

Flag varieties, Bott-Samelson varieties

GRT learning seminar

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1 Flag varieties

1.1 Notational conventions

Let G be a semisimple algebraic group over \mathbb{C} . Fix a Borel (maximal solvable) subgroup $B \subset G$ and a maximal torus $T \subset B$. Let $\mathfrak{h} \subset \mathfrak{b} \subset \mathfrak{g}$ denote the respective Lie algebras. These choices determine a weight lattice $P \subset \mathfrak{h}^*$ and a root system $\Delta \subset P^*$ with a set of positive roots Δ^+ and a set of simple roots $\Pi = \{\alpha_1, \dots, \alpha_n\}$. They also determine a Weyl group $W = N_G(T)/T$ with a given set of generators s_i and length function $l : W \rightarrow \mathbb{N}$.

Example 1.1. *The main example to have in mind is $G = \mathrm{SL}_n(\mathbb{C})$, with B upper triangular matrices, and T diagonal matrices. Here the weight lattice is $P = \{\vec{x} \in \mathbb{Z}^n \mid \vec{x} \cdot (1, 1, \dots, 1)^T = 0\}$, the set of roots is $\{e_i - e_j \mid i \neq j\}$, where e_i is the i -th standard basis vector. The positive roots are $\Delta^+ = \{e_i - e_j \mid i < j\}$ and the simple roots are $\Pi = \{e_i - e_{i+1}\}$. The Weyl group W is the symmetric group S_n .*

1.2 Introduction

We are interested in the **flag variety** G/B of G . Since B is a closed subgroup, this is a smooth variety with a transitive G -action.

Example 1.2. *For $G = \mathrm{SL}_n(\mathbb{C})$, G/B is the variety of complete flags in \mathbb{C}^n*

$$\{0 = F_0 \subset F_1 \subset \dots \subset F_{n-1} \subset F_n = \mathbb{C}^n \mid \dim F_i = i\}.$$

To see this, notice that G/B is isomorphic to \mathcal{B} , the variety of all Borel subgroups via

$$\mathfrak{g}B/B \mapsto \mathfrak{g}Bg^{-1}$$

and the stabilizer of a complete flag is a Borel subgroup. Under this identification, the point B/B corresponds to the Borel subgroup B and to the base flag $\{0 \subset \mathrm{Span}\{e_1\} \subset \mathrm{Span}\{e_1, e_2\} \subset \dots \subset \mathrm{Span}\{e_1, \dots, e_{n-1}\} \subset \mathbb{C}^n\}$.

The flag variety has a T -action (since $T \subset G$).

Proposition 1.3. *The T -fixed points in G/B are in bijection with the Weyl group, more precisely, we have*

$$(G/B)^T = \{\dot{w}B/B\}_{w \in W},$$

where \dot{w} denotes a representative of an element of $W = N_G(T)/T$ in G .

Example 1.4. *For $G = \mathrm{SL}_n(\mathbb{C})$, the T -fixed flags are precisely the coordinate flags*

$$\{0 = F_0 \subset \mathrm{Span} e_{w(1)} \subset \mathrm{Span}\{e_{w(1)}, e_{w(2)}\} \subset \dots \subset \mathrm{Span}\{e_{w(1)}, \dots, e_{w(n-1)}\} \subset \mathbb{C}^n\}.$$

The flag variety is also a projective variety, which means that we can gain a lot of leverage on it by looking at its T -moment map image (see Figure 1) which is known to be given by the convex hull of the images of the T -fixed points.

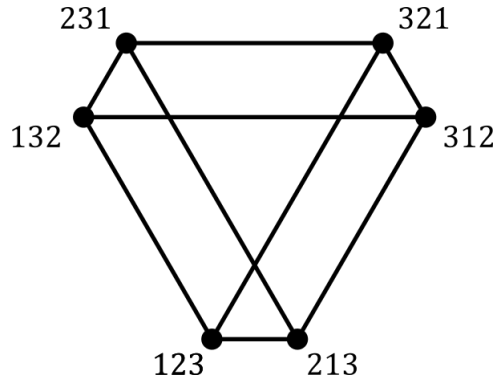


Figure 1: The moment map image of $SL_3(\mathbb{C})$'s flag manifold

1.3 The Bruhat decomposition

The sets $X_o^w = BwB/B$ are called **Bruhat cells**. They are cells in the sense of algebraic topology, i.e. $X_o^w \cong \mathbb{C}^{l(w)}$. Their closures $X^w = \overline{X_o^w}$ are called **Schubert varieties**.

