

The divergence theorem

(also called Gauss theorem or Green-Ostrogradski theorem)

[Not part of MAT237: it is again a consequence of the general Stokes theorem $\int_{\partial R} \omega = \int_R d\omega$]

Theorem: $R \subset \mathbb{R}^3$ a regular region with piecewise smooth boundary (i.e. ∂R is as in the surface integral section)

We assume that ∂R is oriented by the normal outward pointing unit vector $\vec{n}(x)$

$F: U \rightarrow \mathbb{R}^3$ C^1 , $U \subset \mathbb{R}^3$ open, $R \subset U$

$$\text{Then } \iint_{\partial R} \vec{F} \cdot \vec{n} = \iiint_R \operatorname{div} F$$

Surface integral for vector fields \rightarrow usual integral for 3 variables and $\operatorname{div} F: \mathbb{R}^3 \rightarrow \mathbb{R}$

Δ We are not proving this theorem

① If each part of the boundary is elementary

$$\text{i.e. } \{ \varphi_1(x,y) \leq z \leq \varphi_2(x,y) \} = \{ \psi_1(y,z) \leq x \leq \psi_2(y,z) \} \\ = \{ \tau_1(x,z) \leq y \leq \tau_2(x,z) \}$$

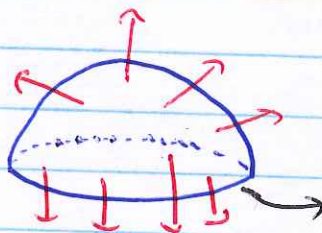
then we may follow the proof of Green theorem

② The general case is too difficult for MAT237

□

Ex: Let $R = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 2, z \geq 0\}$

and $S = \partial R$ oriented by taking the unit 'outward pointing normal vector \vec{m} '



on this circle the normal vector is not well defined but it's a curve so it has an integral of 0 (zero content)

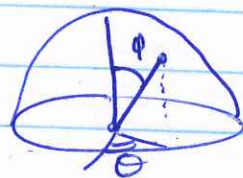
$$F(x, y, z) = (2x + y)z, 0, z$$

Compute $\iint_S \vec{F} \cdot \vec{m}$

$$\iint_S \vec{F} \cdot \vec{m} = \iiint_R \operatorname{div} F = \iiint_R 2z + 1$$

divergence theorem

$$= \int_0^{2\pi} \int_0^{\frac{\pi}{2}} \int_0^{\sqrt{2}} (2r \cos \varphi + 1) r^2 \sin \varphi \, dr \, d\varphi \, d\theta$$



$$= 2\pi \int_0^{\pi/2} \int_0^{\sqrt{2}} r^3 \sin(2\varphi) + r^2 \sin \varphi \, dr \, d\varphi$$

$$= 2\pi \int_0^{\sqrt{2}} r^3 + r^2 \, dr$$

$$= 2\pi \left(1 + \frac{2\sqrt{2}}{3} \right)$$

The divergence theorem allows to give a physical interpretation of the divergence operator.

$$\mathcal{U} \subset \mathbb{R}^3 \text{ open, } F: \mathcal{U} \rightarrow \mathbb{R}^3 \text{ } C^1, \quad p \in \mathcal{U}$$

then if $r > 0$ is small $\operatorname{div} F(x) \approx \operatorname{div} F(p)$ for $x \in \overline{B}(p, r)$
(continuity)

so that:

$$\iiint_{\overline{B}(p, r)} \operatorname{div} F \approx \operatorname{div} F(p) \cdot \iiint_{\overline{B}(p, r)} 1 = \frac{4}{3} \pi r^3 \operatorname{div} F(p)$$

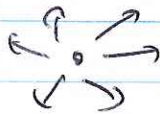
$$\text{ie } \operatorname{div} F(p) \approx \frac{3}{4\pi r^3} \iiint_{\overline{B}(p, r)} \operatorname{div} F$$

$$= \frac{3}{4\pi r^3} \iint_{\partial \overline{B}(p, r)} \vec{F} \cdot \vec{m}$$

$$\text{Def: } \operatorname{div} F(p) = \lim_{r \rightarrow 0} \frac{3}{4\pi r^3} \iint_{\partial \overline{B}(p, r)} \vec{F} \cdot \vec{m}$$

ie $\operatorname{div} F(p)$ measures the outward flux near p
per unit of volume per unit of time

so if $\operatorname{div} F(p) > 0$, p is a source, the flux is outgoing



if $\operatorname{div} F(p) < 0$, p is a sink, the flux is ingoing



By the way this is independent of the coordinates so $\operatorname{div} F$ is the same in any coordinate systems

Gauss' Law: $R \subset \mathbb{R}^3$ a regular region with piecewise smooth boundary s.t. $\vec{0} \notin \partial R$
 We assume that ∂R is oriented by the normal outward pointing unit vector field.

Then
$$\iint_{\partial R} \frac{\vec{F}}{\|\vec{F}\|^3} \cdot \vec{n} = \begin{cases} 4\pi & \text{if } \vec{0} \in R \\ 0 & \text{otherwise} \end{cases}$$
 where $\vec{F}(x, y, z) = (x, y, z)$

First case: $\vec{0} \notin R$

$$\begin{aligned} \operatorname{div} \left(\frac{\vec{F}}{\|\vec{F}\|^3} \right) &= \operatorname{div} \left(\frac{x}{(x^2+y^2+z^2)^{3/2}}, \frac{y}{(x^2+y^2+z^2)^{3/2}}, \frac{z}{(x^2+y^2+z^2)^{3/2}} \right) \\ &= \|\vec{F}\|^2 - 3x^2 + \|\vec{F}\|^2 - 3y^2 + \|\vec{F}\|^2 - 3z^2 \\ &= 3\|\vec{F}\|^2 - 3\|\vec{F}\|^2 \\ &= 0 \end{aligned}$$

and it is true on R because $\vec{0} \notin R$

By the divergence theorem: $\iint_{\partial R} \frac{\vec{F}}{\|\vec{F}\|^3} = \iiint_R 0 = 0$

Second case: $\vec{0} \in R$

We can no longer ^{directly} apply the divergence theorem since $\frac{\vec{F}}{\|\vec{F}\|}$ is not defined at $\vec{0} \in R$

Since $\vec{0} \in R \setminus \partial R$, we know that $\vec{0} \in \overset{\circ}{R}$
 hence $\exists \varepsilon > 0$ s.t.

