmetry properties and the Ω_r constraint allow to assume

$$N_1 \sim N_2 \gtrsim N, N_2 \gtrsim N_3 \gtrsim N_4 \gtrsim 1.$$

For most cases, suffices to use (enhanced) [CKSTT 02] and

Lemma

 $\forall (\xi_1,\xi_2,\xi_3,\xi_4) \in \Sigma_4$,

 $|[2iX(\sigma_2)]_{sym}| \lesssim \min(m_1, m_2, m_3, m_4)^2 |\xi_{12}| |\xi_{14}|.$

This follows from the mean value theorem.

OVERVIEW AND DELICATE CASE OF PROOF

The most delicate case occurs in Ω_r and when



A REMARK ON NORMAL FORMS AND THE "I-METHOD" FOR PERIODIC NLS

By

JEAN BOURGAIN

0 Introduction

different from) that to establish LWP results in $H^{s}(\mathbb{T})$, s > 0 (the key ingredient is again Strichartz' inequality). For self containedness sake, this analysis is repeated here in §7 (Appendix).

In principle, once the appropriate normal form is obtained, the estimates are direct and purely spatial. The main point is that now the remaining monomials in the nonlinearity satisfy certain specific frequency configurations, which allow us to improve on the I-method approach. This is exactly how we proceed to establish GWP in H^s , $s > \frac{1}{2}$. To go beyond this, we rely on a refined bilinear (or trilinear) Strichartz inequality with different frequency ranges for the factors; see §4. We only prove a qualitative statement, and it would be worth extracting a precise formulation. The actual proof of GWP for $s < \frac{1}{2}$ proceeds in two stages. We first carry out the preceding analysis, upgraded with the improved Strichartz inequality, for a truncated equation $|n| \leq N_1$ (§5). The full equation is then treated perturbatively in §6 along a scheme similar to that in [Bo4] but replacing the usual Hamiltonian by the almost conserved quantities studied in §5. Possibly, this part of the analysis could be avoided by modifying the framework of §5 to avoid the need of restricting Fourier modes. Rather than trying this, we return in §6 to spacetime estimates, following a scheme that, while perhaps not technically obvious, is conceptually rather familiar (cf. [Bo4], [St]).

Angle constraint in Ω_r gives better estimates based on two effects:

- Cancellation with $[X(\sigma_2)]_{sym}$,
- Angular refinement of Bilinear Strichartz.

We use a refinement exploiting spherical symmetry of m.

LEMMA Let N_1, \ldots, N_4 be in the delicate case with $(\xi_1, \xi_2, \xi_3, \xi_4) \in \Omega_r$. Then $|[X(\sigma_2)]_{svm}| \lesssim m(N_1)^2 N_1 N_3 \theta_0 + m(N_3)^2 N_3^2$.

LEMMA (ANGLE REFINED BILINEAR STRICHARTZ)

Let $0 < N_1 \le N_2$ and $0 < \theta < \frac{1}{50}$. Then for any $v_1, v_2 \in X^{0,1/2+}$ with spatial frequencies N_1, N_2 respectively, the spacetime function

$$F(t,x) := \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} e^{i(t(\tau_1 + \tau_2) + x \cdot (\xi_1 + \xi_2))} \\ \times \chi_{\{|\cos \angle (\xi_1, \xi_2)| \le \theta\}} \tilde{v}_1(\tau_1, \xi_1) \tilde{v}_2(\tau_2, \xi_2) \ d\xi_1 d\xi_2$$

obeys the bound

$$\|F\|_{L^{2}_{t,x}} \lesssim \theta^{1/2} \|v_{1}\|_{X^{0,1/2+}} \|v_{2}\|_{X^{0,1/2+}}.$$

as in P. Gérard's Lectures