Theorem 1.5 (Bruhat decomposition). *The Bruhat cells form a cell decomposition of G/B , i.e.*

$$G/B = \bigsqcup_{w \in W} X_o^w.$$

Moreover, any Schubert variety is a union of Bruhat cells, and the closure relations define a partial ordering on W , called the **Bruhat order**

$$X^w = \bigsqcup_{v \leq w} X_o^v.$$

Example 1.6. For $G = SL_n(\mathbb{C})$, the B -orbit of a standard basis vector e_k is

$$\left\{ c_k e_k + \sum_{i=1}^{k-1} c_i e_i \mid c_k \neq 0 \right\},$$

in particular, if we start at a coordinate flag wB/B , and apply elements of B , we can get arbitrarily close to other coordinate flags where some of the inversions of the permutation w are eliminated, i.e. where instead of the standard basis $e_{w(i)}$ vector occurring at step i of the flag, any of the standard basis vectors e_k with $k \leq w(i)$ occurs instead (with $e_{w(i)}$ occurring later). See Figure 2 for an example in $SL_3(\mathbb{C})$.

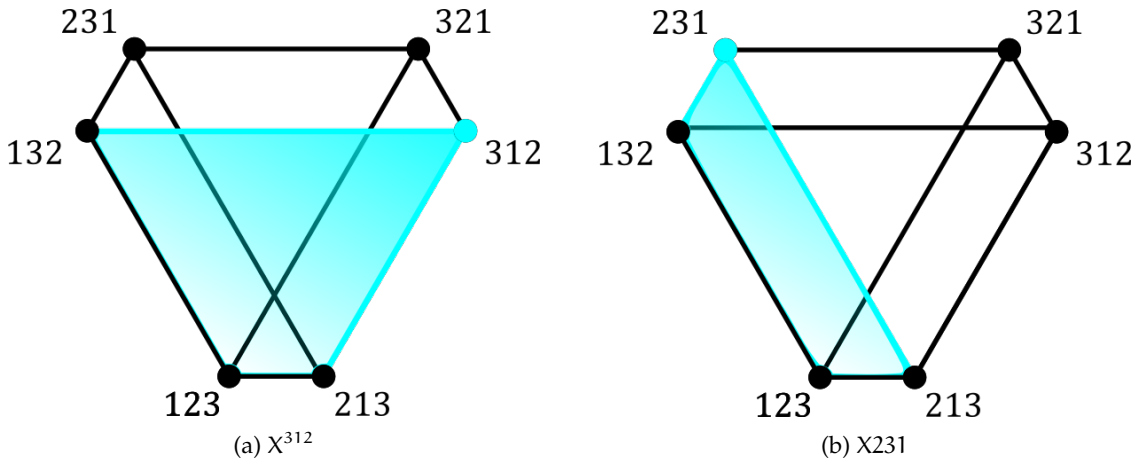


Figure 2: Two Bruhat cells in $SL_3(\mathbb{C})/B$.

If we take closures, these points are added, and we see that the Bruhat order then has the description that $v \leq w$ if for all $i = 1, \dots, n$,

$$\text{sort}(v(1), v(2), \dots, v(i)) \leq \text{sort}(w(1), w(2), \dots, w(i)),$$

and the \leq stands for comparing sequences entry-wise.

If $G = \text{SL}_n(\mathbb{C})$, given a flag F , we can decide which Schubert cell it belongs to by looking at the $(n-1) \times (n-1)$ **rank matrix** whose (i, j) -th entry is $\dim(F_i \cap \text{Span}\{e_1, \dots, e_j\})$, and comparing it to the rank matrices of the coordinate flags.