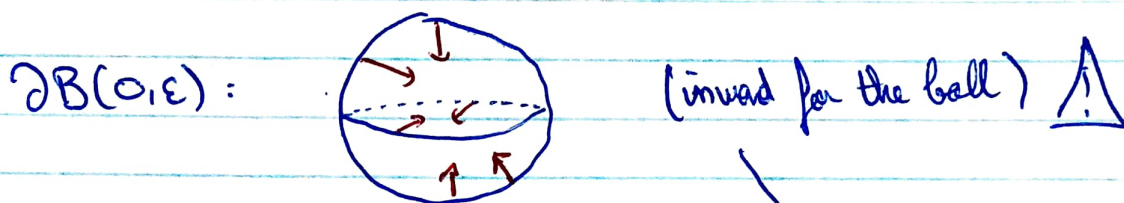
$$B(\vec{0}, \varepsilon) \subset \overset{\circ}{R} \subset \bar{\overset{\circ}{R}} = \bar{R}$$

$\hookrightarrow \overset{\circ}{R}$ open \rightarrow always true $\rightarrow R$ is a regular region



We define $R' = R \setminus B(0, \epsilon)$

then $\partial R' = \partial R \cup \partial B(0, \epsilon)$ with the orientation pointing outward from R' so



By the divergence theorem:

$$0 = \iiint_{R'} 0 = \iiint_{R'} \operatorname{div} \left(\frac{\vec{r}}{\|\vec{r}\|^3} \right) = \iint_{\partial R} \frac{\vec{r}}{\|\vec{r}\|^3} \cdot \vec{n} = \iint_{\partial B(0, \epsilon)} \frac{\vec{r}}{\|\vec{r}\|^3} \cdot \vec{n}$$

\hookrightarrow outward pointing for the ball fine

$$\Rightarrow \iint_{\partial R} \frac{\vec{r}}{\|\vec{r}\|^3} \cdot \vec{n} = \iint_{\partial B(0, \epsilon)} \frac{\vec{r}}{\|\vec{r}\|^3} \cdot \vec{n}$$

$$\partial B(0, \epsilon) = \{ (\epsilon \cos \theta \sin \varphi, \epsilon \sin \theta \sin \varphi, \epsilon \cos \varphi) \mid \theta \in [0, 2\pi], \varphi \in [0, \pi] \}$$

$$\partial_\theta \vec{r} \times \partial_\varphi \vec{r} = -\sin \varphi \epsilon \vec{r}(\sigma(\theta, \varphi))$$

$$= \int_0^\pi \int_0^{2\pi} \frac{\vec{r}(\sigma(\theta, \varphi))}{\|\vec{r}(\sigma(\theta, \varphi))\|^3} \cdot (-\sin \varphi \epsilon \vec{r}(\sigma(\theta, \varphi))) \, d\theta \, d\varphi < 0 \text{ inward}$$

but we want outward so $\times -1$

$$\|\vec{r}(\sigma(\theta, \varphi))\| = \epsilon \quad \Rightarrow \quad = \int_0^\pi \int_0^{2\pi} \frac{\sin \varphi \epsilon \|\vec{r}\|^2}{\|\vec{r}\|^3} \, d\theta \, d\varphi$$

$$= \int_0^\pi \int_0^{2\pi} \sin \varphi \, d\theta \, d\varphi = 2\pi \left[-\cos \varphi \right]_0^\pi = 4\pi$$

□



$$\iint_{\partial B(0,1)} \frac{\vec{r}}{\|\vec{r}\|^3} = 4\pi \neq 0$$

whereas $\operatorname{div} \left(\frac{\vec{r}}{\|\vec{r}\|^3} \right) = 0$

because we can't apply the divergence theorem to $B(\vec{0}, 1)$ since $\vec{0} \in B(\vec{0}, 1)$ but $\frac{\vec{r}}{\|\vec{r}\|^3}$ is not defined at $\vec{0}$

→ Be careful before applying the divergence theorem

Example: We can use the divergence theorem to compute a volume using a surface integral (in the same way that we use Green's theorem to compute an area using a line integral)

Let $R \subset \mathbb{R}^3$ be a regular region with a piecewise smooth boundary.

We assume that ∂R is oriented using the outward normal unit vector \vec{m} .

Let $\vec{r}(x, y, z) = (x, y, z)$

$$\mathcal{V}(R) = \iiint_R 1 = \iiint_R \frac{\operatorname{div}(\vec{r})}{3}$$

$$= \frac{1}{3} \iiint_R \operatorname{div}(\vec{r})$$

$$= \frac{1}{3} \iint_{\partial R} \vec{r} \cdot \vec{m} \quad \text{by the divergence theorem}$$

↳ outward orientation

$$\mathcal{V}(R) = \frac{1}{3} \iint_{\partial R} \vec{r} \cdot \vec{m}$$