Example 1.7. The flag $F = (0 \subset \text{Span}\{e_1 + e_3\} \subset \text{Span}(e_1 + e_3, e_1) \subset \mathbb{C}^3)$ has rank matrix

	$\text{Span}\{e_1\}$	$\text{Span}\{e_1, e_2\}$
$\text{Span}\{e_1 + e_3\}$	0	0
$\text{Span}(e_1 + e_3, e_1)$	1	1

The coordinate flag corresponding to the permutation 312 has the same rank matrix, so $F \in X_0^{312}$.

2 Bott-Samelson varieties

2.1 Motivation: Desingularizations of Schubert varieties

Schubert varieties are in general singular.

Example 2.1. For $G = \text{SL}_n(\mathbb{C})$, a Schubert variety X^w is singular if and only if the permutation does not contain any 4×4 permutation submatrix equal to the permutation 3412 or 4231.

If X and Y are varieties with a right action of B on X and a left action of B on Y , then we define the quotient

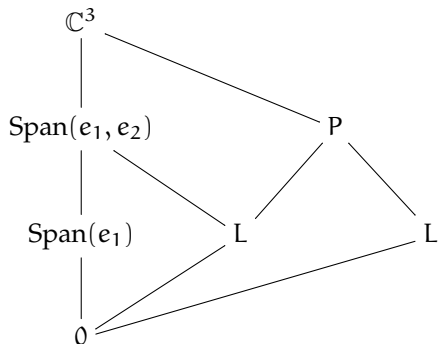
$$X \times^B Y = \{[x, y] \mid x \in X, y \in Y, [x, y] = [xb^{-1}, by]\}$$

Definition 2.2. Let $Q = (s_{i_1}, s_{i_2}, \dots, s_{i_k})$ be a word in the simple reflections. The **Bott-Samelson variety** is

$$\text{BS}^Q = P_{i_1} \times^B P_{i_2} \times^B \dots \times^B P_{i_k} / B,$$

where P_j denotes the minimal parabolic containing the root subgroup for $-\alpha_j$.

Example 2.3. For $G = \text{SL}_n(\mathbb{C})$ the Bott-Samelson variety G^Q can be interpreted as the **incidence variety**, where start from the base flag and at every step of Q , we change only the subspace corresponding to the simple reflection. More concretely, for $G = \text{SL}_3(\mathbb{C})$ and $Q = (s_1, s_2, s_1)$, we have that $\text{BS}^Q = \{(L, P, L') \mid L \subset \text{Span}(e_1, e_2) \cap P, L' \subset P\}$, or, more visually



Theorem 2.4. The Bott-Samelson variety BS^Q has a map to the flag variety

$$m : \text{BS}^Q \rightarrow G/B$$

$$[p_1, p_2, \dots, p_k] \mapsto p_1 p_2 \dots p_k B/B.$$

Moreover, if Q is a reduced word, then the image $m(\text{BS}^Q)$ is the Schubert variety X^w (where $w = \prod Q$), and this map is generically one-to-one.

Example 2.5. For $G = \mathrm{SL}_n(\mathbb{C})$, the map is “take the rightmost flag in the incidence variety picture”.

Remark 2.6. Note that the Bott-Samelson variety is not a resolution of singularities in the strictest sense, since it is not generically one-to-one to the smooth locus of the Schubert variety. For example, G/B is smooth, but $m : \mathrm{BS}^Q \rightarrow G/B$ is not an isomorphism.

2.2 Charts on Bott-Samelson varieties

The Bott-Samelson variety is an iterated \mathbb{P}^1 -bundle because each quotient P_k/B is isomorphic to \mathbb{P}^1 . Therefore it has many natural coordinate charts.

Proposition 2.7. On $P_k/B \cong \mathbb{P}^1$, we have two charts $u_+, u_- : \mathbb{C} \rightarrow P_k/B$ given by

$$\begin{aligned} u_+(z) &= u_{\alpha_k}(z) \cdot s_k \\ u_-(w) &= u_{-\alpha_k}(w) \end{aligned}$$

where $u_\beta : \mathrm{SL}_2(\mathbb{C}) \rightarrow G$ is the root subgroup corresponding to β . The change of coordinates between the two charts is $w = \frac{1}{z}$.

Example 2.8. For $\mathrm{SL}_3(\mathbb{C})$, and $Q = (s_1, s_2)$, the $+-$ chart is given by

$$\left[\begin{pmatrix} z_1 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & w_2 & 1 \end{pmatrix} \right].$$

Theorem 2.9. For Q a reduced word for w , the $+|Q|$ -chart of BS^Q is an isomorphism from $\mathbb{C}^{|Q|}$ to X_o^w .

Example 2.10. For $Q = (s_1, s_2)$, the image of the $++$ chart in G/B is

$$\begin{pmatrix} z_1 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & z_2 & -1 \\ 0 & 1 & 0 \end{pmatrix} / B = \begin{pmatrix} z_1 & -z_2 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} / B.$$

Notice that the origin $z_1 = z_2 = 0$ is mapped to the T -fixed flag 312, which is in X_o^{312} .

For us, the most important application of Bott-Samelson varieties is to give explicit coordinates to the big cell $X_o^{w_o}$.

3 Actions of vector fields

3.1 $\mathrm{SL}_2(\mathbb{C})$

For $G = \mathrm{SL}_2(\mathbb{C})$, the Bott-Samelson variety is isomorphic to the flag variety

$$\mathrm{BS}^{(s)} = G/B.$$

The big cell is parametrized by

$$\begin{pmatrix} z & -1 \\ 1 & 0 \end{pmatrix} / B.$$

Recall that we have a left $U(\mathfrak{g})$ -action on G/B generated by the vector fields corresponding to the basis e, f, h of $\mathfrak{sl}_2(\mathbb{C})$. We compute these actions in this coordinate chart.

We have

$$\exp(-te) = \begin{pmatrix} 1 & -t \\ 0 & 1 \end{pmatrix}, \quad \exp(-tf) = \begin{pmatrix} 1 & 0 \\ -t & 1 \end{pmatrix}, \quad \exp(-th) = \begin{pmatrix} e^{-t} & 0 \\ 0 & e^t \end{pmatrix},$$

Since

$$\begin{pmatrix} e^{-t} & 0 \\ 0 & e^t \end{pmatrix} \begin{pmatrix} z & -1 \\ 1 & 0 \end{pmatrix} / B = \begin{pmatrix} e^{-t}z & -e^{-t} \\ e^t & 0 \end{pmatrix} / B = \begin{pmatrix} e^{-2t}z & -1 \\ 1 & 0 \end{pmatrix} / B,$$

and we have

$$\begin{aligned}\frac{d}{dt}(e^{-2t}z) &= -2e^{-2t}z \\ h \cdot z &= \left. \frac{d}{dt} \right|_{t=0} (e^{-2t}z) = -2z \\ h &\mapsto -2z \frac{d}{dz}.\end{aligned}$$

Similarly, we compute the action of f :

Since

$$\begin{pmatrix} 1 & 0 \\ -t & 1 \end{pmatrix} \begin{pmatrix} z & -1 \\ 1 & 0 \end{pmatrix} / B = \begin{pmatrix} z & -1 \\ -tz+1 & t \end{pmatrix} / B = \begin{pmatrix} \frac{z}{-tz+1} & tz-1 \\ 1 & -t(tz-1) \end{pmatrix} / B = \begin{pmatrix} \frac{z}{-tz+1} & -1 \\ 1 & 0 \end{pmatrix} / B,$$

and we have

$$\begin{aligned}\frac{d}{dt} \left(\frac{z}{-tz+1} \right) &= \frac{z^2}{(-tz+1)^2} \\ f \cdot z &= \left. \frac{d}{dt} \right|_{t=0} \left(\frac{z}{-tz+1} \right) = z^2 \\ f &\mapsto z^2 \frac{d}{dz}.\end{aligned}$$

Exercise 3.1. Using this coordinate chart, verify that $e \mapsto -\frac{d}{dz}$.

4 $SL_3(\mathbb{C})$

Let $G = SL_3(\mathbb{C})$ and $Q = (s_1, s_2, s_1)$. Then $BS^Q \rightarrow G/B$ is generically one-to one. Let us compute the image of the + + + chart.

$$\begin{pmatrix} z_1 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & z_2 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} z_3 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} / B = \begin{pmatrix} z_1 z_3 & -z_1 & 1 \\ z_2 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix} / B$$

The z_2 coordinate can be recovered by taking the top left 2×2 minor (this is preserved under the right action of B , if the antidiagonal entries are scaled appropriately).

We have to compute the action of the vector fields $e_1, f_1, h_1, e_2, f_2, h_2$. We have

$$\begin{aligned}\exp(-te_1) &= \begin{pmatrix} 1 & -t & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, & \exp(-tf_1) &= \begin{pmatrix} 1 & 0 & 0 \\ -t & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, & \exp(-th_1) &= \begin{pmatrix} e^{-t} & 0 & 0 \\ 0 & e^t & 0 \\ 0 & 0 & 1 \end{pmatrix}, \\ \exp(-te_2) &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -t \\ 0 & 0 & 1 \end{pmatrix}, & \exp(-tf_2) &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -t & 1 \end{pmatrix}, & \exp(-th_2) &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^{-t} & 0 \\ 0 & 0 & e^t \end{pmatrix}\end{aligned}$$

Exercise 4.1. Verify that or find a sign mistake in

$$\begin{aligned}e_1 &\mapsto -\partial_{z_1} \\ f_1 &\mapsto z_1^2 \partial_{z_1} - z_1 z_2 \partial_{z_2} + (z_2 - z_1 z_3) \partial_{z_3} \\ h_1 &\mapsto -2z_1 \partial_{z_1} + z_2 \partial_{z_2} + z_3 \partial_{z_3} \\ e_2 &\mapsto z_1 \partial_{z_2} - \partial_{z_3} \\ f_2 &\mapsto z_2 \partial_{z_1} + z_3^2 \partial_{z_3} \\ h_2 &\mapsto z_1 \partial_{z_1} - z_2 \partial_{z_2} - 2z_3 \partial_{z_3}\end{aligned}$$

Example 4.2. Note that $[e_1, f_1] = h_1$

Exercise 4.3. Verify the remaining relations in $\mathfrak{sl}_3(\mathbb{C})$ or find a sign mistake in the formulas.

4.1 The principal block of category \mathcal{O}

Similarly to the situation with \mathbb{P}^1 described by Dylan in the first lecture, we realize see the dual Verma module $M(0)^\vee$ as $\mathbb{C}[z_1, z_2, z_3]$. Notice that there is a highest weight vector of weight 0 (corresponding to the scalars) that is annihilated by all of the operators (this realizes the trivial representation as a submodule).

Recall that we have the BGG resolution

$$L(0) \rightarrow M(0)^\vee \rightarrow M(s_1 \cdot 0)^\vee \oplus M(s_2 \cdot 0)^\vee \rightarrow M(s_1 s_2 \cdot 0)^\vee \oplus M(s_2 s_1 \cdot 0)^\vee \rightarrow M(s_1 s_2 s_1 \cdot 0)^\vee \rightarrow 0$$

Exercise 4.4. *Verify that in the above resolution the highest weight vectors of $M(s_1 \cdot 0)^\vee$ and $M(s_2 \cdot 0)^\vee$ are z_1 and z_3 , respectively.*

Note that the maps in the BGG resolution are given by taking residues with respect to some of the variables. For example, the map $M(0)^\vee \rightarrow M(s_1 \cdot 0)^\vee \oplus M(s_2 \cdot 0)^\vee$ is $\text{Res}_{z_1} \oplus \text{Res}_{z_3}$. This corresponds to sending the coordinates z_1, z_3 to ∞ , respectively.